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Computer Solutions to Heat and Diffraction Equations in High Energy Laser Windows

Volume II

PETER D. GIANINO
BERNARD BENDOW
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20. Abstract (Continued)

developed to predict the extent of this lensing in various candidate materials under a variety of conditions. This work contributed to selection of appropriate materials, as well as to design of geometrical configurations, in which the lensing could be reduced. To quantify the effects of thermal lensing, an efficient computer program package was developed and programmed to run on a CDC6600 computer. The package was written to handle Gaussian-shaped beams incident on either a thin disc- or annular-shaped cylindrical window. Three coupled programs make up the package: TEMP5, which solves the full heat transport equation within the window for any given set of initial and boundary conditions on each surface; TIKIRK, which solves the vector Kirchhoff diffraction integrals for the beam transmitted to the far field; and DISPLAY, which plots these temperatures and/or intensities in a variety of ways, including three-dimensional perspective views. Volume I of this report lays the theoretical foundations underlying these programs and presents graphical results for two model problems using disc- and annular-shaped windows. Volume II is a "user's manual." It describes how each program functions, enumerates the constituent subroutines and subprograms, gives complete Fortran listings, and even provides typical detailed commands to initiate and run the programs in both the Intercom and Batch modes of operation. Results of this work should substantially aid engineers in planning configurations and specifications for current and conceptual systems.

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Computer Solutions to Heat and Diffraction Equations in High Energy Laser Windows Volume II

7. INTRODUCTION

In Volume II we will give a detailed documentation of the Fortran programs TEMP5, TIKIRK and DISPLAY, explaining how to implement them. This will include: listings of main and ancillary programs and subroutines, plus an explanation of their functions; derivations of how the heat, boundary condition (BC) and diffraction intensity equations are transformed into algorithms solvable by the computer; flow charts; and, glossaries of variables for some of the more important subroutines. Since programs TEMP5 and TIKIRK have been coded to permit systems operation under both an Intercom and Batch mode, we will list typical interactive commands and card deck setups which control these two types of operation. Because program DISPLAY can function only in the Batch mode, we will list typical card deck setups for its operation.

Much of the details presented in Volume II appeared originally in the following unpublished reports from Parke Mathematical Laboratories, Inc., Carlisle, Mass.:

(i) N.G. Parke, III, "Program TEMP5," Sci. Rpt. No. 1 (April 1973); also documented as AFCRL Rpt TR-73-0039 by the same author.

(Received for publication 26 November 1976)



(ii) T. B. Barrett, "An Interactive Set of Programs Using Program TEMP5 for the Determination of Calorimetric Material Parameters from Experimental Data on Cylindrical IR Laser Window Materials," Tech. Memo. No. 16 (Oct. 1973).

(iii) T. B. Barrett, "TIKIRK Program," PML Rpt. 110, with revision (April 1974).

(iv) T. B. Barrett, "GETDATA Subroutine," PML Rpt. 111 (May 1974).

(v) T. B. Barrett, "DISPLAY Program," PML Rpt. 116 (May 1974).

8. TEMP5 PROGRAM

8.1 Introductory Remarks

Initial attempts to code the numerical solution to the heat and BC equations used the Crank-Nicolson method.¹¹ This procedure leads to a pentagonal system of linear difference equations, which are usually solved by an appropriate iteration technique.¹² However, if the edges of the "net" of points — at which the temperature is to be evaluated — is situated at the boundaries, three problems arise:

(1) Iteration techniques must be used.

(2) Symmetry dictates that along the window axis ($\rho = 0$) there be no heat flow across the window center, that is, $\partial u / \partial \rho = 0$. Under this condition, however, the term $(1/\rho)(\partial u / \partial \rho)$ which occurs in the partial differential equation would be indeterminate.

(3) A satisfactory finite-difference analog must be found for the general BC's, which have the form:

$$\partial u / \partial \nu + hu = g \quad . \quad (38)$$

[cf, Eq. (32) of Volume I].

These difficulties were resolved as follows:

(1) The Crank-Nicolson method was replaced by the Implicit Alternating Difference (IAD) method.¹¹ This procedure reduces the algebraic problem at each stage to the inversion of a tridiagonal matrix. The Thomas algorithm is employed and iteration is avoided. The cost of this approach for a problem involving two space variables is a two-time-level pair of difference equations.

11. Carnahan, B., Luther, H.A., and Wilkes, J.O. (1969) Applied Numerical Methods, Wiley and Sons, Inc., New York.

12. Parke, N.G., III (1971) Technical Memorandum No. 4, Parke Mathematical Laboratories, Inc., Carlisle, Massachusetts, unpublished.

(2) By applying L'Hospital's rule along the cylinder axis there results:
 $\lim_{\rho \rightarrow 0} (\rho^{-1})(\partial u / \partial \rho) = \partial^2 u / \partial \rho^2$.

(3) A suitable finite difference analog for Eq. (38) is established by shifting the "net" half an increment off the boundaries.

To see how the finite difference method is applied, consider a transverse cross-sectional cut through the window's center (that is, the plane of the cross-section is perpendicular to the window's faces). The borders of the resulting rectangular cross-section are parallel to the ρ and ξ axes (see Figure 1, Volume I). Because of the rotational symmetry, only one half of the section need be shown. The geometry of the choice of net points superimposed on this cut is indicated in Figure 19. The window faces occur at the lines marked $\xi = \xi_1$, and $\xi = \xi_2$; the inner and outer cylindrical surfaces are denoted by the lines marked $\rho = \rho_1$ and $\rho = 1$, respectively. The ρ, ξ coordinates of each net point are represented by the indices i, j , respectively, with i running from 0 to $M+1$, and, j running from 0 to $N+1$. That is,

$$\begin{aligned}\rho_i &= \rho_1 + \left(i - \frac{1}{2}\right) \cdot \Delta\rho, \quad i = 0, 1, \dots, M+1 \\ \xi_j &= \xi_1 + \left(j - \frac{1}{2}\right) \cdot \Delta\xi, \quad j = 0, 1, \dots, N+1\end{aligned}\tag{39}$$

These coordinates are measured relative to the surfaces ρ_1 and ξ_1 , respectively. All of the net points bearing one or both of the indices 0, $M+1$ and $N+1$ fall outside of the window itself and are considered to be "fictitious" or "corner" points.

8.2 Finite Difference Analogs for the General BC's

It is now possible to write the finite difference analog of the general BC's for the shifted net. First, we note that the derivative term $\partial u / \partial \nu$ in Eq. (38) differs for each surface due to the sign conventions chosen for ρ and ξ . For example, at the surfaces $\rho = \rho_1$ and $\rho = 1$, the term $\partial u / \partial \nu$ becomes $-$ and $+$ $\partial u / \partial \rho$, respectively; while at the surfaces $\xi = \xi_1$, and $\xi = \xi_2$ it becomes $-$ and $+$ $\partial u / \partial \xi$, respectively. Thus, the finite difference analogs of the BC's become:

$$\frac{u_{0,j} - u_{1,j}}{\Delta\rho} + h_1 \frac{u_{0,j} + u_{1,j}}{2} = g_1 \text{ at } \rho = \rho_1\tag{40}$$

$$\frac{u_{M+1,j} - u_{M,j}}{\Delta\rho} + h_2 \frac{u_{M+1,j} + u_{M,j}}{2} = g_2 \text{ at } \rho = 1\tag{41}$$

for $j = 1, 2, \dots, N-1$

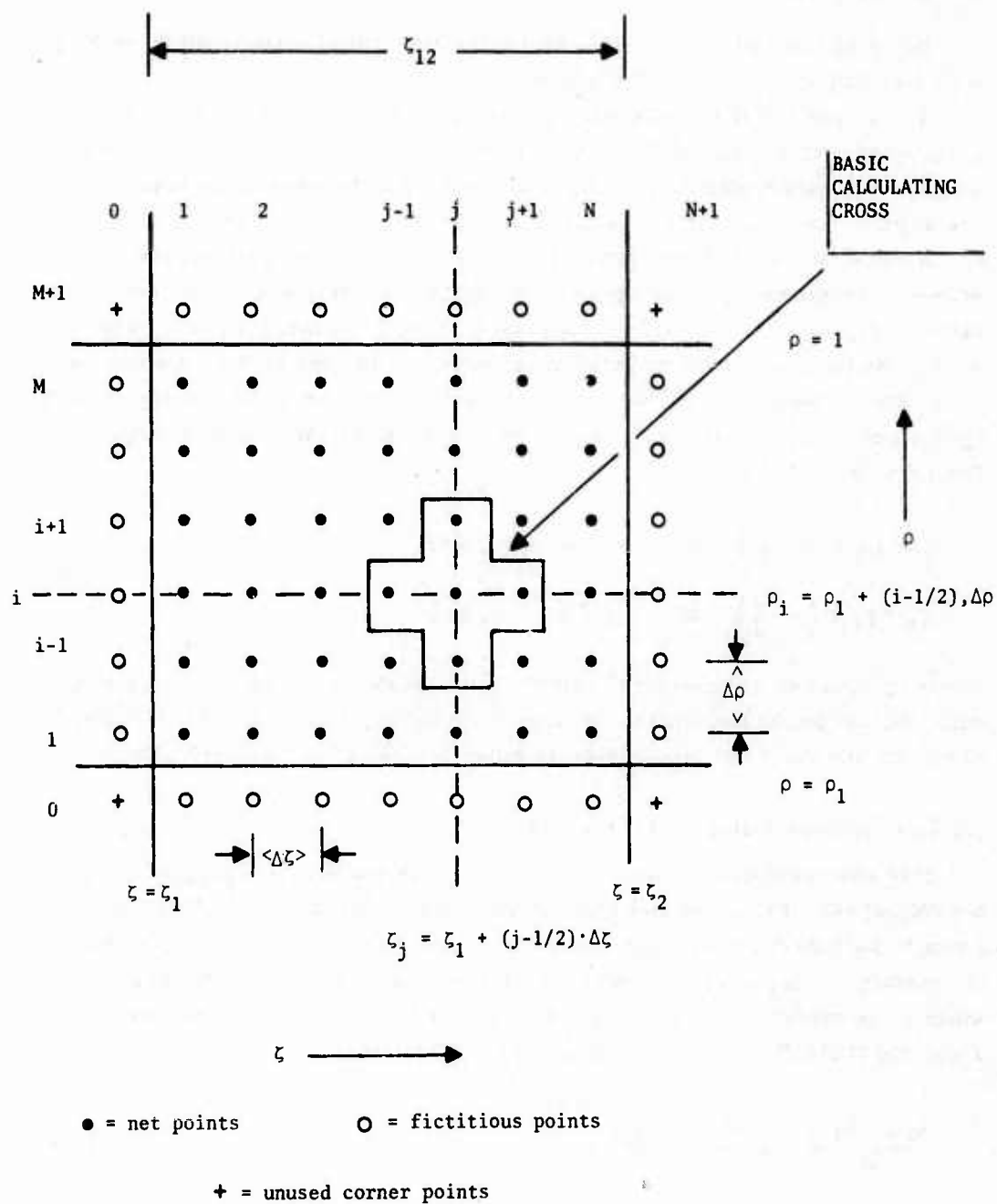


Figure 19. Geometry of Finite Difference Net. The boundaries are straddled by a net point and a fictitious point

$$\frac{u_{i,0} - u_{i,1}}{\Delta \xi} + h_3 \frac{u_{i,0} + u_{i,1}}{2} = g_3 \text{ at } \xi = \xi_1 \quad (42)$$

$$\frac{u_{i,N+1} - u_{i,N}}{\Delta \xi} + h_4 \frac{u_{i,N+1} + u_{i,N}}{2} = g_4 \text{ at } \xi = \xi_2 \quad (43)$$

When these are solved for the "fictitious" points, one obtains

$$u_{0,j} = \left[\frac{2 - h_1 \cdot \Delta \rho}{2 + h_1 \cdot \Delta \rho} \right] u_{1,j} + \left[\frac{2 \cdot \Delta \rho \cdot g_1}{2 + h_1 \cdot \Delta \rho} \right] \quad (44)$$

$$u_{M+1,j} = \left[\frac{2 - h_2 \cdot \Delta \rho}{2 + h_2 \cdot \Delta \rho} \right] u_{M,j} + \left[\frac{2 \cdot \Delta \rho \cdot g_2}{2 + h_2 \cdot \Delta \rho} \right] \quad (45)$$

$$u_{i,0} = \left[\frac{2 - h_3 \cdot \Delta \xi}{2 + h_3 \cdot \Delta \xi} \right] u_{i,1} + \left[\frac{2 \cdot \Delta \xi \cdot g_3}{2 + h_3 \cdot \Delta \xi} \right] \quad (46)$$

$$u_{i,N+1} = \left[\frac{2 - h_4 \cdot \Delta \xi}{2 + h_4 \cdot \Delta \xi} \right] u_{i,N} + \left[\frac{2 \cdot \Delta \xi \cdot g_4}{2 + h_4 \cdot \Delta \xi} \right] \quad (47)$$

We saw in Section 3.3, Volume I, that all BC's of practical interest can be represented by appropriate choices of the g_i and h_i . With this capability in the above analogs, the resulting computer program becomes very flexible.

8.3 Finite Difference Equations for I.A.D. Method

Having set up the "net," we shall now use the I.A.D. method on the parabolic heat equation having the general form [cf Eq. (29), Volume I]:

$$\partial u / \partial \tau = \partial^2 u / \partial \rho^2 + \rho^{-1} \partial u / \partial \rho + \partial^2 u / \partial \xi^2 + q \quad (48)$$

where

$$q = A \exp(-\rho^2 / 2\sigma_e^2).$$

In the first finite difference equation set, the analog of the partial derivatives with respect to ρ will be written at the new time level $n + 1$, and the analog of the ξ -derivative written at the old level n . Here, n is even starting with $n = 0$. To complete the cycle, the second finite difference equation set is written at the new time level $n + 2$ for derivatives in the ξ direction. In other words, the equations are now implicit in ξ -direction and explicit in the ρ -direction. Partial derivatives with respect to ρ are written in terms of values of u at the, now old, time level $n + 1$. These "intermediate" values of u are sometimes designated u^* (meaning a correction). They are not accurate representations of the u . This point is discussed in detail by von Rosenberg.¹³

Our analogs for the various partial derivatives take the forms:

$$(u_{\rho\rho})_{i,j,n+1} = \frac{u_{i+1,j,n+1} - 2u_{i,j,n+1} + u_{i-1,j,n+1}}{(\Delta\rho)^2}, \quad (49)$$

$$\left(\frac{1}{\rho} u_{\rho}\right)_{i,j,n+1} = \frac{u_{i+1,j,n+1} - u_{i-1,j,n+1}}{2\rho_i(\Delta\rho)}, \quad (50)$$

$$(u_{\xi\xi})_{i,j,n} = \frac{u_{i,j+1,n} - 2u_{i,j,n} + u_{i,j-1,n}}{(\Delta\xi)^2}, \quad (51)$$

$$(u_{\tau})_{i,j,n+1/2} = \frac{u_{i,j,n+1} - u_{i,j,n}}{(\Delta\tau)}, \quad (52)$$

and

$$q(\rho_i, \xi_j) = q_{i,j}. \quad (53)$$

The subscripts i, j merely represent generalized indices and extend over the generalized ranges: $i = 1, 2, \dots, M$ and $j = 1, 2, \dots, N$. After substitution, the first set of I. A. D. equations are:

13. von Rosenberg, D. U. (1969) Methods for the Numerical Solution of Partial Differential Equations, American-Elsevier Publishing Co., Inc., New York.

$$\begin{aligned}
& \frac{u_{i+1,j,n+1} - 2u_{i,j,n+1} + u_{i-1,j,n+1}}{(\Delta\rho)^2} + \frac{u_{i+1,j,n+1} - u_{i-1,j,n+1}}{2\rho_i(\Delta\rho)} \\
& + \frac{u_{i,j+1,n} - 2u_{i,j,n} + u_{i,j-1,n}}{(\Delta\xi)^2} + q_{i,j} = \frac{u_{i,j,n+1} - u_{i,j,n}}{\Delta\tau} .
\end{aligned} \tag{54}$$

The second set of I.A.D. equations is:

$$\begin{aligned}
& \frac{u_{i+1,j,n+1} - 2u_{i,j,n+1} + u_{i-1,j,n+1}}{(\Delta\rho)^2} + \frac{u_{i+1,j,n+1} - u_{i-1,j,n+1}}{2\rho_i(\Delta\rho)} \\
& + \frac{u_{i,j+1,n+2} - 2u_{i,j,n+2} + u_{i,j-1,n+2}}{(\Delta\xi)^2} + q_{i,j} = \frac{u_{i,j,n+2} - u_{i,j,n+1}}{\Delta\tau} .
\end{aligned} \tag{55}$$

It is convenient to introduce the parameters

$$\lambda = \frac{\Delta\tau}{(\Delta\rho)^2} , \quad \mu = \frac{\Delta\tau}{(\Delta\xi)^2} . \tag{56}$$

Observe that Eqs. (54) are tridiagonal, containing the unknowns

$$u_{i+1,j,n+1} , \quad u_{i,j,n+1} , \quad u_{i-1,j,n+1}$$

and can be solved by the Thomas algorithm. Likewise, Eqs. (55) are tridiagonal, containing the unknowns

$$u_{i,j+1,n+2} , \quad u_{i,j,n+2} , \quad u_{i,j-1,n+2}$$

and can likewise be solved by the Thomas algorithm.

Before continuing, let us take up the mathematics of the Thomas algorithm (which will be incorporated in the subroutine TRIDAG, to be explained later).

8.4 The Solution of a Tridiagonal System of Equations

The whole purpose of the implicit-alternating direction method is to reduce the number of unknown variables at the "next" time level to three in any one equation. Such a set of equations is called a tridiagonal system that has a relatively

simple solution. This strategy avoids "iteration" techniques of the Crank-Nicolson approach, described in Parke.¹²

The general form of a tridiagonal system of equations is

$$\begin{aligned}
 b_1 v_1 + c_1 v_2 &= d_1 \\
 a_2 v_1 + b_2 v_2 + c_2 v_3 &= d_1 \\
 a_3 v_2 + b_3 v_3 + c_3 v_4 &= d_2 \\
 \dots\dots\dots & \\
 a_i v_{i-1} + b_i v_i + c_i v_{i+1} &= d_i \\
 \dots\dots\dots & \\
 a_{N-1} v_{N-2} + b_{N-1} v_{N-1} + c_{N-1} v_N &= d_{N-1} \\
 a_N v_{N-1} + b_N v_N &= d_N
 \end{aligned} \tag{57}$$

where*

d_i . = . known quantities

a_i, b_i, c_i . = . known coefficients

v_i . = . unknown quantities .

The tridiagonal matrix is defined as the matrix of coefficients a, b, c alone.

We follow the treatment in Carnahan.¹¹ To continue, the validity of the form

$$v_i = \gamma_i - \frac{c_i}{\beta_i} v_{i+1} \tag{58}$$

can be demonstrated. The constants γ_i and β_i are to be determined. Indeed, substitution into the i-th equation of (57) gives

$$a_i \left(\gamma_{i-1} - \frac{c_{i-1}}{\beta_{i-1}} v_i \right) + b_i v_i + c_i v_{i+1} = d_i .$$

*The symbol . = . means "is defined as."

As a result

$$v_i = \frac{d_i - a_i \gamma_{i-1}}{b_i - \frac{a_i c_{i-1}}{\beta_{i-1}}} - \frac{c_i v_{i+1}}{b_i - \frac{a_i c_{i-1}}{\beta_{i-1}}}$$

where we have the recursion relations

$$\beta_i = b_i - \frac{a_i c_{i-1}}{\beta_{i-1}} ; \quad \gamma_i = \frac{d_i - a_i \gamma_{i-1}}{\beta_i}. \quad (59)$$

From the first of Eqs. (57), we have

$$v_1 = \frac{d_1}{b_1} - \frac{c_1 v_2}{b_1}$$

where

$$\beta_1 = b_1, \quad \gamma_1 = d_1 / \beta_1. \quad (60)$$

Finally, from the last of Eqs. (57), we have

$$v_N = \frac{d_N - a_N v_{N-1}}{b_N} = \frac{d_N - a_N \left(\gamma_{N-1} - \frac{c_{N-1}}{\beta_{N-1}} v_N \right)}{b_N} \quad (61)$$

where

$$v_N = \frac{d_N - a_N (\gamma_{N-1})}{b_N - \frac{a_N c_{N-1}}{\beta_{N-1}}} = \frac{d_N - a_N \gamma_{N-1}}{\beta_N} = \gamma_N. \quad (61a)$$

To summarize the complete algorithm for the solution of the tridiagonal system, we have

$$v_N = \gamma_N$$

$$v_i = \gamma_i - \frac{c_i v_{i+1}}{\beta_i} \quad ; \quad i = N-1, N-2, \dots, 1 \quad (62)$$

$$b_i = -(2\lambda + 1) \quad (67)$$

$$c_i = \lambda \left(1 + \frac{\Delta\rho}{2\rho_1 + (2i-1) \cdot \Delta\rho} \right) = \lambda \left(1 + \frac{\Delta\rho}{2\rho_i} \right) \quad (68)$$

$$d_i = -\mu(u_{i,j+1,n} - 2u_{i,j,n} + u_{i,j-1,n}) - \Delta\tau \cdot q_{ij} - u_{i,j,n} \quad (69)$$

We notice that from Eq. (44)

$$a_1 u_{0,j,n+1} = a_1 \left\{ \left[\frac{2 - h_1 \cdot \Delta\rho}{2 + h_1 \cdot \Delta\rho} \right] u_{1,j} + \left[\frac{2 \cdot \Delta\rho \cdot g_1}{2 + h_1 \cdot \Delta\rho} \right] \right\} \quad (70)$$

Hence, we have to change b_1 according to

$$b_1 \leftarrow b_1 + a_1 \left[\frac{2 - h_1 \cdot \Delta\rho}{2 + h_1 \cdot \Delta\rho} \right] \quad (71)$$

We also have to change d_1

$$d_1 \leftarrow d_1 - a_1 \left[\frac{2 \cdot \Delta\rho \cdot g_1}{2 + h_1 \cdot \Delta\rho} \right] \quad (72)$$

Similarly we have to change b_M

$$b_M \leftarrow b_M + c_M \left[\frac{2 - h_2 \cdot \Delta\rho}{2 + h_2 \cdot \Delta\rho} \right] \quad (73)$$

using Eq. (45). Likewise

$$d_M \leftarrow d_M - c_M \left[\frac{2 \cdot \Delta\rho \cdot g_2}{2 + h_2 \cdot \Delta\rho} \right] \quad (74)$$

It should be observed that as long as $j \neq 1$ or $j = N$, the d 's require no further modification because their computation involves only "net" points at time level n . However, when $j = 1$, the fictitious points $u_{i,0,n}$ are involved. Also, when $j = N$,

the fictitious points $u_{i, N+1, n}$ are involved. The simplest way to handle this is to "border" the $u_{i, j, n}$ array by computing $u_{i, 0, n}$ with Eq. (46) and $u_{i, N+1, n}$ with Eq. (47) just before computing the first sets of a, b, c, d for the ξ -explicit, ρ -implicit I. A. D. set.

To summarize, in step I we modify b_1, d_1, b_M, d_M having extended $u_{i, j, n}$ with Eqs. (46) and (47).

Now let us turn to step II of the I. A. D. method. We begin with Eqs. (55) and write

$$\mu[u_{i, j+1, n+2} - 2u_{i, j, n+2} + u_{i, j-1, n+2}] = d_j + u_{i, j, n+2} - \Delta\tau \cdot q_{ij} \quad (75)$$

These equations are to be written in the standard form:

$$\begin{aligned} b_1 u_{i, 1, n+2} + c_1 u_{i, 2, n+2} &= d_1 \\ \dots\dots\dots \\ a_j u_{i, j-1, n+2} + b_j u_{i, j, n+2} + c_j u_{i, j+1, n+2} &= d_j \\ \dots\dots\dots \\ a_N u_{i, N-1, n+2} + b_N u_{i, N, n+2} &= d_N \end{aligned} \quad (76)$$

We find again that, in general, that is, for $j \neq 1$ or $j \neq N$

$$\begin{aligned} a_j &= \mu, \quad b_j = -(2\mu + 1), \quad c_j = \mu, \\ d_j &= -\lambda[u_{i+1, j, n+1} - 2u_{i, j, n+1} + u_{i-1, j, n+1}] - \frac{\lambda \cdot \Delta\rho^*}{2\rho_1 + (2i-1) \cdot \Delta\rho} \\ &\quad [u_{i+1, j, n+1} - u_{i-1, j, n+1}] - \Delta\tau \cdot q_{ij} - u_{i, j, n+1} \end{aligned} \quad (77)$$

Using Eq. (46) for $u_{i, 0, n+2}$, we change b_1 to

$$b_1 \leftarrow b_1 + a_1 \left[\frac{2 - h_3 \cdot \Delta\xi}{2 + h_3 \cdot \Delta\xi} \right] \quad (78)$$

* $-\lambda\Delta\rho/2\rho_i$

We also change d_1 to

$$d_1 \leftarrow d_1 - a_1 \left[\frac{2 \cdot \Delta \xi \cdot g_3}{2 + h_3 \cdot \Delta \xi} \right] . \quad (79)$$

Similarly we use Eq. (47) for $u_{i,N,n+2}$ to change b_{N-1} to

$$b_N \leftarrow b_N + c_N \left[\frac{2 - h_4 \cdot \Delta \xi}{2 + h_4 \cdot \Delta \xi} \right] . \quad (80)$$

and

$$d_N \leftarrow d_N - c_N \left[\frac{2 \cdot \Delta \xi \cdot g_4}{2 + h_4 \cdot \Delta \xi} \right] . \quad (81)$$

Again, as long as $i \neq 1$, or $i \neq M$, the d 's require no further modification because their computation involves only "net" points at time level $n + 1$. However, when $i = 1$, the fictitious points $u_{0,j,n+1}$ are involved. Also, when $i = M$, the fictitious points $u_{M+1,j,n+1}$ are involved. The simplest way to handle this is to "border" the $u^* = u_{i,j,n+1}$ array by computing $u_{0,j,n+1}$ with Eq. (44) and $u_{M+1,j,n+1}$ with Eq. (45) before starting on the second half of the I.A.D. set. We shall keep the $0, 2, \dots, n$ even level u 's in an array $U(I, J)$. We shall keep the $1, 3, \dots, n$ odd level u 's in an array $USTAR(I, J)$.

8.6 The Time Coordinate

The time coordinate τ_n is constructed so as to be controlled by an integer n and an increment $\Delta\tau$ in a special way. Because we are using the I.A.D. method, the "net" values of temperature are only valid when u is an even integer. In addition, it should be noted that $\Delta\tau$ may be changed before entering a new cycle involving an alternating difference pair of finite difference equations.

Initially, temperature varies relatively rapidly with time. This means that rather closely spaced time units should be selected at which to calculate the temperature. Later, as the temperature approaches its steady state value, its change is less rapid so that it seems reasonable, especially from the viewpoint of conserving computer time, to calculate temperatures at much larger intervals of time. This can be accomplished by allowing the time interval $\Delta\tau$ at a particular choice of n to increase according to the scheme:

$$\Delta\tau(n) = 2^{n/n_0} \Delta\tau_0 . \quad (82)$$

$\Delta\tau_0$ is some arbitrarily-selected initial value of $\Delta\tau$, n is a positive even integer and n_0 is some arbitrary positive integer, called the "doubling count number," because when n reaches n_0 , $\Delta\tau$ will double to $2\Delta\tau_0$. Making n_0 very large is equivalent to holding $\Delta\tau(n) = \Delta\tau_0$.

Meanwhile, the time coordinate τ_n is formed according to the prescription:

$$\tau_n = 2 \sum_{k=0}^n \Delta\tau(k) = 2\Delta\tau_0 \sum_{k=0}^n 2^{k/n_0} \quad (83)$$

in which k is incremented in steps of 2 up to n . This prescription will hold up to the limit $n = n_L$. The actual value of n_L will be determined by the parameter n_{\max} , a positive integer which is inputted at the start of the program. The integer n_L will be equal to $n_{\max} - 2$ if n_{\max} is even, or, to $n_{\max} - 1$ if n_{\max} is odd. At $n = n_L$, the increment is designated by $\Delta\tau(n_L)$ and the time by τ_{n_L} . That is:

$$\Delta\tau(n_L) = 2^{n_L/n_0} \Delta\tau_0 \quad (84)$$

$$\tau_{n_L} = 2\Delta\tau_0 \sum_{k=0}^{n_L} 2^{k/n_0} \quad (85)$$

For times greater than τ_{n_L} , corresponding to $n > n_L$, the increment will remain fixed at $\Delta\tau(n_L)$, whereas the time will be given by:

$$\tau_n = \tau_{n_L} + \Delta\tau(n_L) \cdot (n - n_L)/2 \quad (86)$$

The time τ_n will keep increasing by these fixed increments until it reaches some arbitrarily-fixed upper limit τ_{\max} , at which point the program initiates a termination procedure.

By virtue of another time-control parameter, the program also makes provision for turning the source off and then determining the temperature changes as the window cools off. This occurs at $\tau = \tau_{\text{off}}$, where, of course, τ_{off} must be $\leq \tau_{\max}$.

Should τ_n , as determined by Eq. (86), become greater than τ_{off} at the start of a time loop, and if $\tau_{\text{off}} < \tau_{\max}$, then the time-incrementing procedure is reinitiated. On the other hand, should τ_n exceed τ_{off} at the start of a time loop, and if $\tau_{\text{off}} = \tau_{\max}$, then the subroutine CYLTMP (to be described later) does not

continue with the calculation, but returns control to the main program. Thus, the actual maximum time value will usually be slightly less than τ_{off} if the window is being irradiated, and will be slightly less than τ_{max} if the window is experiencing a cooling phase.

From the analysis above, we see that, apart from the running index n , usually 4, or, at most 5, parameters are required to control the time coordinate, viz, n_0 , n_{max} , $\Delta\tau_0$, τ_{max} and τ_{off} . The time interval $\Delta\tau$ can be enlarged by increasing $\Delta\tau_0$ or n_{max} , or by decreasing n_0 .

8.7 The Main Program and Principal Subroutines

The coding necessary to input all of the data, to carry out all of the required calculations, including the I.A.D. prescriptions, and finally, to print out the results constitutes a major programmed package, named the TEMP5 program. This package consists of eight principal subroutines called into execution by one very short main program. This latter program has also been designated as TEMP5. However, whenever we use the term "TEMP5 program" throughout this report we will always mean the collective "package" rather than this one main program, unless stated otherwise.

The TEMP5 program is composed of the following:

- (1) TEMP5 - a very short program whose principal purpose is to call the 2 principal subroutines DATINIT and CYLTMP.
- (2) DATINIT - a subroutine which inputs all required parameters necessary for program operation by a call to subroutine GETDATA. It initializes the principal arrays used by subroutine CYLTMP. It also calls subroutine GAUSS.
- (3) CYLTMP - the "core" subroutine of the TEMP5 program. It calculates the temperature u according to the I.A.D. method using both subroutines TRIDAG and SPLNI and then the related integrals $F1$ and $F2$ again using SPLNI. It stores u , $F1$ and $F2$ in unformatted form on a file named TAPE3. These temperatures (u) are calculated at the RHO, ZED lattice points and are designated by the variable name $U(I, J)$.
- (4) TRIDAG - the subroutine which implements the Thomas algorithms for solving a system of simultaneous linear equations having a tridiagonal coefficient matrix.
- (5) GAUSS - a subroutine for loading the volume heating source term Q with a truncated Gaussian distribution into the program.
- (6) SPLNI - The subroutine which finds the third order spline function for a function $y(x)$ given at the points $(X(I), Y(I))$. It is used both for integrating the $F1$ and $F2$ functions as well as for interpolating values of u at the RFIN, ZFIN lattice points, which occur halfway between the RHO, ZED lattice points. These interpolated temperatures are designated by the variable name $UFIN(I, J)$. They enable

us to calculate temperatures out to the window's edges. SPLNI, which follows Chapter 8 of Ralston and Wilf,¹⁴ is a modification of the IBM standard Scientific Subroutine Package subroutine SPLIE.

(7) GETDATA - obtains data from the operator. It can be used as a universal inputting subroutine for either the Batch or Intercom modes of operation of any program requiring input data. (More will be said about these two modes later.) However, it was written mainly for Intercom operation. It also calls on subroutines SSWTCH and RJUST.

(8) SSWTCH - reads in the first three data values (and prints out appropriate messages) for GETDATA control. (It should be noted that SSWTCH is not the same as the CDC Fortran subroutine bearing the same name.)

(9) RJUST - right adjusts all numerical values.

The TEMP5 program has been coded to permit operation under either Batch processing or Intercom. The latter mode permits relatively easy interactive use, as implemented under CDC Scope 3.4 with the CDC6600.

The complete Fortran listings for each of the above are given in Appendix A.

8.8 Implementation of Some of the Subroutines

8.8.1 DATINIT

The implementation of the TEMP5 program begins with the inputting of all required program parameters and the initializing of the working arrays which will eventually be used by CYLTMP. DATINIT accomplishes all of this by a call to GETDATA. Furthermore, DATINIT assigns default values to the VALUE portion of DATAIN, which is an array of TEMP5 parameters, and also assigns names and format codes to the NAME and FORMAT portions of DATAIN. This will be described in more detail in Section 8.8.4 on GETDATA.

A complete tabulation of all the required input data is given in Table 2. The table lists both the data and the variable names, their corresponding default values, formats, the particular major programming package in which each quantity is ultimately used, and a succinct description. The default values listed in Table 2 for the material properties such as refractive index, absorption coefficient, etc., pertain to KCl.

It should be noted that although all of the variables itemized in Table 2 may be inputted at this stage of the program, not all of them will actually be used in TEMP5. Many of them will be called up later in the TIKIRK and DISPLAY programs.

14. Ralston, A., and Wilf, H.S. (1967) Mathematical Methods for Digital Computers, Vol. II, Wiley and Sons, Inc., New York.

Another factor to be noted in Table 2 is that the values of M and N have been chosen to be 80 and 20, respectively. Since the indices on the RHO and ZED coordinates extend from 0 to M+1, and, 0 to N+1, respectively, this means that the net depicted in Figure 3 consists of 82 points along the radial direction and 22 points along the axis. Meanwhile, since the indices on the RFIN, ZFIN coordinates extend from 1 to M+1, and, 1 to N+1, respectively, then the array of points at which interpolation occurs consists of 81 points along the radial direction and 21 points along the axis.

8.8.2 CYLTMP

The temperature-related terms U, F1 and F2 really constitute the principal output of the entire TEMP5 program. Computation of these quantities, as prescribed by Eqs. (29), (30), (16) and (17), are actually carried out by the subroutine CYLTMP, with the aid of TRIDAG and SPLNI. Figure 20 shows a flow chart for the CYLTMP algorithm. Table 3 gives a glossary of the variable names.

Source turn-off is accomplished in subroutine CYLTMP by setting the volume source term (array q) and "boundary" source term (array g) to 0 at the appropriate time. At the end of each τ -cycle through CYLTMP, the temperature distribution at $\tau + \Delta\tau$ has been computed where τ is the time at the start of the cycle. Thus, a check is made at the start of each cycle to see if $\tau + \Delta\tau$ is less than τ_{off} . If it is, then the cycle continues normally with the source terms "on." When $\tau + \Delta\tau$ first becomes equal to or greater than τ_{off} , a "flag" is set and a new $\Delta\tau$ is computed such that $\tau + \Delta\tau = \tau_{\text{off}}$ and the cycle continues. When the subroutine returns to the start of the next cycle, the source term is set to 0. In addition the variable NN is reset to 0 and $\Delta\tau$ is computed as was done for source turn-on.

8.8.3 TRIDAG

This is a subroutine for solving a system of linear simultaneous equations having a tridiagonal coefficient matrix. The equations are numbered from IF through L, and their subdiagonal, diagonal, and superdiagonal coefficients are stored in arrays A, B, C. The computed solution vector (V(IF),, V(L)) is stored in array V.

The mathematical details of all of the steps involved in solving the tridiagonal equations have been given in Section 8.4.

The coding for subroutine TRIDAG is taken from Carnahan et al¹¹ on page 446.

8.8.4 GETDATA

8.8.4.1 Description

This subroutine is designed for inputting problem data when a program is run under CDC6600 INTERCOM control. It may also be used, however, for inputting

Table 2. Input Data for the Implementation of the TEMP5 Program

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Useage Code	(7) Description
1*	I1	I1	2	0	T	Print/punch F1, F2 and parameters.
2*	I2	I2	2	0	T, K	Print TAU, LMDA, MU, MN, NQ, INIT, ICNTR. Also, use 1 if IKIRKP option is desired; use 2 for IKIRK option. (see Sec. 9.2.)
3*	I3	I3	2	0	T	Print arrays: KK, A, B, C, D, UPRIM in CYLTMP; also initial values of U, USTAR, etc.
4*	I4	I4	2	0	T	Print U and Q after initial data read-in or computation.
5*	I5	I5	2	0	T	Print array UFIN at every fifth value of both RFIN and ZFIN.
6*	I6	I6	2	0	T	Punch array UFIN and parameters.
7*	I7	I7	2	0	T	Print array U at the following RHO(I) and ZED(J) points: I=2, 2+MI, 2+2MI, 2+3MI, ..., ≤ 81 J=2, 2+NI, 2+2NI, 2+3NI, ..., ≤ 21 .
8	M	M	80	0	T	M+1 is the number of radial points at which temperature data is outputted.
9	N	N	20	0	T	N+1 is the number of axial points at which temperature data is outputted.

*For I1 through I7: If the value is set equal to 1, then appropriate output will be printed; if the value is set equal to 2, then output will be suppressed.

Table 2. Input Data for the Implementation of the TEMP5 Program (Cont.)

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Useage Code	(7) Description
10	MI	MI	1	0	T	Every MI-th point in the radial direction is printed (see I7).
11	NI	NI	1	0	T	Every NI-th point in the axial direction is printed (see I7).
12	ICNT	ICNT	1	0	T	Array U is printed out for every ICNT-th time cycle (see I7).
13	IU	IU	0	0	T	If 0, temperature distribution U initialized to U0. If 1, initial temperature distribution read-in on file tape ICARD.
14	IQ	IQ	1	0	T	If IQ = 0, initialize source Q to zero. If IQ = 1, initialize source Q to Gaussian. If IQ \neq 0, 1 read source Q from file tape ICARD.
15	<u>N0</u>	<u>N0</u>	2	0	T	The arbitrary positive integer n_0 in Eq. (82) of text.
16	NMX	NMX	11	0	T	n_{max} (see Sec. 8.6).
17	IRUN	IRUN	100	0		Not used.
18	ICARD	ICARD	5	0	T	Input file for some of the input controlled by IU, IQ.

Table 2. Input Data for the Implementation of the TEMP5 Program (Cont.)

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Usage Code	(7) Description
19	IPRINT	IPRINT	6	0	T	Output file for all TEMP5 output except for some of the "interactive" output and unformatted temperature output.
20	IPNCH	IPNCH	-	0	N	In original TEMP5, identifies "punch" output file.
21	ITAP3	ITAP3	3	0	T	Unformatted output file for time-temperature.
22	ITAP4	ITAP4	4	0	T	"Interactive" input file.
23	RHO1	RHO1	0	1	T	ρ_1
24	RHO12	RHO12	1	1	T	ρ_{12}
25	ZED1	ZED1	-.5546	1	T	ξ_1
26	ZED12	ZED12	1.1092	1	T	ξ_{12}
27	DTAU0	DTAU0	.0035	1	T	$\Delta\tau_0$
28	TAUMX	TAUMX	5.0	1	T, K	τ_{\max} (see Sec.8.6).
29	TAUOFF	TAUOFF	5.0	1	T	τ_{off} (see Sec.8.6).
30	SIG	SIG	.1292	1	T, K	Either σ or σ_e (see Eq. (33) or (37)).
31	Q0	Q0	0	1	T	If you want $A = \Delta\tau_c/2\sigma^2$ (see Eq. 37), then set $Q0 = A$. (Be sure $A \geq .001$; highly unlikely to be otherwise). If you want $A = 1/2 \sigma_e^2$ (see Eq. 33), then set $Q0 < .001$ (say, 0).
32	U0	U0	0	1	T	Initial (uniform) temperature distribution.

Table 2. Input Data for the Implementation of the TEMP5 Program (Cont.)

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Useage Code	(7) Description
33	EPS	EPS	.001	1	T	Error tolerance in spline interpolation.
34 to 37	G1(1), G1(2), G1(3), G1(4)	G1	0, 0, 0, 0	1	T	Surface heat flux (see Eqs. (33) or (37)).
38 to 41	H1(1), H1(2), H1(3), H1(4)	H1	0, .0113 .0113 .0113	1	T	Surface heat transfer coefficient (see Eqs. (33) or (37)).
42	MATERIAL	MATER	KCL	-1		Cylinder material identifier. Used for identification purposes only. It is not "used" by any program, but can, of course, be printed in TIKIRK listings and on DISPLAY plots.
43	REF. IND.	NX	1.47	1	K	Cylinder refractive index.
44	BETA	BETA	.00048	1	K	Bulk absorption coefficient (cm^{-1}).
45	THER. COND	K	.0653	1	K	Thermal conductivity ($\text{W}/\text{cm}^{\circ}\text{C}$).
46	LAMBDA	LAMBDA	10.6	1	K	Wavelength (microns).
47	S1R	S1R	-.34E-5	1	K	Stress optic coefficient $S_1^p(^{\circ}\text{C})^{-1}$.
48	S1T	S1T	.05E-5	1	K	Stress optic coefficient $S_1^t(^{\circ}\text{C})^{-1}$.
49	S2R	S2R	.1E-5	1	K	Stress optic coefficient $S_2^p(^{\circ}\text{C})^{-1}$.
50	S2T	S2T	-.1E-5	1	K	Stress optic coefficient $S_2^t(^{\circ}\text{C})^{-1}$.
51	DENSITY	DEN	1.98	1	K	Density (gm/cm^3).
52	SPEC. HEAT	CP	.691	1	K	Specific heat ($\text{J}/\text{gm}^{\circ}\text{C}$).
53	RADIUS	R	1.258	1	K	Radius (cm).

Table 2. Input Data for the Implementation of the TEMP5 Program (Cont.)

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Useage Code	(7) Description
54	EXPER	EXPER	2	-1		Not used.
55	PWR	PW	24.7	1	K	Transmitted power P_t , in watts (see Eq. 9).
56	R1	R1	81	0		Not used.
57	Z1	Z1	11	0		Not used.
58	R2	R2	1	0		Not used.
59	PLT ? IY, 2N	IPLOT	1	0		Not used.
60	PROBNO	PROBNO	2347	-1		Problem number- for plot identifi- cation.
61	TICU	TICU	.5	1		Not used.
62	XLEN	XLEN	20.	1		Not used.
63	YLEN	YLEN	9.	1		Not used.
64	X-SCALE	SCALEX	12.	1		Not used.
65	Y1-SCALE	SCALEY1	.2	1		Not used.
66	Y2-SCALE	SCALEY2	.2	1		Not used.
67 to 71	XTITLE1 2, 3, 4, 5	XTITLE	time	-1	D	The x-axis is given a title of the form "XTITLE scale is n units/ tic" where n may be scalex. Also parameter title.
72 to 76	YTITLE1 2, 3, 4, 5	YTITLE1	temp- deg. C above amb	-1	D	Similar to XTITLE, "sur- face" title in DISPLAY.
77 to 81	YTITLE2 2, 3, 4, 5	YTITLE2	mean temp above amb	-1		Not used.
82	OPERATOR	NAME	GIANINO	-1	D	Plot identification (required for pick- ing up plots at central site).

Table 2. Input Data for the Implementation of the TEMP5 Program (Cont.)

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Useage Code	(7) Description
83 to 87	XTI 2, 3, 4, 5		radial distance rho-(cm)	-1	D	Title for "x-axis" in DISPLAY.
88 to 92	YT1 2, 3, 4, 5		axial distance, z-(cm)	-1	D	Title for "y-axis" in DISPLAY.

N.B. 0 means "zero"; 0 means "oh".

Explanation of Columns

- (1) The sequence number of the datum stored in array DATAIN.
- (2) Datum name used by operator when he inputs the data. This name is a character string. E.g., I1 means 2HI1 in Hollerith notation.
- (3) The symbolic name used in the TEMP5 program. The same quantity may be given a different variable name in other programs that used the quantity.
- (4) The value that will be assigned to each item listed, unless a different value is inputted.
- (5) 0 \equiv integer (I10) format.
1 \equiv floating point (E10.0) format.
-1 \equiv character string (6A10) format, that is, up to 60 characters are permitted.
- (6) N \equiv not used.
Y \equiv used in TEMP5 program.
K \equiv used in TIKIRK program.
D \equiv used in DISPLAY program.

Table 3. Glossary of Variable Names^{*†}

A(I)	. =. Tridiagonal system . =. coefficient vectors.
B(I)	. =. Tridiagonal system . =. coefficient vectors.
BETA(I)	. =. Auxiliary variable: Thomas Algorithm for TRIDAG matrix inversion.
C(I)	. =. Tridiagonal system . =. coefficient vectors.
D(I)	. =. Tridiagonal system . =. coefficient vectors.
DRHO	. =. Program control parameter . =. $\Delta\rho = (\rho_2 - \rho_1)/M$.
DTAU	. =. Time increment parameter . =. $\Delta\tau$.
DTAU ₀	. =. Time increment parameter . =. $\Delta\tau_0$.
DZED	. =. Program control parameter . =. $\Delta\xi = (\xi_2 - \xi_1)/N$.
E(I)	. =. Space increment array . =. DRHO, DZED.
EPS	. =. Error tolerance in iterative steps.
F1(I)	. =. An array of integrals.
F2(I)	. =. An array of integrals.
G(I)	. =. Coefficient in general boundary condition.
GAMMA	. =. Auxiliary working variables-Thomas Algorithm (see Eq. (58)).
GAUSS	. =. Subroutine for loading Q with a truncated Gaussian distribution.
GF(X, Y, Z)	. =. Statement function = $(2.*Y*Z)/(2.+X*Y)$.
G/H	. =. Given nondimensional surface temperature.
G(I)	. =. g_1, g_2, g_3, g_4 . =. boundary condition parameter.
G1(I)	. =. Buffer to retain input G(I). G(I) modified during program execution.
H(I)	. =. h_1, h_2, h_3, h_4 . =. boundary condition parameter. Film coefficient.
HF(X, Y)	. =. Statement function . =. boundary condition . =. $(2.-X*Y)/(2.+X*Y)$ (see Eqs. (44)-(47)).

*The symbol . =. means "is defined as."

† 0 means "zero"; 0 means "oh."

Table 3. Glossary of Variable Names (Cont.)

H=0, G=0	.	=. No heat crosses boundary .=. physical significance of H and G.
H1(I)	.	=. Buffer to retain input H(I). H(I) is modified during program execution.
I	.	=. Indexing variable.
ICARD	.	=. Logical device number for card reader.
ICNT	.	=. Number of I. A. D. cycles between printouts.
ICNTR	.	=. Number of I. A. D. cycles since last printouts.
IF	.	=. Indexing variable.
II	.	=. I-1.
IKEY	.	=. Logical device number for keyboard (or card) input.
IPM(I)	.	=. Basic program parameters integer: see equivalence statements.
IPNCH	.	=. Logical device number for the card punch.
IPRINT	.	=. Logical device number for line printer.
IQ	= 0	=. Initialize Q to zero .=. no absorption.
	= 1	=. Calculated Q for Gaussian distribution.
	= 2	=. Read in value of Q.
IRUN	.	=. Run number.
ITAP3	.	=. Logical device number for TAPE3.
ITAP4	.	=. Logical device number for TAPE4.
ITYPE	.	=. Printing out on operators terminal (if possible). Logical device number.
IU	= 0	=. Initialize U (temp) to zero.
	= 1	=. Read in initial value of U.
I1	.	=. Punch and print F1, F2, and parameters. Control for output.
I2	.	=. Print TAU, LMDA, MU, NN, NO, ICNT, ICNTR. Control for output.
I3	.	=. Print KK, A, B, C, D, UPRIM .=. Initialize values of U, USTAR, etc. TRIDAG debug.
I4	.	=. Print U and Q after initial data read-in or computed.

Table 3. Glossary of Variable Names (Cont.)

I5	.=. Print I, J, UFIN(I, J, K).
I6	.=. Punch UFIN and parameters.
I7	.=. Print I, J, U(I, J) on half increment shifted lattice.
J	.=. Indexing variable.
JJ	.=. Varies with J for indexing.
K	.=. Indexing variable .=. see cross reference.
KK, KS, L	.=. Indexing variables.
LMDA	.=. $\lambda = \Delta\zeta(\Delta\rho)$.=. Special parameter.
M	.=. ρ -net length .=. $M \cdot \Delta\rho = 1 - \rho_1$.
MI	.=. Step size for output do-loop .=. ρ -direction.
MS	.=. Number of given data points.
MU	.=. $\mu = \Delta\tau / (\Delta\zeta)^2$.
M1	.=. M+1. Loop indexing variable.
M2	.=. M1+1. Loop indexing variable.
N	.=. Special parameter .=. Count of Tau increments.
NF	.=. Number of time intervals.
NFF	.=. Duplicate storage for NF.
NI	.=. Step size for output do-loop .=. zed direction.
NMX	.=. N_{\max} .
NN	.=. n.
NS	.=. Number of Spline Interpolated arguments.
NSEQ	.=. Sequencing index for punched card output.
N0	.=. Delta Tau doubling count.
N1	.=. N+1.
N2	.=. N1+1.
PARAM(I)	.=. Basic program parameters, REAL, see equivalence statements.
Q(I, J)	.=. Source distribution.

Table 3. Glossary of Variable Names (Cont.)

QQ	. =. Working variable used in do-loop for Q(I, J).
QUA(I)	. =. Values of integral SS from X(I) to X(N).
Q0	. =. Control parameter for calculation of Q(I, J) in GAUSS.
REX	. =. RNN/RNO.
RFIN(I)	. =. Even R-Lattice point coordinates.
RHO(I)	. =. Half-interval shifted.
RHO1	. =. ρ_1 .
RHO12	. =. $1 - \rho_1$.
RI	. =. II.
RJ	. =. JJ . =. RJ/2.
RM	. =. M.
RN	. =. N.
RNN	. =. Real representation of NN to avoid mixed mode in Delta Tau calculation.
RN0	. =. Real representation of N0 to avoid mixed mode in Delta Tau calculation.
RRR(I)	. =. RFIN(I).
SIG	. =. Variance of Gaussian beam intensity dist.
SIG2	. =. SIG squared.
SS1(I)	. =. First derivatives of U.
SS2(I)	. =. Second derivatives of U.
TAU	. =. Nondimensional time . =. τ .
TAUMX	. =. Maximum tau to be computed . =. τ_{\max} .
TFIN	. =. Array of τ -values for which we take printed or punched output.
U(I, J)	. =. Array of nondimensional temperatures on RHO-ZED lattice.
UCARD	. =. UFIN buffer for card and line printer output.
UFIN(I, J, K)	. =. U on RFIN-ZFIN lattice at Kth time.

Table 3. Glossary of Variable Names (Cont.)

UPRIM(I)	. = . Storage of results of solutions to tridiagonal equations.
USPLN(I)	. = . Temporary work space used between Rho-splining and Zed-splining.
USTAR(I, J)	. = . Intermediate temperature distribution in I. A. D. method.
U0	. = . U(I, J). For uniform initial temperature option.
V	. = . Computed solution vectors in TRIDAG.
X(I)	. = . Array of strictly increasing abscissa.
XR(I)	. = . RHO(I).
XX	. = . Work space for desired abscissas.
XZ(I)	. = . RHO protection.
YU(I)	. = . UFIN(I, J).
ZED(I)	. = . Nondimensional axial coordinate [cm] . = . Z/A.
ZED1	. = . Lower Zed boundary . = . ξ_1 .
ZED12	. = . $\xi_2 - \xi_1$.
ZFIN(I)	. = . Lattice coordinates that land on boundary instead of half shifted position. Used for CYLTMP Algorithm.
ZJ	. = . JJ.
ZZZ(I)	. = . ZFIN(I).

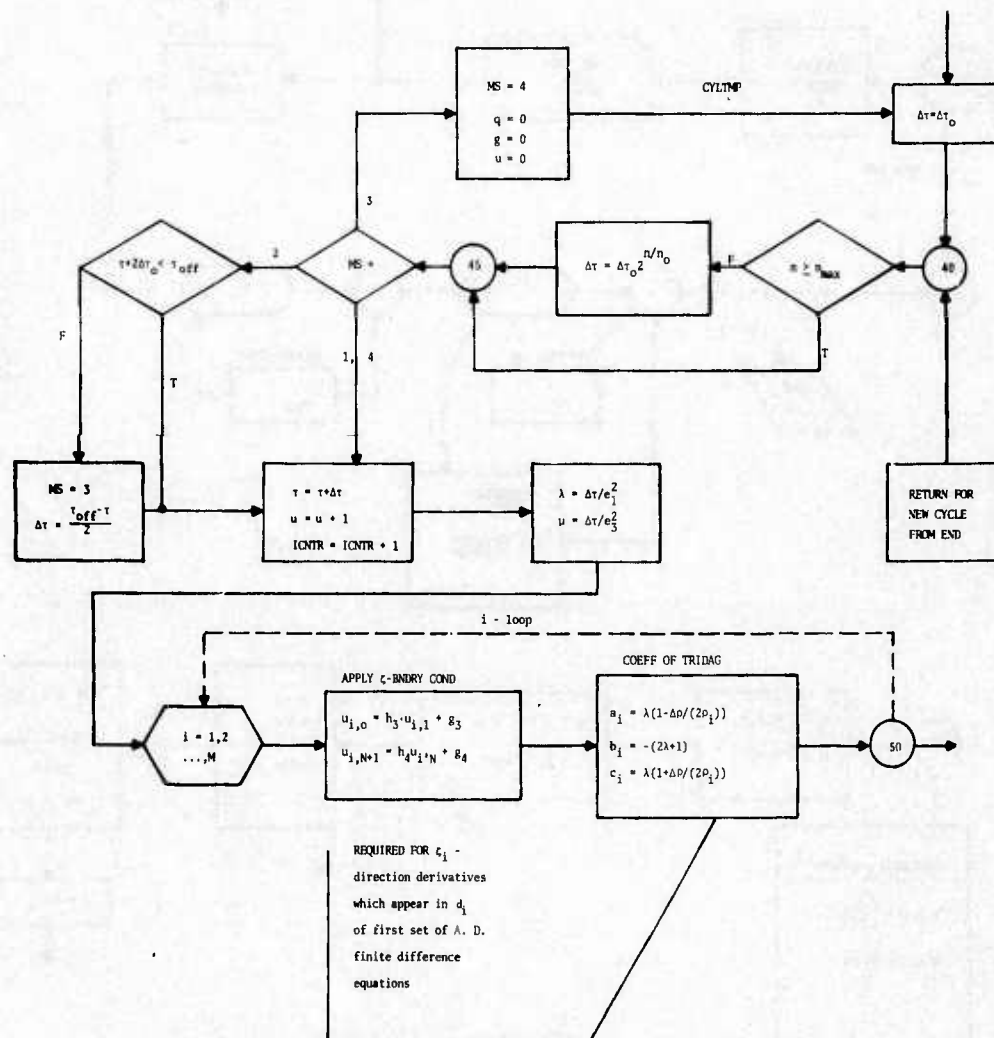


Figure 20. Flow Chart for the CYLTMP Algorithm (Sheet 2 of 4)

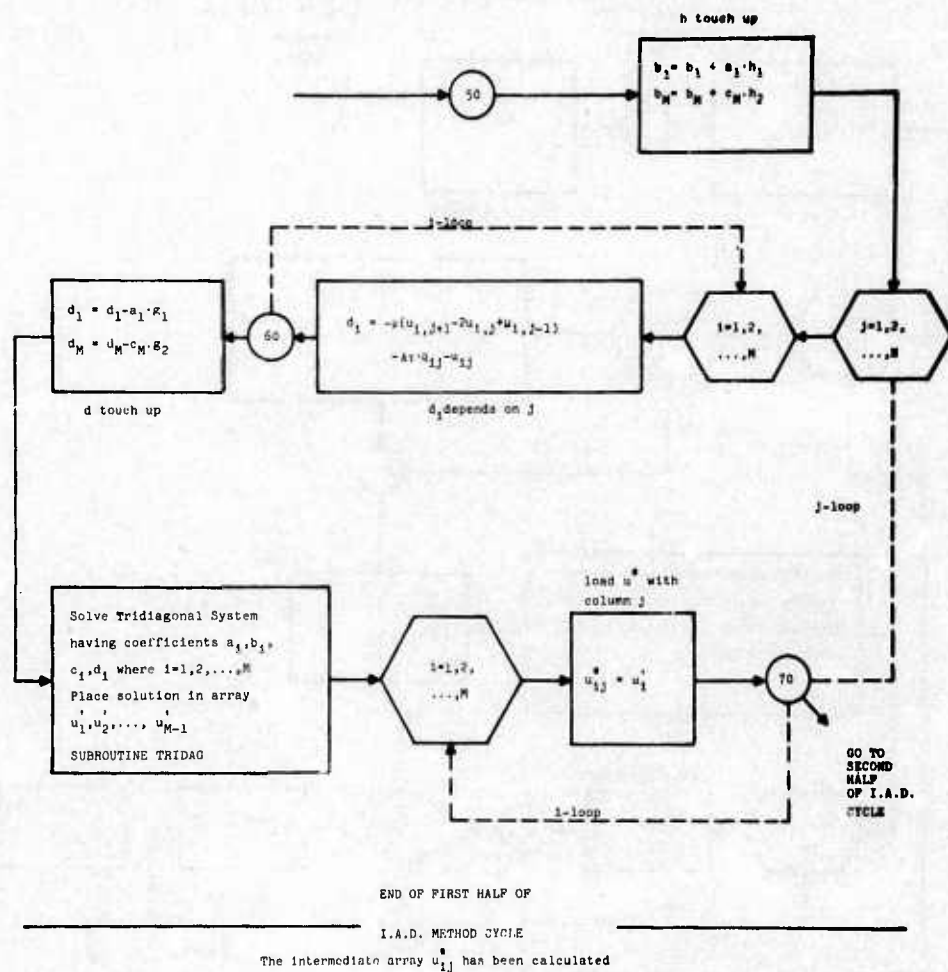


Figure 20. Flow Chart for the CYLTMP Algorithm (Sheet 3 of 4)

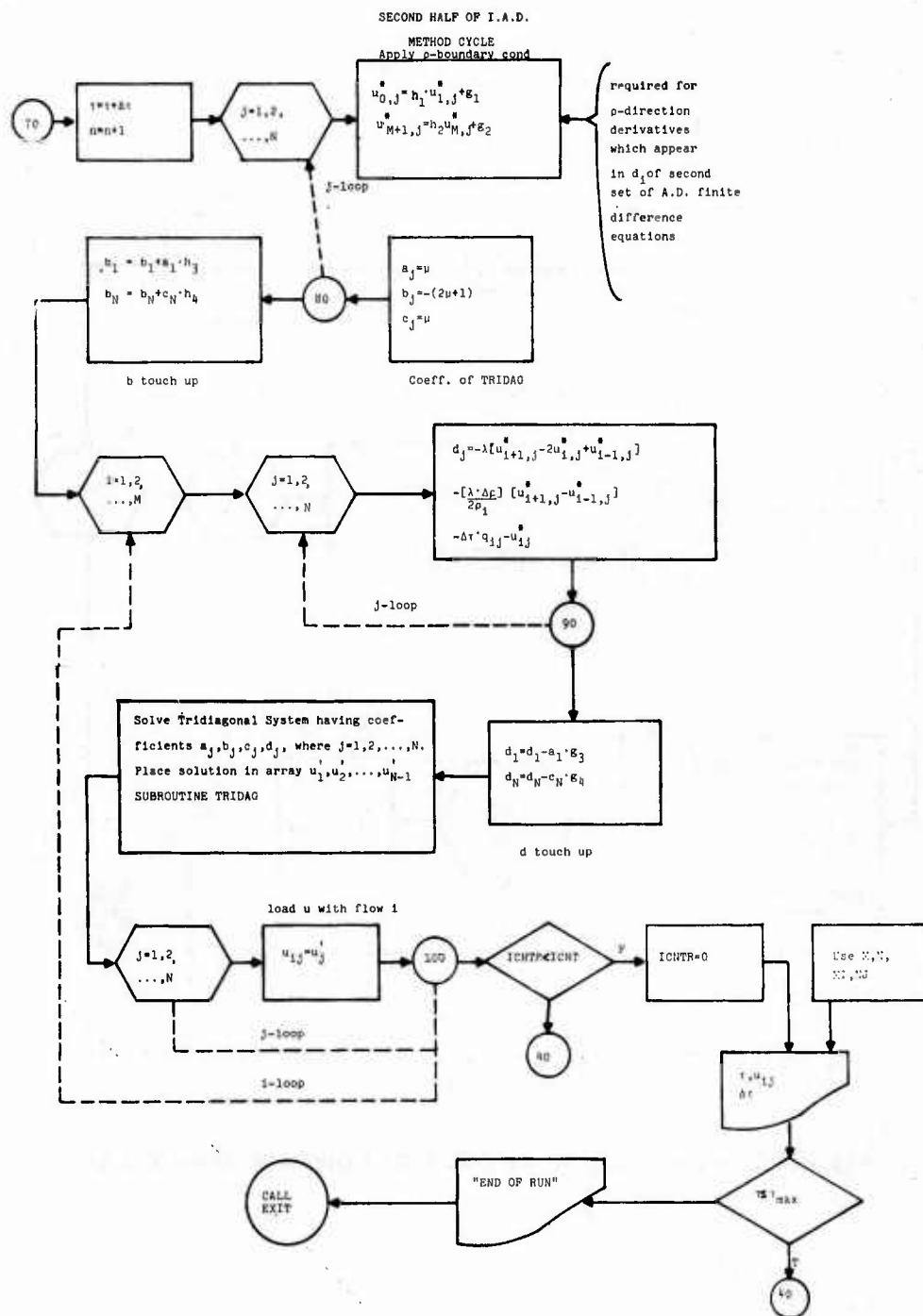


Figure 20. Flow Chart for the CYLTMP Algorithm (Sheet 4 of 4)

data when the program is "batched." The data which is obtained through GETDATA is stored in array DATAIN as an n by 3 array, where n is the maximum number of data to be inputted. Each datum consists of three parts (hence $n \times 3$), which is herein referred to as VALUE, NAME, and FORMAT. VALUE is the numerical or character string value which will be stored for the datum; NAME is a character string (up to ten characters) by which the datum may be identified. FORMAT is a code number (-1, 0, or 1) which is used to indicate that the datum is to be interpreted respectively as: character string, integer, or real (floating point) number.

The first three data required by GETDATA are not part of DATAIN, but are used to control the operation of GETDATA. In INTERCOM mode each of these three data are preceded by questions as follows:

- 1) READ DATA FILE - n ?- (n is the file number)
- 2) DEFAULTS LISTED?-
- 3) NAME-VALUE MODE?-

The input data is either YES or NO (the default is NO). If the answer to 1) is YES, then array DATAIN is filled from the first record on TAPE- n . Normally, DATAIN should be filled with defaults in the calling program. These default values will then be replaced by new "default" values obtained from TAPE- n .

If the answer to 2) is YES, then the default DATAIN is printed out in the form:

NAME=VALUE.

FORMAT is indicated by the form in which VALUE is printed. Integers are numerical values with no decimal point; floating point numbers are printed with a decimal point and possibly an exponent. Character strings are indicated by single quotes. The default values are listed in the order in which they are stored in DATAIN.

If the answer to question 3) is YES, then the NAME-VALUE input-mode is used to input data; otherwise, the LIST mode is used. These two input modes are described in detail below.

After these "control" data have been inputted, the DATAIN data are inputted.

8.8.4.2 List Mode

In the LIST mode, GETDATA starts out by printing the first NAME in DATAIN and then waits for the operator to type the VALUE to be assigned to NAME. Similarly, it sequences up to the last NAME in DATAIN, and then prints out a message "data input complete," after the last VALUE in the sequence has been given by the operator. The operator defaults a value by punching the "space," "carriage return" keys (denoted below as SP, CR, respectively). If at any time the operator realizes that an error has been made in typing any preceding VALUE (not just the

current one), it may be corrected by typing \$, CR. This causes a shift to the NAME-VALUE mode, under which both the VALUE and NAME must be given by the operator. By this means, VALUES which were assigned earlier in the sequence can be changed. After the correct name and value have been given by the operator, the LIST mode continues where it left off. For example, if the NAME, OPERATOR was listed and the operator had typed \$ next to this NAME, the same NAME would be typed again upon return from the NAME-VALUE mode. It might be noted that if a VALUE has been typed (and not signaled with \$) which is incompatible with the FORMAT to be associated with that value, then the sub-routine automatically goes into the NAME-VALUE mode after typing the message: "wrong data type-try again."

The NAME-VALUE mode has the feature of terminating input, whenever SP, CR are typed, when the program is waiting for a new NAME, VALUE pair. Thus, it may be convenient to terminate inputting when in the LIST mode, by typing \$, then SP, CR after the NAME-VALUE mode has been initiated.

8.8.4.3 Name-Value Mode

In this mode, the program first types out the words "name" (6 blanks) "value.....", and then waits expectantly with the type head directly under the "n" of "name." The operator must then type the NAME and corresponding VALUE, with the VALUE starting under or after the "v" of "value." The "....." after "value" indicate the maximum field for inputting numerical data. If the operator types a NAME which is unrecognizable, the message "try again" is typed, followed by another "name" (6 blanks) value.....". A mistake is corrected by merely typing the NAME of the datum to be corrected followed by its correct VALUE. (If a format mistake has been made--see LIST MODE--then the message "wrong data type-try again" is printed indicating that the name-value should be retyped. The "name value....." header is printed only once (or every time an unrecognizable NAME has been inputted) since thereafter it is easy to start NAME and VALUES in the correct positions. (The typehead is always placed under "n" when new data is expected.)

Data input is terminated by typing SP, CR whenever the typehead is under the "n" column of the header.

The field width for all data is ten. Specifically, integers (format=0) are read under I10 format; reals (format=1) are read under E10.0 format. Character strings (format=-1) are read under A10 format, but up to 60 characters may be inputted "at once" provided contiguous space in DATAIN has been provided for them. For example, suppose that DATAIN(10, 2), DATAIN(11, 2), DATAIN(12, 2) are given the NAMES XTITLE(1), XTITLE(2), XTITLE(3), respectively (implying that space for up to 30 "XTITLE" characters has been provided for), then the entire "XTITLE" could be inputted as follows:

NAME	VALUE.....
XTITLE(1)	DISTANCE ALONG X-AXIS (INCHES)

In the LIST MODE it is also possible to input six numerical data values at "one time." This should only be done when the job is "batched," in which case six data values may be placed on one card, each one occupying a 10-column field. Data which is not to be changed should be replaced by blanks. All or some of the data may be defaulted by using an end-of-record card after the last data to be inputted, causing GETDATA to return to the program or subroutine. If no data is included in the input file a call to GETDATA will have no effect (default DATAIN as provided by the calling program will be used), except the end-of-file indicator INDIC will be set to 1.

GETDATA has a special "gimmick" in that if it is called with a value of INDIC other than 0, it may be used to input a single datum in the LIST mode. To be used in this mode, INDIC should be set equal to the location in DATAIN of the value desired, for example, 50 for DATAIN (50, 1).

According to standard Fortran practice, trailing blanks (of numerical values) are treated as zeros. For example, 10E1 would be interpreted as 10E1~~0000~~ (that is, 10^{10000}) and 1 would be interpreted as 1~~0000000000~~ (that is, 1×10^9). GETDATA calls a subroutine (RJUST) which removes all trailing blanks from numerical (but not character string) data so that trailing blanks are not treated as zeros.

8.8.4.4 Entry-Parameter List:

SUBROUTINE GETDATA (DATAIN, NV, IIN, IOUT1, IOUT2, IIN1, ISIZE, ISIZET, INDIC) Parameters:

DATAIN	- 3 dimensional array of values, names and formats.
NV	- amount of data to be inputted.
IIN	- input file number for GETDATA.
IOUT1	- "interactive" (primary) output file for GETDATA.
IOUT2	- secondary output file (stores formatted names and values which are returned by GETDATA).
IIN1	- "scratch" input/output file for reading in "default" values of DATAIN and outputting DATAIN as modified by GETDATA. (Unformatted i/o).
ISIZE	- DATAIN is assumed to be dimensioned (ISIZE, 3) in the calling program. It is the size of the first dimension of DATAIN.
ISIZET	- 3* ISIZE.

INDIC - an end of file indicator. A value of 1 is returned if an end-of-file on input occurs. If INDIC is given a value other than 0 in the calling program, GETDATA will go into the LIST mode to obtain DATAIN (INDIC-).

When operating under INTERCOM, files IIN and IOUT1 should be "connected." The storage required for GETDATA plus its two required subroutines RJUST and SSWTCH is 266 words.

8.8.4.5 Algorithm

All data "cards" are read using 6A10 format. If the first word is blank, then the subroutine goes to the next "card" (LIST-mode) or terminates (NAME-VALUE mode). In the LIST mode, fields are searched for the first blank field, upon which the next "card" is read. In NAME-VALUE mode, the search is made only if the FORMAT code for the datum is -1, indicating a possible character string greater than 10 characters. In LIST mode, a search is made of each field to see if \$ occurs using AFCRL subroutine MXGETX. If it does, a jump is made to the NAME-VALUE mode of input. All values which are to be interpreted as numbers (integer or real) have their character string representations right adjusted using PML subroutine RJUST. The conversion from character string to coded number is done with the DECODE statement using the appropriate format (I10, F10.0, or A10).

The CDC subroutine ERRSET is called in case of a bad format. A bad format causes a jump to NAME VALUE mode of input.

8.8.4.6 Special Caution and Features

There are three different formats recognized by GETDATA: floating point (E10.0), integer (I10), and character string (6A10).

These formats are given the codes 1, 0, -1, respectively. The E10.0 format converts any decimal number which can be "sensibly" written as a string of ten or less characters into CDC6600 floating point number representation. Examples of permissible character strings are:

328.5678E4

328.5678+4 (the E may be omitted)

3285678.

3285678 (a decimal point is not necessary)

-5.77E-10

Specifically, a floating point number may be written with or without an exponent (which may be indicated by the letter E followed by a signed or unsigned integer OR a signed integer). It may or may not have a decimal point. Blanks are ignored.

The I10 format converts any decimal integer which can be written as a sequence of 10 or less characters from the set [+ , - , 0 , . . . , 9] into a CDC6600 integer. Trailing, as well as leading blanks within the field are effectively ignored. This is convenient since it is easier to input 1 for instance, as opposed to ~~0000000001~~ or 0000000001. Note, however, that ~~3002~~ would be interpreted as 3002, that is, intermediate blanks are considered to be zeros. (Note that an all blank field is NOT equivalent to 0 for GETDATA.)

The 6A10 format allows character strings of up to 60 characters to be inputted "at once." However, one must make sure that sufficient space has been provided to receive character strings of length greater than 10, since each computer word holds a maximum of 10 characters. Any of the 64 characters listed in Appendix A of the CDC Fortran Extended Manual (more or less equivalent to the set on an INTERCOM teletype terminal) are permissible characters in the string. However, the character \$ has special significance. When operating in the LIST mode, its appearance signifies that a mistake has been made in inputting some value, and the subroutine temporarily reverts to the NAME-VALUE mode. In this mode, \$ has no special significance and is accepted as a legitimate character.

GETDATA assumes that DATAIN has been filled with default VALUES, as well as with the desired NAMES and FORMATS. This initialization of DATAIN can be done by the calling program OR by GETDATA itself, by reading in a DATAIN record from file IIN1.

It is usually convenient to equivalence DATAIN to a block of variables in the calling program. This simplifies subsequent handling of the values returned by GETDATA to the calling program.

GETDATA also prints out the following error messages to aid the programmer:

- | | |
|------------------------------------|---|
| i) "try again" | Occurs when in the NAME-VALUE mode and an unrecognizable NAME is given. |
| ii) "file n is empty" | Occurs when an attempt is made to fill DATAIN from an empty file. |
| iii) "wrong data type - try again" | Occurs when a bad format is given for the datum. |

9. TIKIRK PROGRAM

9.1 Introductory Remarks

The principal objective of the TIKIRK program is to compute the Kirchhoff intensity function, as given in Eqs. (23) or (28), Volume I. Before this can be accomplished, however, the file TAPE3 containing the nondimensional temperature w versus nondimensional time τ , as outputted by program TEMP5, must be available. Besides providing the nondimensional mean temperature distributions F1 and F2 mentioned previously, this file also provides as the first record an array of constants which are required to dimensionalize the data into real temperature versus real time (cf, Sections 3, 4, and 5 of Volume I and Table 2 of Volume II). For a more complete description of this file, see Section 9.5.

9.2 Program Options

The TIKIRK program has been set up to operate under two different options; each one being brought into play by an appropriate choice of the parameter I2 in TEMP5 (see Table 2). The first option uses subroutine IKIRK, which calculates the intensity I as a function of space and time for a Gaussian source term. It does so using a 24-point Gaussian integration routine. It is the option that would be used under most circumstances. The second option constitutes a special test case. A subroutine called IKIRKP is used to evaluate the intensity functions on either one of the two mutually orthogonal axes going through the Gaussian focal point for the special case of a window having a uniform mean temperature.

Allowing the control parameter I2 in the TEMP5 program to remain equal to its default value of 2, causes the first option to be utilized, while setting I2=1 brings the second option into play.

Since the form of numerical quadrature employed in option #1 may not be accurate for all parameter values which occur in practice, a third option, which uses a subroutine called IKIRK1, is also available. This program is highly accurate (because its integration methods are more exact), but it is extremely slow. It should be used for relatively small ranges of the space-time variables, for example, as a "spot check" for IKIRK.

9.3 Principal Functions and Subroutines

The TIKIRK program requires that various operations, such as integration, interpolation, Bessel function computation, etc., be carried out during the process of its execution. These operations are performed by various function subprograms and subroutines. The names of these functions and subroutines are listed below, together with their principal tasks:

- (1) TIKIRK - the main program which calls the other subroutines and subprograms into execution. It also acts as the input/output interface for the main real functions IKIRK, IKIRKP and IKIRK1 (see below).
- (2) IKIRK - the main real function for option #1.
- (3) PHI - the function which computes $\Phi^{\rho, \theta}$.
- (4), (5) J0 and J1 - real functions; compute $J_0(\rho v)$ and $J_1(\rho v)$, respectively.
- (6) RTAPE3 - subroutine; reads and linearly interpolates (in time) temperature values from TEMP5. It also linearly interpolates in time and then outputs the dimensionalized window temperature function in a form suitable for plotting via program DISPLAY.
- (7), (8) ALI and ATSE - interpolation subroutines for PHI. ALI uses the Aitken-Lagrange method.
- (9) DQG24A - subroutine; computes x-values for Gaussian integration.
- (10) DQG24B - subroutine; does Gaussian integration.
- (11) IKIRKP - the main real function for option #2.
- (12) COMPUTE - subroutine; computes the approximations to the integrals which are used in option IKIRKP.
- (13) JI - a real function which computes moments of Bessel functions.
- (14), (15) BESJF and BESJ - a function and a subroutine, respectively, which compute the Bessel function for a given argument and order.
- (16) GETDATA - a subroutine for interactively inputting data.
- (17), (18) SSWTCH and RJUST - subroutine used by GETDATA. (See Sections 8.7 and 8.8 for more detailed explanations of GETDATA, SSWTCH and RJUST.) The listings for these two subroutines have already been given in Appendices A.8 and A.9.
- (19) PRT - printed output subroutine.

All three options mentioned above use the same "core package" of the following function subprograms and subroutines in their execution: TIKIRK, PHI, J0, J1, RTAPE3, ALI, ATSE, GETDATA, SSWTCH, RJUST and PRT. In addition to these, option #1 uses IKIRK plus the subroutines DQG24A and DQG24B, while option #2 utilizes IKIRKP plus COMPUTE, JI, BESJF and BESJ.

We have given this entire package of 19 main programs, subroutines, etc., constituting the TIKIRK program for options #1 and #2 only, the permanent file name (PFN) of TIBX.

The complete Fortran listings for each of the above function subprograms and subroutines are given in Appendix B.

9.4 Inputting the Data

After program TEMP5 has been executed, output file TAPE3 has been produced and the TIKIRK program attached, various program control data and constants pertaining to the calculation of the intensity function must be inputted, regardless of the option desired. A list of these data is given in Table 4. (The array containing this information is called DATAIN1 in the TIKIRK program.) The column headings are identical with those of Table 2, except that there is no Usage Code column included here. Their meanings are cited in a footnote in the table.

The total "load" storage required for the TIKIRK program is 56133 B words. (The program will operate with a core memory of 60K.) Single precision is used for most calculations. In fact, a comparison of IKIRK and IKIRKP indicates agreement to 4 significant figures.

Since the maximum number of sample "v-values" is 100, then MP should be ≤ 100 . If more sample values are required, then array BUF should be dimensioned accordingly. Producing the full array of 100×100 function values takes 327 cpu secs (with OPT=1).

9.5 Program Files

The TIKIRK program depends on unformatted output from the TEMP5 program and requires up to 6 files. The names of the files used are (in the order they appear in the program statement):

- TAPE4 - "Interactive" input file for inputting data via GETDATA. It is used for formatted read and must be set to INPUT for batch operation.
- TAPE5 - "Interactive" output file for outputting messages from GETDATA and for outputting a small amount of program flow information.
- TAPE3 - Unformatted file outputted by TEMP5. This file, among other things, contains the mean temperature distribution functions F1 and F2 required by IKIRK and IKIRKP. In addition, the first record is the 100 by 3 array referred to as DATAIN containing various constants required by TIKIRK and contained in Table 2. The following temperature records are assumed to be of the form:

NF, TFIN, RFIN(82), ZFIN(22), UFIN(82, 22), F1(82), F2(82)

- TAPE7 - Unformatted file containing the intensity distribution function in a form suitable for DISPLAY. The first two records are the 100 by 3 data arrays DATAIN and DATAIN1, the contents of which contain all pertinent program parameters as well as labeling information for DISPLAY. All subsequent records are of the form:

Table 4. Program Control Data and Constants Pertaining to the Calculation of the Intensity Function. The column headings are identical with those of Table 2, except that there is no Usage Code column included here.

(1) Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Description
1	X0	X0	1500.	1	Gaussian focus X_0 (meters).
2	X1	X1	1000.	1	Minimum X-value (meters).
3	X2	X2	2000.	1	Maximum X-value (meters).
4	RHOP1	RHOP1	0.	1	Minimum ρ' -value (cm).
5	RHOP2	RHOP2	2.	1	Maximum ρ' -value (cm).
6	MP	MP	100	0	To calculate J values of intensity along the ρ' (or v) axis, where J = any integer, and have each calculation spaced by ρ'_{\max}/J (or v_{\max}/J) units, set $MP = J + 1$.
7	NP	NP	100	0	To calculate K values of intensity along the X (or u) axis, where K = any integer, and have each calculation spaced by $(X_{\max} - X_{\min})/K$ [or, $(u_{\max} - u_{\min})/K$] units, set $NP = K + 1$.
8	T1	TIM(1)	10.	1	} Array of time values for function evaluation (seconds). Note that if $t_{i+1} < t_i$ then the program stops. Never set $T1 = 0$; use some small number instead, e.g., $1E-6$.
9	T2	TIM(2)	-1	1	
-	-	-	-	-	
17	T10	TIM(10)	-1	1	} Array of time values for function evaluation (seconds). Note that if $t_{i+1} < t_i$ then the program stops. Never set $T1 = 0$; use some small number instead, e.g., $1E-6$.
18	EPSI	EPSI	.001	1	
19	MINT	MINT	6	0	
20	IPRNT	IPRINT	1	0	Used by IBM Sci. Sub. ALI in interpolation of Φ^{ρ} , Φ^{θ} .
21	NGAUS	NGAUS	24	0	Used by IBM Sci. Sub. ALI and ATSE in interpolation of Φ^{ρ} and Φ^{θ} , MINT is the number of points used in the interpolation.
					Use 1 for controlling debug output. Use 2 when producing a TAPE8 file for plotting purposes.
					Number of points for Gaussian integration. Note that this number should be changed if and only if the Gaussian integration subroutine is changed.

Table 4. Program Control Data and Constants Pertaining to the Calculation of the Intensity Function. The column headings are identical with those of Table 2, except that there is no Usage Code column included here. (Cont.)

(1) Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Description
22	MODE	MODE	2	0	Use 1 if you want $I(X, \rho', t)$. Use 2 if you want $I'(u, v, t)$. (See Eqs. (28) and (23)).
23	UMIN	UMIN	-40.	1	Minimum u-value.
24	UMAX	UMAX	40.	1	Maximum u-value.
25	VMIN	VMIN	0.	1	Minimum v-value.
26	VMAX	VMAX	10.	1	Maximum v-value.
27 to 31	ST1 2, 3, 4, 5	-	Kirchhoff intensity function	-1	"Surface" title (see DISPLAY).
32 to 36	PTI 2, 3, 4, 5	-	Time (seconds)	-1	"Parameter" title (see DISPLAY).
37 to 41	XTI 2, 3, 4, 5	-	Nondimen- sional radial distance, V	-1	"X-axis" title (see DISPLAY and note below).
42 to 46	YTI 2, 3, 4, 5	-	Nondimen- sional axial distance, U	-1	"Y-axis" title (see DISPLAY and note below).
47	MSKIP	-	5	0	Of the J values of intensity calculated along the ρ' (or v) axis (see MP), every MSKIP-th value will be printed out.
48	NSKIP	-	5	0	Of the K values of intensity calculated along the X (or u) axis (see NP), every NSKIP-th value will be printed out.

NOTE: If mode = 1, then the above x, y-titles are replaced by "radial distance, rho-prime (cm)" and "axial distance, X (relative to gauss focus) (cm)," respectively.

N.B. 0 means "zero; o means "oh".

Explanation of Columns

- (1) The sequence number of the datum stored in array DATAIN1.
- (2) Same as in Table 2.
- (3) The symbolic name used in the TIKIRK program. A blank variable name means that that part of DATAIN1 has not been equivalenced to another variable.
- (4) Same as Table 2.
- (5) Same as Table 2.

I, NP, U, T, MP, XMIN, XMAX, (MP intensity values)

where

I = 1, NP for each value of time, T

NP = number of axial points

U = axial distance (either u or x depending on mode)

T = dimensionalized time

MP = number of radial points

XMIN = minimum radial distance (either VMIN or RHOP1 depending on mode)

XMAX = maximum radial distance (either VMAX or RHOP2 depending on mode)

TAPE8 - Unformatted file containing the temperature distribution function in a form suitable for display. The first record contains the 100 by 3 data array DATAIN. All subsequent records have the same form as that listed above for TAPE7 except:

U = distance along window axis (cm)

XMIN = inner window radius (usually 0)

XMAX = outer window radius
(MP temperature values)

TAPE6 - Formatted "output" file. This file contains output suitable for printing in the following sequence:

1) Contents of DATAIN

2) Contents of DATAIN1

3) Array of x-values used for Gaussian integration (if IPRNT=1 and IKIRK is called).

4) I, U, XMIN, XMAX, T every r^{th} I value
Intensity (I, J), J=1, MP, 5 if IPRNT=1

9.6 Implementing the Program

9.6.1 GENERAL INSTRUCTIONS

All of the TIKIRK data listed on Table 4 are inputted by two calls to subroutine GETDATA, regardless of the option desired. Normally, in the first call to GETDATA the required data (viz, the first DATAIN array) are obtained from file

TAPE3 by answering "yes" to the query READ DATA FILE-3? Then no changes are made to these data by returning a "space" in the "name value" mode of inputting data. On the second call to GETDATA, the operator always answers "no" to the query READ DATA FILE-7? and "yes" to the query NAME-VALUE MODE? At this point he enters the names and values of all of the input data whose numerical values differ from the default values as shown in Table 4.

The above information is sufficient for inputting the data when using the first option (that is, IKIRK). However, for those circumstances in which options #2 or #3 are desired, additional instructions are required and will be discussed in the next two sections.

Typical detailed commands which can be used to run all of the programs in both the Intercom and Batch modes are listed in various Attachments after Section 11. The "A" attachments pertain to full system operation in the Intercom mode; the "B" attachments exhibit typical control deck setups used to operate the system in the Batch mode.

Attachment 1 shows how to initiate and run a typical TEMP5- and TIKIRK-type calculation, catalog the results on permanent file and then print out these results. If a TEMP5 calculation has already been made and cataloged, Attachment 2 reveals how to change a few of the input variables so that a new temperature distribution may be obtained. If the TEMP5 calculation has been completed and cataloged, Attachment 3 indicates how to make changes in the TIKIRK parameters so that either a different portion of the former diffraction pattern or a completely new diffraction pattern will be produced with each change. Attachment 4 lists the commands necessary to produce the file, called TAPE8, which contains the temperature distribution in the window. This file is required in order to plot the temperatures.

Throughout all of the attachments, PFN stands for "permanent file name" and LFN for "logical file name."

9.6.2 SPECIAL INSTRUCTIONS FOR IKIRKP OPTION

As mentioned previously, the IKIRKP option will be employed when I2=1 in TEMP5. It then calculates the intensities along either the X- or the ρ' -axes if MODE is set equal to 1, or, along either the u- or the v-axes if MODE=2. The choice of the value for MODE is made, of course, at the second call to GETDATA when inputting the data for the TIKIRK program. Specifically, IKIRKP assumes that the window temperature is constant throughout and that it may or may not be a function of time. This assumption considerably simplifies the integrations delineated in Eq. (23), Volume I, which lead to the intensity function. The details of the mathematics leading to the evaluation of $I'(u, 0, t)$ and $I'(0, v, t)$ are enumerated in Appendix C.

In addition to this choice of I2, a few other input parameters in TEMP5 must be fixed to assure that all of the conditions imposed on the window are properly accounted for. If the window temperature is to remain fixed with time (implying that there is no source), the IQ must be set to zero and U0 to the appropriate temperature. Also, all H1(I) must equal zero, otherwise, if the window temperature is allowed to vary with time, then IQ must be set equal to 1, U0 to the appropriate initial temperature and all H1(I) to zero. Furthermore, the numerical value of σ must be ≥ 0.601 (corresponding to $\alpha \leq 0.8325$), otherwise, the message "alpha * 2 is out of range" will be outputted. The reason for this restriction on σ is given in Appendix C.

In Table 5 we list the values that should be used for certain TIKIRK input parameters whenever IKIRKP is employed.

Table 5. Values Used for Certain TIKIRK Input Parameters Whenever IKIRKP is Employed.

MODE	Intensity Function Wanted	MP	NP	X1	X2	RHOP2
1	$I(X, 0, t)$	1	*	*	*	-
	$I(0, \rho', t)$	*	1	$ X_0 $	-	*
MODE	Intensity Function Wanted	MP	NP	UMIN	UMAX	VMAX
2	$I'(u, 0, t)$	1	*	*	*	-
	$I'(0, v, t)$	*	1	<u>0</u>	-	*

*Means that operator should insert whatever value he desires.

-Means that that particular parameter is of no consequence.

The commands listed in the attachments apply equally as well to the IKIRKP option. The only responses which the operator will change will be those special values of the input parameters discussed above.

9.7 The IKIRK1 Option and an Alternate TIKIRK Package

The IKIRK1 option #3 is not contained in the TIKIRK program as described in Sections 9.1 through 9.6. However, a second TIKIRK program package has been assembled which not only offers option #3 but incorporates #1 and #2 as well. Thus, it can be substituted for the original program, if desired. This package consists essentially of four parts, each one to be stored in the computer under its own PFN. The first part contains a main program, also called TIKIRK, plus those

function subprograms and subroutines making up the "core package" listed in Section 9.3 (viz, PHI, J0, J1, RTAPE3, ALI, ATSE, GETDATA, SSWTCH, RJUST and PRT). This "core package" will be utilized by the last three parts. The main program, called TIKIRK, is a slightly modified form of the main program TIKIRK first introduced in Section 8.3. As before, its principal role is to call the other subroutines and subprograms into execution. Since this first part would play a major role in computing the diffraction pattern of the transmitted beam and call upon the various options, it too has been given the PFN of TIBX by us, whenever it has been used.

The next three parts pertain to options #3, #1, and #2 in that order and we have assigned them their own particular PFN. Each one of these parts includes a major function subroutine which is also given the name IKIRK. The modified TIKIRK main program mentioned above, summons a given option by putting in a call to IKIRK. Which IKIRK (and its concomitant subroutines) gets executed depends upon which one was attached just previous to the call. (It should be noted that in this alternate TIKIRK package, the control parameter I2 no longer plays any role in determining which option will be utilized.) This procedure is demonstrated in Attachment 5, which lists typical control commands for running this new TIKIRK package under either Intercom or Batch mode of operation:

The second part, as noted above, pertains to option #3 (IKIRK1). Besides its major function subroutine IKIRK, it contains the following three subroutines:

(1) FREAL1 - computes the products of the functions $f_w f_x$ and $f_w f_y$ (see Eqs. 23-27, Volume I). It has 4 entry points since actually 4 functions have to be integrated.

(2) DCADRE - an integration subroutine from the IMSL set of routines. It requires the external function subroutine FREAL1 as one of the arguments.

(3) UERTST - required by DCADRE to output error messages.

We have stored this second part under the PFN of IK1BX.

The third part pertains to option #1, which was also referred to as IKIRK in Sections 9.2-9.6. Besides its major function subroutine, called IKIRK, it contains the two subroutines DQG24A and DQG24B, mentioned in Section 9.3. To this part, we have given the PFN of IKBX.

The fourth part contains option #2 (IKIRKP). Besides its major function subroutine, called IKIRK, it utilizes the four subroutines COMPUTE, JI, BESJF and BESJ, previously mentioned in Section 9.3. We have given the PFN of IKPBX to this part.

The Fortran listings for the modified TIKIRK program - the three major function subroutines which are each called IKIRK and which lead into each of the three options, as well as the subroutines FREAL1, DCADRE and UERTST - are given in Appendix D. All of the other subprograms and subroutines mentioned above are the same as those listed in Appendix B.

It has already been noted that option #3 (IKIRK1) is exceedingly slow. However, it may be possible to speed it up by increasing the absolute and relative errors which are presently set at 10^{-3} and 10^{-6} , respectively. In addition, the maximum value of the error parameter IER in DCADRE, as well as the maximum estimated bound on the absolute error in integration, is always printed out.

Whenever the results of IKIRK1 disagree with the results of IKIRK (option #1), those of the former should be preferred because of its greater inherent accuracy.

10. DISPLAY PROGRAM

10.1 Introductory Remarks

Program DISPLAY is a general purpose program for displaying two-dimensional arrays of numbers which, intuitively at least, can be thought of as a surface which has been sampled over an evenly spaced grid. The array size is essentially limited (by computer storage capabilities) to a maximum of 100 by 100; there is no minimum size other than the practical one that it does not make good sense to use a program such as this to display a single point. However, it may make sense to use the program to display one-dimensional arrays; for example, an array of size 1 by n . As will be explained in detail later, three types of display are offered by the program: contour map, perspective view, and multiple cross sections (parallel to two rectangular coordinate axes only). Moreover, the program is designed to display several such arrays at one RUN with the idea in mind that these arrays represent the evolution in time (or with some other parameter) of a function of two variables.

In addition to merely plotting the arrays in one or more of the above mentioned forms, this program labels all plots (provided the labeling information is furnished) and lists pertinent experimental parameters (if desired). Most of this labeling information is supplied in one or more data arrays, the structure of which has been described in DATAIN (see Section 8.8). The rest of the labeling information is provided in the records which contain the array rows.

Program control is afforded by a set of input "commands" which are supplied by input cards. The program interprets each command, obeys each command, and terminates when all commands have been followed (or when time runs out).

Before the program is used, it must be somewhat "tailored to fit." This is accomplished through the use of a fixed number of input data which must be supplied in entirety. Examples of such data are: plot id, maximum plot size, array of indices for obtaining labeling information, etc. A complete list of such data is provided in Section 10.2.

The program allows for selection of the starting "time" and its increment assuming that the surface to be displayed is a function of "time." ("Time" may be any suitable parameter.) A surface cross-section may be displayed as a function of time on a single coordinate frame.

10.2 General Instructions

The surfaces to be displayed are assumed to be stored on file TAPE3 in unformatted records where each logical record consists of one "row" of the $mp \times np$ array of floating point numbers representing the surface. In addition, each record contains the information: row number (I), total number of rows (NP), y-value to be associated with that row (Y), parameter value (if any) to be associated with (T), number of samples in the row (MP), x-value to be associated with the first element of the row (XMIN), x-value to be associated with the last element of the row (XMAX). Specifically, each record must have the form:

I, NP, Y, T, MP, XMIN, XMAX, (F(I, J;T), J=1, MP)

where $F(\cdot, \cdot; T)$ is the function to be displayed. Thus, for each value of the parameter T, NP logical records represent one "surface." Several such "surfaces" corresponding to several values of T may be stored on file TAPE3 and exhibited by DISPLAY.

In addition to the above mentioned "surfaces," file TAPE3 may contain any number (including 0) of "information" records, the contents of which include information (such as experimental parameters) which should be printed on each plot and plot titles. Each such information record must be an array (which will be called here DATAIN) of the form DATAIN(100, 3). Thus, each datum is represented by three parts called (in the order in which they appear) VALUE, NAME, and FORMAT. DATAIN is stored in unformatted form. VALUE is the numerical or character string value of the datum, NAME is a character string of up to ten characters which may be used to identify the datum, while FORMAT is a format code number (-1, 0 or 1) which specifies whether the datum value is to be interpreted as a character string (-1), integer (0), or floating point number (1). (See GETDATA, Section 8.8.4.)

These DATAIN records (if any) must be the first records on file TAPE3. Titles (if any) must appear only in the last DATAIN record.

10.3 Data Cards

The following data cards must be inputted to tailor the program for the user's particular application. The number in parenthesis in front of each datum name is the card column at which to start the datum. The number in parenthesis following the datum is the default value of the datum. If the default value is to be used, leave the corresponding card field blank.

Data Card #1

(1)	XMAX	(100.)	Maximum plot length in inches.
(11)	YMAX	(12.)	Maximum plot width in inches.
(21)	PPI	(10.)	Number of points/inch for contours.
(31)	TICU	(.5)	Number of inches between tic-marks for user defined x-y plots.
(41)	XLEN	(10.)	x-y plot coordinate frame x-size.
(51)	YLEN	(8.)	x-y plot coordinate frame y-size.
(61)	SCALEX	(1.)	x-y plot x-scale, that is, no. of x-units/ tic-mark.
(71)	SCALEY	(1.)	x-y plot y-scale, that is, no. of y-units/ tic-mark.

Data Card #2

(1)	XMIN	(0.)	} The minimum x-value and y-value to be plotted for user-defined x-y coordinate frame x-y plots.
(11)	YMIN	(0.)	
(21)	NAME	(GIANINO)	User's name to appear on plot.
(31)	PROB. NO.	(2347)	4-digit user's problem number.

Data Card #3

This card provides information for the two-dimensional array INDEX, which is the index of locations for labeling information assumed to be contained in the last DATAIN on the file containing the surfaces to be plotted. INDEX consists of pairs of numbers wherein the first number is the starting location of the label and the second number is the length of the label. If there is no such data, then this card may be left blank and the labeling will not be done. If the letter D is placed in column 1 of this card, the default values shown below are used. In addition to the values of INDEX, the field starting in column 41 should contain the number of DATAIN arrays on TAPE3.

(1)	INDEX(1, 1)	(1)	Surface title.
(6)	INDEX(1, 2)	(30)	Surface title length (characters).
(11)	INDEX(2, 1)	(4)	Parameter title.
(16)	INDEX(2, 2)	(30)	Parameter title length.
(21)	INDEX(3, 1)	(7)	x-title.
(26)	INDEX(3, 2)	(30)	x-title length.
(31)	INDEX(4, 1)	(10)	y-title.
(36)	INDEX(4, 2)	(30)	y-title length.
(41)	NDA	(2)	Number of DATAIN arrays on TAPE3. The INDEX information is taken from the last DATAIN array.

We employ the following numerical values on data card #3 for displaying the intensity (using TAPE7) and the temperature (using TAPE8):

for TAPE7: 27 29 32 14 37 33 42 32
for TAPE8: 72 20 67 13 83 24 88 31 1

Data Cards #4A, 4B, etc.

These cards contain the sequence numbers of data in DATAIN which are to be listed at the beginning of each run of DISPLAY. The sequence numbers pertaining to the TEMP5 parameters have been listed in Table 2, while those pertaining to the TIKIRK parameters have been listed in Table 4. There must be one card for each DATAIN array (see the last entry number in data card #3 above). For example, in our particular data card #3 above for the TAPE7 case, the default value of 2 is implied as the NDA entry, signifying that 2 cards must be used. The first card contains the sequence numbers of the TEMP5 parameters, while the second contains the sequence numbers of the TIKIRK parameters. The objective is to list both sets of parameters on the plots. In data card #3 above for the TAPE8 case, the NDA value of 1 was employed, indicating that only one card is to be used, viz, that containing the sequence numbers of the TEMP5 parameters which are to be listed on the plots.

The sequence numbers start in columns 1, 3, 5, 7, for a total of up to 40 indices per card. The default is a blank card. When the default is used, no DATAIN data is to be listed.

The above cards comprise the mandatory data cards. The remaining cards are the "command" cards which indicate what kinds of plots are wanted.

10.4 Command Cards

As stated previously, the DISPLAY program has the capability of 3 different types of plots, viz, multiple x-y, perspective view and contour map. Consequently, there is a command to control each type and they are indicated by the keywords PLOT, PERSPECTIVE and CONTOUR, respectively. The abbreviations PL, P and C, respectively, may also be used. These keywords are modified by certain parameters p_i . We now enumerate all of the modifying parameters of these command keywords and their meanings:

(1) Command: PLOT ($p_1, p_2, p_3, p_4, p_5, p_6$)

The parameters p_1, p_2, p_4 and p_5 are integers. In the process of creating a TAPE7 or TAPE8 file, up to ten times had to be chosen at each of which a temperature or an intensity distribution was calculated. These ten times were designated by the datum names T1, T2, ..., T10 (see Table 4). The first two parameters in the above command allow for control in selecting which times are to be chosen in the DISPLAY program. For example, the above command directs that the appropriate data corresponding to every p_1 -th time value is to be displayed, starting with the p_2 -th value (that is, T_{p_2}).

Recall that both the temperature and the intensity can be plotted either as a function of radial distance or of axial distance. The parameter p_3 can account for either of these two types of plots by taking on the code symbol X when it is a radial distance plot that is desired, or, the code symbol Y, when the axial distance plot is wanted.

For a temperature calculation, the TEMP5 program sets up a net of 82 temperature points in the radial direction (r), extending from the inner to the outer window radius, and 22 temperature points in the axial direction (z), extending from the entrance to the exit faces. Consequently, there are 22 cross-sectional surfaces of T versus r (that is, 22 type-X plots) and 82 cross-sectional surfaces of T versus z (that is, 82 type-Y plots). Thus, depending on the symbol given by p_3 , the above PLOT command directs that on one coordinate frame every p_4 -th T -versus-distance surface is to be plotted starting with the p_5 -th surface.

On the other hand, for intensity calculations, the TIKIRK program establishes a net in the far field consisting of NP intensity points along the axial line (X), extending from some minimum to some maximum axial distance, and MP intensity points in the radial direction (ρ'), starting from the axial line and going perpendicular to it. Consequently, there are NP cross-sectional surfaces of I versus r (that is, NP type-X plots) and MP cross-sectional surfaces of I versus z (that is, MP type-Y plots). Again, depending on the symbol given by p_3 , the PLOT

command directs that every p_4 -th I-versus-distance surface is to be plotted on one coordinate frame starting with the p_5 -th surface.*

The parameter p_6 can take on any one of the following code symbols: NA, NAS, NE, NES, DN or DNS. These symbols will be explained in Section 10.4, paragraph (4).

The default values for the above 6 parameters are: $p_1 = p_2 = p_4 = p_5 = 1$, $p_3 = X$ and $p_6 = NA$.

(2) Command: PERSPECTIVE (p_1, p_2, p_3, p_4)

The parameters p_1 and p_2 are the same as in the PLOT command above. The numerical value p_3 is the magnitude of the view angle in degrees, measured from the plane of the window's exit face. Parameter p_4 can take on the code symbols NA or NE only.

The default values are: $p_1 = p_2 = 1$, $p_3 = 45$ and $p_4 = NA$.

(3) Command: CONTOUR (p_1, p_2, p_3, p_4)

The parameters p_1 and p_2 are the same as in the PLOT command above. The integer p_3 refers to the number of contour levels of constant temperature, or intensity, that are to be plotted, up to a maximum of 50. Parameter p_4 can take on any one of the code symbols NA, NE or DN.

The default values are: $p_1 = p_2 = 1$, $p_3 = 10$ and $p_4 = NA$.

Note that in the above three commands, parameters are separated by commas. Missing parameters are indicated by commas (with no blank spaces between commas), or by a right parenthesis. If the keyword only appears, then default parameters are assumed.

(4) Meaning of Code Symbols NA, NAS, NE, NES, DN and DNS

The letter N means that the functions to be displayed are first normalized before being plotted, that is, the transformation

$$z \rightarrow \frac{c}{(z_{\max} - z_{\min})} (z - z_{\min})$$

(where z refers to the value of the ordinate) is made, where the value of $c = 100$ for CONTOUR plots; for PERSPECTIVE plots, it depends on the size of the array to be displayed. The latter N has a slightly different connotation for X-Y plots. Here, it means that the array is scaled such that it will fit in a coordinate frame with nice scale values. The second letter A or E indicates whether the normalization is over all (A) surfaces or whether each (E) surface is normalized separately, that is, the z_{\max} , z_{\min} are searched for over all arrays or over each array individually. The letters DN mean don't normalize, that is, do not do the above

*There is a circumstance in which the above meaning for p_4 does not apply. See Section 10.4, paragraph (4).

transformation. Note that for PERSPECTIVE displays normalization always occurs. Therefore, DN should never be used. This is done mainly to force the plot to remain within the plot paper boundaries. Again, for X-Y plots the connotation is slightly different, in that in this case the user must provide plot scale values.

The letter S indicates that there will be superimposed on a single coordinate frame many time curves (as chosen by p_1 and p_2) for a given cross-section, rather than having several cross-sections appear on a single frame for one particular time. Since the time variable can have as many as 10 values, then there can be as many as 10 time surfaces, that is, curves, superimposed on one frame. If it is desired to have one coordinate frame for each value of time that has been utilized, then the S should be omitted. This situation definitely pertains to CONTOUR and PERSPECTIVE plots.

When NA or NAS is used, the values assigned to SCALEX, SCALEY on data card #1 and XMIN, YMIN on data card #2 are ignored, so then the computer selects values which are more appropriate for the ranges of ordinate and abscissa involved. When NE or NES is used, the operator must select his own values for these data.

For X-Y plots, it is recommended that either NA or NAS be used. If NE or NES is employed instead, the operator should beware of erroneous coordinate scaling by ensuring that the values for any subsequent maxima and minima do not exceed those of the initial maximum and minimum. If the S is used in these plots, then parameter p_4 has no effect since several surfaces corresponding to several time values at one cross-section are to be plotted, rather than several cross-sections for one time value.

If no command card is included, then the default command of PERSPECTIVE is assumed. Several commands, one per card, may be given for any single run of the program. For example, a perspective display might be followed by a contour display or several perspective displays from several view angles might be called for by a sequence of PERSPECTIVE commands.

Typical detailed commands used for running the DISPLAY program in the Batch mode only are listed in Attachment 6. We do not run this program in the Intercom mode because usually there is not sufficient space allocated on Intercom to allow the program to run to completion.

10.5 Examples of the Use of the Three Different Plotting Commands

In Section 6 of Volume I, we presented many examples of the three different kinds of plots that program DISPLAY was capable of generating, listing in the figure captions the plot commands which controlled the actual plotting of these

curves. We are now in a position to understand and to analyze how these commands control the graphing.

For example, in Figure 3 the command is PLOT (1, 1, Y, 100, 1, NAS). The keyword PLOT indicates that a multiple X-Y plot is involved. The first two parameters (1, 1) mean that every time value available is to be utilized, starting with time value #1 (that is, T1). In this example, there were 9 time curves used (T1 through T9), which are shown on the right hand side of the figure. Whether the curves drawn will represent temperature - or intensity - versus distance depends on whether the permanent file attached previously to the PLOT command was a TAPE8 - or TAPE7 - type file, respectively. For this particular case, it was a TAPE8 file. The third parameter (Y) signifies that the abscissa is the axial distance through the window. The fourth and fifth parameters (100, 1) signify that every 100th T - versus - z surface is to be plotted, starting with the first (that is, starting with the surface existing at zero radial distance, which is through the center of the window). Since there are only 82 T - versus - z surfaces, then setting $p_4 = 100$ can be seen as a ploy for selecting only the first surface ($p_5 = 1$) to the exclusion of all others. In other words, the selection of any value of p_4 greater than 82 would have ensured the same result. The sixth parameter (NAS) indicates that the normalization is to occur over all surfaces and that all of the (9) time curves are to be superimposed on one coordinate frame.

In Figures 4 and 5 the same kind of information was desired except that the T - versus - z profiles were to occur at constant radial distances of 15 and 30 cm, respectively. Since these distances represent ~50 percent and ~100 percent of the radial distance up the window, the parameter p_5 was chosen to be equal to 41 and 81, respectively. (Actually, because of the way the 82 radial positions were chosen, p_5 -values of 1, 41 and 81 represent distances of 0.6 percent, 49.4 percent and 99.4 percent up the radial axis, respectively.)

In Figure 6 we wanted to superimpose plots of T - versus - z at the above 3 radial positions at the fixed time of 5 sec, which is the 8th time value. The p_1, p_2 pair of 4, 8 signifies that every 4th time value is to be plotted, starting with T8. As above, this is a ploy to select only T8 and to exclude the others, since there are only 9 times available. Any $p_1 > 2$ would have produced the same result. The p_4, p_5 pair of 40, 1 means that every 40th surface is to be plotted, starting with surface #1. Thus, surfaces #1, 41 and 81 are plotted. Because we want these 3 surfaces, properly normalized, to be superimposed on one coordinate frame at the one fixed time, we leave off the letter S in the parameter p_6 .

Temperature is plotted against radial distance for the same model problem in Figure 7 (hence, $p_3 = X$). Here, we wanted to plot all 21 T - versus - r surfaces (therefore, $p_4 = p_5 = 1$) at 1 and 5 sec. (The reason for there being only 21 rather

than 22 surfaces is due to the way we chose the points; the 22nd point falls outside of the window.) Thus, we choose p_1 and p_2 to be 3 and 5, respectively, meaning that every 3rd time is selected, starting with T5 (=1 sec). As before, dropping the letter S in parameter p_6 ensures one coordinate frame for each time chosen.

Figures 8 and 9 are examples of T - versus - r temperature plots at approximately 1/4 and 3/4 of the way through the window (hence, $p_5 = 6$ and 16), respectively. Note that setting $p_1 = p_2 = 1$ assures that all times are accounted for and are superimposed because of the S in p_6 . Letting p_4 be greater than 22 (here, 100) assures that only that one particular surface will be plotted.

Figures 10 and 11 pertain to the annular-shaped window. Setting $p_5 = 11$ and 21 results in plots for T - versus - r surfaces through the middle and at the exit face of the window, respectively.

Figures 12-14 show multiple X-Y plots for intensity. In Figure 12 we wanted every time included (hence, $p_1 = p_2 = 1$) of T - versus - axial distance plots (hence, $p_3 = Y$) along the axis ($p_5 = 1$), with no other radial distances included ($p_4 = 100$); and all of the time curves are to be superimposed (hence, S in p_6). In this particular example, we let MP = 100. Thus, any p_4 - value ≥ 100 would have ensured that only those surfaces along the axis would be used.

The axial range is covered by NP points; in our particular example, NP = 61. In Figure 13 we wanted to have superimposed time plots of I - versus - ρ' (hence, $p_3 = X$) at the center of the axial range only (hence, $p_4 = 100$, $p_5 = 31$). At a time of 3 sec (that is, $p_2 = 7$), the Gaussian focal point occurs at a distance of 830 m along the axis (corresponding to $p_5 = 34$). Figure 14 displays the I - versus - ρ' graph for this time only.

The plot command for the PERSPECTIVE graphs of Figures 15 and 16 use the default values. Even though a 3D plot was drawn for all 9 times, only a few representative cases are presented here.

For contour plots we wanted the time values of 2 and 8 sec only. Hence, $p_1 = 3$ and $p_2 = 6$ in Figures 17 and 18. Twenty contour lines are shown (thus, $p_3 = 20$). Since we wanted each one of these contours to be labeled with its dimensioned temperature value, rather than a normalized value, we chose the code symbol DN for p_4 .

In summary, we can say that program DISPLAY is used mainly to provide a "readable" output of functions of two variables. The PERSPECTIVE plot furnishes a very good general "view" of the function in question. CONTOUR also provides a good view as well as quantitative knowledge of the function values. PLOT (either X-cross-sections or Y-cross-sections) supplies the most quantitative output but usually the least satisfactory overall "view" of the function. It should be pointed out that PLOT can be used for functions of one variable.

10.6 Principal Functions and Subroutines

The various operations associated with the DISPLAY program are carried out by the following subprograms, subroutines and functions:

- (1) DISPLAY - the main program which calls the other subroutines and functions into execution.

All of the following are subroutines:

- (2) PLOTT1 - draws and titles coordinate frame. It also does the scaling, if it isn't supplied by the user.
- (3) PARMPLT - prints out parameters at the beginning of each plotting run.
- (4) FILL - selects data from DATAIN and places it in a 2D array which, in turn, is passed to PARMPLT for printing.
- (5) CFRAME - draws and labels the coordinate frame for contour and perspective plots.
- (6) INTERP - converts user commands and command parameters to subroutine control arguments. It also calls subroutine NUMB to decode parameters.
- (7) NUMB - used by INTERP to convert display code numbers in the commands to the proper internal representation of numbers in the computer.
- (8) ARROW - draws the arrow used above the rectangular coordinate frame in perspective plots.
- (9) APLACE - locates arrow-head for perspective view angle.
- (10) RD1 - reads TAPE3 and fills up appropriate arrays to be plotted. Finds maxima and minima of the surfaces to be plotted, if necessary.
- (11) CLEV - returns various equispaced contour levels.
- (12) SKIP - skips over a designated number of records (that is, "surfaces") while reading TAPE3.
- (13) FACE - a system library program which draws the PERSPECTIVE plots. It also uses the library subroutines HIDE, DRAW, SORT and PARFIT.
- (14) CONTOR - a system library program which draws the CONTOUR plots. It also calls the library subroutines NEIBOR and FOUR as well as the Calcomp plot subroutines.
- (15) RJUST - right adjusts all numerical input data. Its Fortran listing is given in Appendix A.9.
- (16) SYMBL - converts a floating point number using a G10.3 format to a display code.

The complete Fortran listings for each of the above programs, subroutines and functions are given in Appendix E.

10.7 Algorithms

10.7.1 MULTIPLE X-Y DISPLAYS

The PLOT display graphs either $f(\cdot, y_i)(p_3 = X)$ or $f(x_i, \cdot)(p_3 = Y)$ for selected values of y_i or x_i determined by command parameters p_4 and p_5 . Specifically:

$$i = p_5 + (k - 1) \cdot p_4 \quad (k = 1, \dots) \quad .$$

Subroutine PLOTT1 is called after each "surface" array has been filled by subroutine RD1. One of two types of coordinate frames are then drawn by PLOTT1 depending on command parameter p_6 . If $p_6 = NA$ or NE , the scaling is done by the Calcomp subroutine SCALE and the coordinate axes are drawn by Calcomp subroutine AXIS. If $p_6 = DN$, then the user-provided scale is used and the coordinate frame is drawn by a set of statements within PLOTT1.

After the coordinate frame has been drawn, the individual surface "cross-sections" represented by $f(\cdot, y_i)$ or $f(x_i, \cdot)$ are plotted as continuous curves. Each curve is labeled with a symbol and symbol table.

10.7.2 PERSPECTIVE DISPLAY

For perspective displays the surface is always normalized in such a way that the display will approximately fill the same plot area regardless of the size of the surface array. The view elevation angle is fixed at approximately 45 degrees while the view azimuthal angle can be any value (given by the parameter p_3 of the PERSPECTIVE command). To produce a better display, the surface is always bordered by zeroes.

The complete perspective display is produced by calls from the main program to four subroutines (which may, in turn, call other subroutines): APLACE, FACE, CFRAME, and ARROW.

After establishing some display constants, a call is made to APLACE which returns the point at which to place the head of the view direction arrow. Next, a surface of constant height is produced and a call made to FACE with a "switch" positioned such that FACE merely returns values of XMIN, YMIN, DX, DY which will be used on subsequent calls to FACE. The surface is next normalized and a "display frame" is plotted. Because of the difficulty of drawing a coordinate frame for a perspective display, a coordinate frame quite similar to that used for the contour display is drawn adjacent to each perspective display. The only difference is that an angle of view arrow is drawn on the frame. This frame, then, is

produced by calls to CFRAME (see Section 10.7.3 on contour display) followed by a call to ARROW which plots an arrow at the point found by APLACE. Finally, FACE is called to produce the perspective display.

10.7.3 CONTOUR DISPLAY

The contour display is produced by calls to three subroutines: CLEV, CFRAME, and CONTOR. Subroutine CLEV returns p_3 contour levels in array ZLEVS, evenly spaced between the surface maximum and minimum (but exclusive of the surface minimum). The surface may or may not be normalized according to parameter p_4 .

After CLEV has been called, the contour "frame" is drawn by a call to subroutine CFRAME. An example of the frame produced by CFRAME is shown below (small letters indicate numerical or character-string values which are inserted):

```
surface title
ALL FUNCTION VALUES HAVE
BEEN SCALED ACCORDING TO -
```

$$z \Rightarrow \frac{c \cdot (Z - ZMIN)}{(ZMAX - ZMIN)}$$

```
WHERE  ZMAX = zmax
        ZMIN = zmin
ARE THE MAX. AND MIN.
VALUES OVER ALL SURFACES
or (VALUES OF THE SURFACE)
parameter = value
```

The contour map is then drawn by a call to CONTOR. Each contour level line is identified by a unique (mod 13) symbol which is printed next to the contour map along with the contour level value which the symbol represents.

10.8 Batch and Intercom Modes

Attachment 6 gives a typical set of commands for running the DISPLAY program under the Batch mode only. The Intercom mode does not have sufficient capacity to handle most plotting jobs, since approximately 142,000 octal words are required in the central memory to run the program (including the plot software). The program will run under Intercom if the arrays in unlabeled common are changed from (102, 102) to (22, 22).

Running time of the program is determined by the size of the array to be displayed, the number of commands and the command parameters. As an example,

a 100 by 100 array was displayed with CONTOUR (20 levels), PLOT (10 cross-sections) and PERSPECTIVE in a total CP time of 82.8 sec.

10.9 Other Features

Various quantities which might be useful for debugging purposes are outputted on file TAPE6. These quantities are:

- 1) XMAX, YMAX, PPI, TICU
- 2) XLEN, YLEN, SCALEX, SCALEY
- 3) XMIN, YMIN
- 4) INDEX (8 integers)
- 5) NDA (if not 0)
- 6) IND (four lines of integers representing the locations in DATAIN of data to be plotted).
- 7) 4) and 5) repeated for each DATAIN.
- 8) Command parameters. (Note that the command itself can be inferred from the form of the parameters.)
- 9) NP, MP
- 10) ZMAX, ZMIN, TIM, ZMIN
- 11) XMAX, YMIN, YMAX, FLAG1 (Note: FLAG1 is a logical variable which is "FALSE" if an end-of-file has been reached on file TAPE3.)
- 12) 9) and 10) possibly repeated.
- 13) XMINF, YMINF, DX, DY (Only for perspective display; these are scale parameters.)

In addition to the output which comes directly from program DISPLAY, the subroutine CONTOR (used in contour display) and FACE (used in perspective display) output various quantities (see subroutine listings).

10.10 Program Files

In addition to OUTPUT, which is used only by the operating system to output messages, DISPLAY uses files TAPE4, TAPE6 and TAPE3.

TAPE3: TAPE3 is the main input file containing the surfaces to be displayed as well as the information records containing titles, etc. All records are unformatted. The file structure is as follows:

record 1:	datain-1 (100, 3)	
record 2:	datain-2 (100, 3)	
·	·	These records may be absent (nda=0)
·	·	
·	·	
record nda:	datain-nda (100, 3)	
·	·	
·	·	
·	·	
record nda+1	row 1 of surface 1	
·	·	
·	·	
·	·	
record nda+np	row np of surface 1	
	row 1 of surface 2	
·	·	
·	·	
·	·	
·	row np of surface 2	
·	·	
	·	
	·	
last record	row np of surface N	

Each "row" of the surface has a record of the form given in the first paragraph of Section 10. 2.

TAPE4: TAPE4 is the "card" input file. It uses formatted data as described in the first paragraph of Section 10. 3.

TAPE6: TAPE6 is the formatted output file for messages and debug quantities. See Section 10. 8 for a partial listing of TAPE6 records.

11. OTHER CAPABILITIES

The computer programs described in this report either have been extended, or are capable of being extended, to various other aspects of the window problem. For example, a program has been written and successfully implemented in fitting the theoretical temperature distribution produced by program TEMP5 to various experimentally measured temperature distributions. More specifically, the temperature at one or more points on the window's surfaces are measured as a function

of time, as a source is turned on, then off. The theoretical temperature rise and fall is made to approximate the experimental values by a judicious choice of various parameters (such as absorption coefficient, β , and the theoretical boundary conditions, as given by the h_i and g_i) which describe the thermal properties of the window material. The details of this procedure are contained in Technical Memorandum No. 16 by T.B. Barrett, Parke Mathematical Labs. (Oct. 1973).

Another phenomenon which could definitely affect the diffraction pattern in the far field would be multiple internal reflections of the laser beam within the window.¹⁵ Analysis shows that this condition can be handled effectively if each exponential term in Eqs. (25), (26) and (27) is replaced according to the prescription:

$$\exp(ik\Phi^\gamma) \rightarrow t_1 t_2 \exp\{ik\Phi^\gamma\} / [1 - r_1 r_2 \exp\{2ik(\Phi^\gamma + \Phi')\}] \quad (87)$$

in which Φ^γ is still determined by Eq. (18) and the extra phase factor Φ' is given by:

$$\Phi'(\rho) = nL + \Delta L_b(\rho) \quad , \quad (88)$$

where ΔL_b is the amount by which the window bulges when heated by the beam. The t 's and r 's are amplitude transmission and reflection coefficients, respectively. The subscript 1 refers to the window's entrance face, and 2 to its exit face. They are given by Weil:⁸

$$\begin{aligned} t_1 &= 2/(n+1) \\ t_2 &= 2n/(n+1) \\ r_1 &= r_2 = -(n-1)/(n+1) \end{aligned} \quad (89)$$

Another capability inherent in the program is allowing an axial (that is, z) dependency in the volume heating source term Q . There are two alternate ways in which this could be effected:

(1) Replace subroutine GAUSS (refer to Appendix A.5) by another, which is also to be called GAUSS. This new subroutine is to have the same arguments as before (see card #7120 in Appendix A.5). However, now the Q -array will contain

15. Bendow, B., Gianino, P.D., Hordvik, A., and Skolnik, L.H. (1973) Optics Commun. 7:219; and Skolnik, L.H., Bendow, B., Gianino, P.D., and Cross, E.F. (1974) AFCRL-TR-74-0085 (III), p. 967.

the appropriate z-dependence. The variable names in the argument are defined in the glossary in Table 3.

(2) If the Batch mode is to be employed, an alternate procedure would be to insert the following data cards in the GETDATA stack. Referring to Attachment 1B, use

IQ 2

ICARD 4

on line 34, and, after the blank card on line 35 insert the desired Q-array using format 7F10.3. At present, Q is dimensioned (82, 22).

Other possible extensions of the computer program include:

- (1) Temperature dependence of some of the material parameters, such as refractive index n , thermal conductivity K and thermal lensing parameters S_1^γ .
- (2) Multiple layers, or coatings, on the window to eliminate reflections and/or to compensate the thermal lensing.¹⁶
- (3) Time dependence in the volume source term Q .

Trying to account for an angular (that is, θ) asymmetry in the beam's cross-section would not be a feasible extension, for it would necessitate a complete rewriting of the program, expanding it from a 2-dimensional to a 3-dimensional treatment.

16. Bendow, B., and Gianino, P.D. (1975) *Appl. Optics* 14:277; and Bendow, B., Gianino, P.D., Flannery, M., and Marburger, J. (1975) *Proc. of the Fourth Annual Conf. on Infrared Laser Window Materials*, C.R. Andrews and C.L. Strecker (Editors), Advanced Research Project Agcy., Arlington, Virginia, p. 299.

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Attachment 1

Commands to Run TEMP5 and TIKIRK

Here, the goal is to initiate and run a specified TEMP5 and a TIKIRK calculation, then print out and catalog the results on permanent file (PF). Before beginning this job, one should have previously stored in the computer the following two PF's: TEBX (the PFN for the TEMP5 program), and, TIBX (the PFN for the TIKIRK program described in Sections 6.1 - 6.6). A third ancillary program, T3D, whose use is optional, is available to be added to the previous two. Given the PFN of T3BX, it prints out functions F1 and F2 (see Eqs. (16) and (17), Volume I). The Fortran listing for program T3D is given in Appendix F. Incidentally, the third letter (B) in each of the above PFN's means that the PF is in binary form.

A. Intercom Commands

The following is a typical set of Intercom commands:

<u>Line No.</u>	<u>Computer types out. .</u>	<u>Operator Response</u>	<u>Comments</u>
1	COMMAND-	ETL(450)	Extends time length to 450 octal sec.
2	COMMAND-	CONNECT(TAPE4,TAPE5)	

Line No.	Computer types out..	Operator Response	Comments
Start of TEMP5 calculation.....		
3	COMMAND-	ATTACH(TEB, TEBX, ID=GIANINO)	TEB is LFN for TEBX.
4	COMMAND-	TEB	
5	READ DATA FILE-3?	N	N=no (because you want to create a new TAPE3)
6	DEFAULTS LISTED?	N	Customary answer.
7	NAME-VALUE MODE?	Y	Y=yes.
8	NAME VALUE....	BETA .003 17 1 etc. - - - - - - -	(i) Enter the new TEMP5 variables here. See Table 2 Volume II. (ii) The name of the variable starts under N in NAME; its numerical value under V in VALUE.
9	DATA INPUT COMPLETE WORK OF DATINIT COMPLETE... WORK OF CYLTMP COMPLETE... END OF RUN EXIT ----CP SECS EXECUTION...TEMP5 Calculation has been completed.....		
10	COMMAND	CONNECT(OUTPUT)	Lines 10-13 cause F1 and F2 to be printed out at remote terminal facility (AU). They may be omitted, if desired.
11	COMMAND-	ATTACH(T3B, T3BX, ID=GIANINO)	T3B is LFN for T3BX.
12	COMMAND-	T3B,,A	A is merely a surrogate name.
	END T3D ..CP SECS EXECUTION..		
13	COMMAND-	ROUTE,A,ST=RMT, FID=GIAAU,DC=PR.	
14	COMMAND-	REQUEST(PAT,*PF)	Lines 14-17 create a new TAPE3-type PF. We arbitrarily give it the PFN of T3NX. PAT is merely a LFN.

Line No.	Computer types out. .	Operator Response	Comments
15	COMMAND-	REWIND(TAPE3)	
16	COMMAND-	COPY(TAPE3, PAT)	
17	COMMAND-	CATALOG(PAT, T3NX, ID=GIANINO, RP=999)	
18	COMMAND-	ROUTE, TAPE6, ST=RMT, FID=GIAAU, DC=PR.	Causes the information on TAPE6, containing the TEMP5 results, to be printed out at remote terminal facility (AU). Also clears TAPE6.
(ASIDE: If all that is desired is the temperature distribution in the window, this would be a convenient place to stop).			
..... Start of TIKIRK calculation.			
19	COMMAND-	ATTACH(TIB, TIBX, ID=GIANINO)	TIB is LFN for TIBX.
20	COMMAND-	TIB	
21	READ DATA FILE-3?	Y	Because you want to use information from the "new" TAPE3, viz. T3NX.
22	DEFAULTS LISTED?	N	
23	NAME-VALUE MODE?	Y	
24	NAME VALUE...	(space, return)	Do not enter any value here; just hit the "space" and "return" keys.
DATA INPUT COMPLETE			
25	READ DATA FILE-7?	N	Answer here is always "no".
26	DEFAULTS LISTED?	N	
27	NAME-VALUE MODE?	Y	
28	NAME VALUE...	X1 800 NP 26 - - - - - -	(i) Enter the new TIKIRK variables here. See Table 4, Volume II. (ii) See Comment (ii) on Line 8.
29	DATA INPUT COMPLETE		TIKIRK calculation has been completed.

<u>Line No.</u>	<u>Computer types out. .</u>	<u>Operator Response</u>	<u>Comments</u>
	NEW VALUE OF TAU IS...		Prints out the 10 values of TAU corresponding to time values T1 through T10. See Eq. (13), Volume I.
	-		
	-		
	-		
30	COMMAND-	ROUTE, TAPE6, ST=RMT, FID=GIAAU, DC=PR.	Routes the TAPE6 information, containing the TIKIRK results, to remote terminal (AU) for printout.
31	COMMAND-	REQUEST(PIT, *PF)	Lines 31-34 create a new TAPE7-type PF. We arbitrarily give it the PFN of TKX. PIT is merely a LFN. This new PF can be used as the input in the DISPLAY program for plotting the intensity.
32	COMMAND-	REWIND(TAPE7)	
33	COMMAND-	COPY(TAPE7, PIT)	
34	COMMAND-	CATALOG(PIT, TKX, ID=GIANINO, RP=999)	

B. Batch Commands

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
1	Job ID with T=2000, core memory=170K	
2	ATTACH(TEB, TEBX, ID=GIANINO)	
3	REQUEST(TAPE3, *PF)	Assigns TAPE3 to permanent file.
4	TEB(INPUT, OUTPUT)	Loads and executes TEBX.
5	REWIND(TAPE6)	
6	COPY(TAPE6, OUTPUT)	Prints output.
7	CATALOG(TAPE3, T3NX, ID=GIANINO, RP=999)	
8	ATTACH(TIB, TIBX, ID=GIANINO)	
9	REQUEST(TAPE7, *PF)	
10	REWIND(TAPE6)	
11	TIB(INPUT)	
12	REWIND(TAPE6)	
13	COPY(TAPE6, OUTPUT)	

Card No.	Command	Comments
14	CATALOG(TAPE7, TKX, ID=GIANINO, RP=999)	
15	EXIT, S.	All commands after EXIT, S. are executed if and only if TEB terminates abnormally, e. g., exceeds time limit.
16	REWIND(TAPE6)	
17	COPY(TAPE6, OUTPUT)	
18	CATALOG(TAPE3, T3NX, ID=GIANINO, RP=999)	
19	CATALOG(TAPE7, TKX, ID=GIANINO, RP=999)	
20	7/8/9	EOR Card.
21	N	
22	N	
23	Y	
24A	BETA .003	Name starts in col. 1;
B	17 1	numerical value starts in
-	- -	col. 11.
-	- -	
-	- -	
25	-----	Blank card.
26	7/8/9	EOR card.
27	Y	
28	N	
29	Y	
30	-----	Blank card.
31	N	
32	N	
33	Y	
34A	X1 800	Name starts in col. 1;
B	NP 26	numerical value starts in
-	- -	col. 11.
-	- -	
-	- -	
35	-----	Blank card.
36	6/7/8/9	EOF card.

If only temperature distribution in the window is desired, the above series of commands would be reduced to the following:

<u>Card No.</u>	<u>Command</u>
C1	Job ID with T=60, corememory=60K
C2	ATTACH(TEB, TEBX, ID=GIANINO)
C3	REQUEST(TAPE3, *PF)
C4	TEB(INPUT, OUTPUT)
C5	REWIND(TAPE6)
C6	COPY(TAPE6, OUTPUT)
C7	CATALOG(TAPE3, T3NX, ID=GIANINO, RP=999)
C8	EXIT, S.
C9	REWIND(TAPE6)
C10	COPY(TAPE6, OUTPUT)
C11	CATALOG(TAPE3, T3NX, ID=GIANINO, RP=999)
C12	7/8/9
C13	N
C14	N
C15	Y
C16A	BETA .003
B	I7 1
-	-
-	-
-	-
C17	(blank card)
C18	6/7/8/9

Attachment 2

Commands to Modify a Temperature Distribution

Assume that a TEMP5 calculation has already been performed and the results cataloged under the PFN of T3NX (cf. lines 14-17 in Attach. 1A). Further, assume that one wants to change only a few of the input variables and then calculate a new temperature distribution. The following commands indicate how the previous results may be utilized.

A. Intercom Commands

<u>Line No.</u>	<u>Computer types out. .</u>	<u>Operator Response</u>	<u>Comments</u>
1	COMMAND-	ETL(450)	
2	COMMAND-	CONNECT(TAPE4, TAPE5)	
3	COMMAND-	REWIND(TAPE6)	Clears TAPE6.
4	COMMAND-	REWIND(TAPE7)	Clears TAPE7.
5	COMMAND-	ATTACH(PET, T3NX, ID=GIANINO)	Attaches former TAPE3 with LFN of PET.
6	COMMAND-	COPY(PET, TAPE3)	Copies "former" TAPE3 onto a "new" TAPE3, which is given the LFN of TAPE3. Thus, the original file (T3NX) is still intact and available for future use.

Line No.	Computer types out..	Operator Response	Comments
7	COMMAND-	ATTACH(TEB, TEBX, ID=GIANINO)	
8	COMMAND-	TEB	
9	READ DATA FILE-3?- N		
10	DEFAULTS LISTED?- N		
11	NAME-VALUE MODE?- Y		
12	NAME VALUE.....	SIG .4 PWR 1E7 - - - -	Enter those TEMP5 variables which are to be changed. Also, see Comment (ii) on Line 8, Attach. 1A.
13	Same as line 9, et seq., Attach. 1A. However, when one gets to the et equivalent of line 17, Attach. 1A, one should give the new PF a new PFN, seq. say, T3QX.		

B. Batch Commands

Card No.	Command	Comments
1	Job ID with T=1000, CM=60K	
2	ATTACH(PET, T3NX, ID=GIANINO)	Attaches old TAPE3.
3	REQUEST(TAPE, *PF)	If new TAPE3 is to be permanent.
4	COPY(PET, TAPE3)	
5	RETURN(PET)	Return if you want to use at a later date. Otherwise, could purge it.
6	ATTACH(TEB, TEBX, ID=GIANINO)	
7	TEB(INPUT, OUTPUT)	
8	CATALOG(TAPE3, T3QX, ID=GIANINO, RP=999)	The new TAPE3 is given the PFN of T3QX.
9	REWIND(TAPE6)	
10	COPY(TAPE6)	
11	7/8/9	EOR card.
12	Y	
13	N	

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
14	Y	
15A	SIG .4	Enter those TEMP5 variables which are to be changed. Also, see comment on line 34, Attach. 1B.
B	PWR 1E7	
	- -	
	- -	
16	(blank card)	
17	6/7/8/9	EOF card.

Attachment 3

Commands to Recalculate TIKIRK, Given TEMP5 Results

There are certain input variables which will affect the computed spatial intensity pattern (and possibly even the dimensioned temperature distribution in the window), but not the normalized temperature distribution. The input parameters which belong to this category are most of the variables found in Table 4 and those in Table 2 which are accompanied by the code letter K in the Useage Code column (Col. #6).

As in Attach. 2, we assume that a previous TEMP5 calculation is available under the PFN of T3NX. Now, we desire to observe the effects which changes in the above-mentioned variables have on the computed intensity pattern. For each set of changes made, the TIKIRK program must be executed. The following gives a representative series of typical commands necessary to implement this procedure.

A. Intercom Commands

<u>Line No.</u>	<u>Computer types out...</u>	<u>Operator Response</u>	<u>Comments</u>
1-4	Same as in Attach. 2A.		
5	COMMAND-	ATTACH(TAPE3, T3NX, ID=GIANINO)	Attaches PF with LFN of TAPE3.

<u>Line No.</u>	<u>Computer types out...</u>	<u>Operator Response</u>	<u>Comments</u>
6-21	Repeat lines 19 through 34, inclusive, from Attach. 1A. However, on line 24 enter the desired TEMP5 variables, if any, which you want to change and which do not affect the normalized temperature distribution in the window. (Note that TEMP5 parameters are being entered at this stage, even though the TIKIRK program currently has control.)		
	On line 28 enter only those TIKIRK variables whose magnitudes are to be different from the default values.		
	On line 34 select a different PFN for the new TAPE7-type PF just completed.		
End of TIKIRK calculation.....		

If you want to change the variables again and repeat the TIKIRK calculation:

22	COMMAND-	TIB
23	Repeat lines 21 through 34, inclusive, from Attach. 1A, subject to the same comments as noted in line 6 above.	

Each time the variables are to be changed and the TIKIRK calculation is to be recomputed, repeat lines 22 and 23 above.

B. Batch Commands

If run as a separate problem, assume that the TEMP5 PF having PFN of T3NX has already been created.

<u>Card No.</u>	<u>Command</u>
1	Job ID with T=2000, CM=170K
2	ATTACH(TIB, TIBX, ID=GIANINO)
3	ATTACH(TAPE3, T3NX, ID=GIANINO)
4	REQUEST(TAPE7, *PF)
5	TIB(INPUT)
6	REWIND(TAPE6)
7	COPY(TAPE6, OUTPUT)
8	CATALOG(TAPE7, TKX, ID=GIANINO)

Plus cards #26-#36, inclusive, of Attach. 1B.

Attachment 4

Commands to Produce a TAPE8 for Temperature Plots

The temperature distribution information contained on the file called TAPE3 is not in the proper format for plotting purposes. Rather, this information must be transferred in the appropriate format to another file, called TAPE8, which is suitable for plotting by the DISPLAY program. This attachment gives all of the commands required to generate and catalog a TAPE8 file, provided that the temperature results are already on a TAPE3-type PF. We assume that this latter file has already been created and given the PFN of T3NX.

A. Intercom Commands

<u>Line No.</u>	<u>Computer types out...</u>	<u>Operator Response</u>	<u>Comments</u>
1	COMMAND-	ETL(450)	
2	COMMAND-	CONNECT(TAPE4, TAPE5)	
3	COMMAND-	REWIND(TAPE6)	
4	COMMAND-	REWIND(TAPE7)	
5	COMMAND-	ATTACH(TAPE3, T3NX, ID=GIANINO)	
6	COMMAND-	ATTACH(TIB, TIBX, ID=GIANINO)	

<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
7	COMMAND-	TIB	
8	READ DATA FILE=3?-	Y	
9	DEFAULTS LISTED?-	N	
10	NAME-VALUE MODE?-	Y	
11	NAME VALUE....	(space, return)	
12	READ DATA FILE-7?-	N	
13	DEFAULTS LISTED?-	N	
14	NAME-VALUE MODE?-	Y	
15	NAME VALUE.....	NP 1 MP 1 IPRNT 2 T1 time value - #1 (in sec) - - - T10 time value #10(in sec)	(i) Only the data shown here can be entered. (ii) See Comment (ii) on line 8, Attach. 1A. (iii) Only those temperatures will be plotted which correspond to the (dimensioned) times given by T1, T2, etc. Linear interpolation is done, if necessary.
16	COMMAND-	REQUEST(DOG, *PF)	Lines 16-19 create a new TAPE8-type PF whose PFN is TEMPX and whose LFN is DOG.
17	COMMAND-	REWIND(TAPE8)	
18	COMMAND-	COPY(TAPE8, DOG)	
19	COMMAND-	CATALOG(DOG, TEMPX, ID=GIANINO, RP=999)	

ASIDE: If you want to calculate the diffraction pattern concomitant with the temperature distribution contained in the permanent file T3NX as mentioned above, refer to Attach. 3A., starting with line #22.

B. Batch Commands

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
1	Job card, T=20, CM=60K	
2	ATTACH(TAPE3, T3NX, ID=GIANINO)	
3	REQUEST(TAPE8, *PF)	
4	ATTACH(TIB, TIBX, ID=GIANINO)	

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
5	TIB(INPUT)	
6	CATALOG(TAPE8, TEMPX, ID=GIANINO	
7	7/8/9	EOR card.
8	Y	
9	N	
10	Y	
11	----	Blank card.
12	N	
13	N	
14	Y	
15	NP 1	For cards #15-27, see comments, line 15, Attach. 4A.
16	MP 1	
17	IPRNT 2	
18	T1 time value #1	On cards #18-27, all time values are in seconds.
-	-	
-	-	
-	-	
-	-	
27	T10 time value #10	
28	-----	Blank card.
29	6/7/8/9	EOF card.

Attachment 5

Commands for Running Alternate TIKIRK Program

Assume that the alternate TIKIRK program, introduced in Section 9.7, Volume II, has been stored in the computer and is available for use, rather than the original TIKIRK program (as discussed in Sections 9.1-9.6). This alternate program is also given the PFN of TIBX. Let us further assume that we want to utilize option #3, which has the PFN of IK1B. The revised commands to run this alternate program are:

A. Intercom Commands

<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
1-19	Same as Attach. 1A.		
20	COMMAND-	ATTACH(IKB, IK1B, ID=GIANINO)	IKB is the LFN for this file.
21	COMMAND-	XEQ	Indicates the following commands are loader commands.
22	OPTION =	LOAD=TIB, IKB	Causes loading of the main program TIKIRK and subroutine IKIRK.



<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
23	OPTION =	EXECUTE=TIKIRK	Initiates execution.
24-37	Same as lines 21-34, inclusive, Attach. 1A.		

The above commands would be the same for the other two options (#1 and 2), except that on line 20 the appropriate PFN would be entered in place of IK1B. However, the LFN of IKB must be maintained.

B. Batch Commands.

<u>Card No.</u>	<u>Command</u>
1	Job card, T=2000, CM=170K
2	ATTACH(TIB, TIBX, ID=GIANINO)
3	ATTACH(TAPE3, T3NX, ID=GIANINO)
4	ATTACH(IKB, IK1B, ID=GIANINO)
5	REQUEST(TAPE7, *PF)
6	LOAD(TIB, IKB)
7	EXECUTE(TIKIRK)
8	REWIND(TAPE6)
9	COPY(TAPE6)
10	CATALOG(TAPE7, TKX, ID=GIANINO, RP=999)
11	7/8/9
12	Y
13	N
14	Y
15	(blank card)
16	N
17	N
18	Y

<u>Card No.</u>	<u>Command</u>	
19A	X1	800
B	NP	26
-	-	-
-	-	-
20	(blank card)	
21	6/7/8/9	

Attachment 6

Batch Commands for Running DISPLAY Program

(1) Intensity Plots

Let us assume that a TAPE7-type file, having the PFN of T7X and containing the intensity information to be plotted, has already been created.

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
1	Job ID, T=300, CM=170000	
2	ATTACH(DISB, DISBX, ID=GIANINO)	Attaches the DISPLAY program, whose PFN is DISBX and whose LFN is DISB.
3	ATTACH(TAPE3, T7X, ID=GIANINO)	Attaches the permanent file T7X, using the LFN of TAPE3.
4	ATTACH(PEN, ONLINEPEN)	Cards #4-13 control the plotting process.
5	LIBRARY(PEN)	
6	LDSET(PRESET=ZERO)	
7	DISB(INPUT)	

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
8	REWIND(TAPE6)	
9	COPY(TAPE6)	
10	DISPOSE, PLOT, *OL.	
11	EXIT.	
12	REWIND(TAPE6)	
13	COPY(TAPE6)	
14	7/8/9	
15	Data card #1	See Section 10.3 for details on data cards.
16	Data card #2	
17	Data card #3	Use the values pertaining to TAPE7.
18A B	Data card #4A Data card #4B	Cards 18A and 18B contain the sequence nos. of those TEMP5 and TIKIRK parameters, respectively, which are to be listed with the plots.
19	Plot command cards (one or more)	See Section 10.4 for details on plot command cards.
20	6/7/8/9	

(2) Temperature Plots

Suppose that a TAPE8-type file has already been created, having the PFN of TEMPX and containing the temperature distribution within the window. Then, the commands to obtain temperature plots are the same as in Part (1), above, with the following exceptions:

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
3	ATTACH(TAPE3, TEMPX, ID=GIANINO)	Again, the PF is given the LFN of TAPE 3.
17	Data card #3	Use the values pertaining to TAPE8.
18B	(Remove data card #4B)	

If it is desired to have any of the above plots drawn with red ink, card #10 above would be replaced by the following:

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
10	DISPOSE, PLOT, *PL. RED INK PLEASE	The word RED starts in col. 21.

Appendix A

Fortran Listings for TEMP5 Program

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A.1 Main Program TEMPS

1	C	PROGRAM TEMPS(TAPE4=12H,TAPE5=12H,TAPE3=TAPE6=12H,OUTPUT=12H)	000100
	C		000110
	C	TEMPS IS THE PROGRAM NAME ASSIGNED TO A PROGRAM BEING ADAPTED	000120
	C	FROM PROGRAM TEMPA FOR THE PURPOSE OF REDUCTION OF EXPERIMENTAL	000130
5	C	DATA (H VS T) TO DETERMINE H AND HETA. JUNE 1972 BY N.G.PARKE.	000140
	C	THE MEANING OF THE SYMBOLS AND PARAMETERS FOR THIS PROGRAM	000150
	C	ARE DESCRIBED IN THE COMMENT CARDS WITH SUBROUTINE DTAF WHICH IS	000160
	C	CALLED BY THIS PROGRAM AFTER IT HAS READ IN THE INITIAL	000170
	C	PARAMETERS AND DATA. A PARAMETER AND DATA DECK IS PUNCHED	000180
10	C	OUT BY DTAF. DTAF ALSO PRINTS OUT ANY DEBUG DATA INDICATED	000190
	C	BY PARAMETERS I1 - I7.	000200
	C		000210
	C	SUBROUTINE DTAF IS A MODIFICATION OF SUBROUTINE TMPBH	000220
	C	FOR AFCEP BY N.G.PARKE IN JUNE 1972	000230
15	C		000240
	C	THIS SUBROUTINE WAS ORIGINALLY MODIFIED ON 4 APRIL 1972 TO SHIFT	000250
	C	THE DATA TO EVEN INCREMENTS, USING SPLINE INTERPOLATION AND	000260
	C	THE CHOSEN ARBITRARY BOUNDARY CONDITIONS. THIS MODIFICATION	000270
	C	WAS MADE BY N.G.PARKE.	000280
20	C		000290
	C	THE PARENT PROGRAM WAS TEMPA FOR CALCULATING THE UNSTEADY HEAT	000300
	C	CONDUCTION IN A FINITE CYLINDER SUBJECT TO GENERAL BOUNDARY	000310
	C	CONDITIONS ON ALL ZEN AND RHO SURFACES. IT THEN COMPUTES THE	000320
	C	INTEGRALS F1 AND F2, DEMAND BY DR. RENDOW AND PUNCHES THE	000330
25	C	INPUT PARAMETERS AND F1 AND F2. IF I1 = 1.	000340
	C		000350
	C	THE CYLINDER IS HEATED BY A VOLUME SOURCE DISTRIBUTION.	000360
	C	CYLINDRICAL SYMMETRY IS ASSUMED. I.E., THE PARABOLIC	000370
	C	PARTIAL DIFFERENTIAL EQUATION IS IN CYLINDRICAL COORDINATES	000380
30	C	WITH THE ANGLE VARIABLE MISSING.	000390
	C		000400
	C	THE NET OF SPACE POINTS IS SHIFTED HALF AN INCREMENT FROM	000410
	C	BOUNDARIES WHICH ARE RECTANGULAR IN CYLINDRICAL COORDINATES.	000420
	C	THIS NET IS BOUNDED BY A FICTITIOUS SET OF POINTS THAT	000430
35	C	ALLOW THE EASY WRITING OF GENERAL BOUNDARY CONDITIONS.	000440
	C	TEMPA IS A PROGRAM WHICH IS BASED ON	000450
	C	THE IMPLICIT ALTERNATING DIFFERENCE METHOD OF INTEGRATING	000460
	C	A PARABOLIC PARTIAL DIFFERENTIAL EQUATION. IT IS CALLED	000470
	C	THE I.A.D. METHOD FOR SHORT.	000480
40	C		000490
	C	IN ADDITION TO THE USUAL LIBRARY OF MATHEMATICAL	000500
	C	AND SYSTEM SUBROUTINES, TEMPA REQUIRES THE SUBROUTINES TOLAG	000510
	C	AND GAUSS, AS WELL AS THE SSP ROUTINE OSF FOR INTEGRATING.	000520
	C		000530
45	C		000540
	C	THE THEORETICAL BASIS FOR THIS PROGRAM IS FULLY DOCUMENTED	000550
	C	IN TM NO. 5, NATHAN ARTER PARKE III, PARKE MATHEMATICAL LABS.	000560
	C	INC., ONE RIVER ROAD, CARLISLE, MASS. 01741, NOVEMBER 1971.	000570
	C	MODIFICATIONS FOR VERSION TEMPA WILL APPEAR IN TM NO. 7.	000580
50	C		000590
	C	INPUT AND INITIALIZATION CONTROL CHARACTERS	000600
	C	I1 = 0, TEMP DISTRIB U INITIALIZED TO U0	000610
	C	I1 = 1, TEMP INITIAL DISTRIBUTION READ IN ON ICARD	000620
	C	I0 = 0, SOURCE DISTRIB U INITIALIZED TO ZERO	000630
55	C	I0 = 1, CALCULATE AND INITIALIZE Q AS A TRUNCATED GAUSSIAN	000640
	C	DISTRIBUTION.	000650
	C	I0 = 2, SOURCE DISTRIBUTION READ IN ON ICARD.	000660
	C		000670
	C	USE OF THE BOUNDARY CONDITION PARAMETERS G AND H	000680
60	C		000690
	C	A PERFECT INSULATING BOUNDARY IS CHARACTERIZED BY G = 0, H = 0	000700
	C	NEWTONS LAW OF COOLING IS CHARACTERIZED BY G = 0, H = FILM COEFF	000710
	C	GIVEN HEAT INPUT IS CHARACTERIZED BY G = INPUT, H = 0	000720
	C	GIVEN TEMPERATURE IS CHARACTERIZED BY G/H = TEMP AND	000730
65	C	BOTH G AND H VERY LARGE, E.G., G = TEMP * E25, H = 1.E25.	000740
	C		000750
	C		000760
	C		000770
	C		000780
70	C	HF(X,Y) AND GF(X,Y,Z) ARE STATEMENT FUNCTIONS OF THE FORM	000790
	C	USED IN EQUATIONS (19).....(24) IN TM NO. 5 TO APPLY THE	000800
	C	THE GENERAL BOUNDARY CONDITIONS RE CALCULATING THE FICTITIOUS	000810
	C	POINTS IN THE U AND VSTAR ARRAYS.....	000820
	C		



75	C	C..... ASSIGN LOGICAL NUMBERS TO ICARD, IKEY, IPRINT AND ITYPE USING	000830
	C	INPUT DEVICE 1. ON CHANGE THE FIRST READ CARD TO REQUIRED DEVICE NO	000840
	C	THIS MAKES THE PROGRAM EASILY TRANSFERABLE TO COMPUTERS WITH	000850
	C	DIFFERENT LOGICAL DEVICE NUMBER ASSIGNMENTS.	000860
	C		000870
80	C	PARAMETERS 11.....17 FOR CONTROLLING THE PRESENCE AND ABSENCE OF	000880
	C	OUTPUT 1. =. OUTPUT 2. =. INHIBIT.	000890
	C	11 =. PUNCH AND POINT FILE; AND PARAM	000900
	C	12 =. POINT TAIL; MOD; MIN; MAX; ICNT; ICNTR	000910
	C	13 =. POINT KK; A; B; C; D; UPRIM; ALSO INITIAL VALUES OF U; USTAR ETC	000920
	C	14 =. POINT U AND A AFTER INITIAL DATA READ IN OR COMPUTED	000930
85	C	15 =. POINT I; IFFIN(I; J; K).	000940
	C	16 =. PUNCH UFIN AND PARAMETERS.	000950
	C	17 =. POINT I; IFFIN(I; J) ON HALF INCREMENT SHIFTED LATTICE.	000960
	C	THE HALF INCREMENT SHIFTED LATTICE IS THE ONE USED BY US TO	000970
	C	WRITE THE PROGRAM EASILY FOR GENERAL BOUNDARY CONDITIONS.	000980
90	C		000990
	C	SUBROUTINE SPLINE(M, EPS, X, Y, I, SS, SS1, SS2, QUA)	001000
	C	THIS IS A MODIFICATION OF SSP SUBROUTINE SPLIE TO MAKE QUA AN	001010
	C	ARRAY TO MAKE THE INTEGRAL A FUNCTION OF X	001020
	C	QUA = INTEGRAL OF SS FROM X(1) TO X(N) - QUA IS AN ARRAY	001030
95	C		001040
	C	FIND THIRD ORDER SPLINE FCT FOR A FCT Y(X) GIVEN AT THE	001050
	C	POINTS X(1), Y(1)	001060
	C	FOLLOWING CHAPTER OF VOL 2 OF BALSTON + WILF	001070
100	C		001080
	C	N = NO. OF GIVEN DATA POINTS	001090
	C	M = NO. OF SPECIFIED ARGUMENTS T(I) FOR WHICH THE SPLINE	001100
	C	SS, ITS FIRST DER. SS1 AND SECOND DER. SS2 ARE TO BE COMPUTED	001110
	C	EPS = ERROR TOLERANCE IN ITERATIVE STEPS	001120
	C	X = ARRAY OF STRICTLY INCREASING ABSCISSAS	001130
105	C	Y = ARRAY OF FCT VALUES	001140
	C	T = ARRAY OF DESIRED ABSCISSAS	001150
	C	SS = ARRAY OF SPLINE VALUES, SS1, SS2 DERIVATIVES	001160
	C	LIMITATIONS N NOT LARGER THAN 50	001170
	C		001180
110	C	THE ADDITION OF THE SPLINE SUBROUTINE HAS MADE IT NECESSARY TO	001190
	C	INTRODUCE SOME NEW SYMBOLS AND ARRAYS	001200
	C	EPS =. ERROR TOLERANCE IN THE ITERATIVE STEPS	001210
	C	X(22) =. WORK SPACE FOR ARRAY OF STRICTLY INCREASING ABSCISSAS	001220
	C	Y(22) =. WORK SPACE FOR ARRAY OF FCT VALUES	001230
115	C	XX(22) =. WORK SPACE FOR DESIRED ABSCISSAS	001240
	C	SS(22) =. SPLINE VALUE OF U	001250
	C	SS1 =. SPLINE VALUE OF FIRST DERIVATIVE OF U	001260
	C	SS2(22) =. SPLINE SECOND DERIVATIVE OF U	001270
	C	QUA =. INTEGRAL OF SS FROM X(1), X(NN)	001280
120	C	USPIN(22, 22) =. TEMPORARY WORK SPACE, USED BETWEEN RHO-SPLINING	001290
	C	AND ZED SPLINING	001300
	C	MS =. NO. OF GIVEN DATA POINTS	001310
	C	NS =. NO. OF SPLINE INTERPOLATED ARGUMENTS	001320
125	C		001330
	C	----- PROGRAM STATEMENTS -----	001350
	C		001360
	C	WRITE PROGRAM TEMPS - A PROGRAM FOR CALLING A SUBROUTINE CYLTMP,	001370
	C	WHICH USES PROGRAM TEMP4 MODIFIED AND DETERMINES H AND BETA FROM	001380
130	C	EXPERIMENTAL RUNS OF TEMPERATURE VS TIME.	001390
	C		001400
	C	WRITE(6, 215)	001410
	C	WRITE(6, 216)	001420
	C	WRITE(6, 217)	001430
135	C	WRITE(6, 218)	001440
	C		001450
	C	CALL DATINIT	001460
	C	WRITE(5, 200)	001470
	C	CALL CYLTMP	001480
140	C	WRITE(5, 210)	001490
	C	WRITE(5, 220)	001500
	C	CALL EXIT	001510
	C		001520
	C	210 FORMAT(6F12.5)	001530
145	C	215 FORMAT(140, *PROGRAM TEMPS - A PROGRAM FOR CALLING A SUBROUTINE*)	001540
	C	216 FORMAT(140, *CYLTMP, WHICH USES PROGRAM TEMP4 MODIFIED TO*)	001550
	C	217 FORMAT(140, *DETERMINE H AND BETA FROM EXPERIMENTAL RUNS OF *)	001560
	C	218 FORMAT(140, *TEMPERATURE VS TIME.**)	001570
	C	200 FORMAT(140, *WORK OF DATINIT COMPLETE - RETURNED TO TEMPS*)	001580
150	C	210 FORMAT(140, *WORK OF CYLTMP COMPLETE - RETURNED TO TEMPS*)	001590
	C	220 FORMAT(140, *END OF RUN*)	001600
	C		001610
	C	END	001620

A.2 Subroutine DATINIT

1	C	SUBROUTINE DATINIT	001630
		REAL LMDA, MU	001640
		COMMON A(82),B(82),C(82),U(82),UPRIM(82),RMO(82),RFIN(82),	001650
5		*U(82,22),USTAR(82,22),Q(82,22),UFIN(82,22),USPLN(82,22),	001660
		*ZFIN(22),ZED(22),F(4),G(4),H(4),LMDA,MU,NN,M1,N1,M2,N2,NF	001670
	C		001680
	C		001690
		REAL NX,K,IO	001700
10		INTEGER P1,Z1,R2	001710
		INTEGER DATAIN	001720
		DIMENSION DATAIN(100,3)	001730
		COMMON/BLOCK1/	001740
		* I1,I2,I3,I4,I5,I6,I7,M,N,M1,N1,ICNT,IU,IQ,N0,NMX,TRUN,	001750
15		*ICAOD,IPRINT,IPNCH,ITAP3,ITAP4,RHO1,RHO12,ZED1,ZED2,UTAU0,	001760
		*TAUXX,TAUOFF,SIG,QQ,U0, EPS,G1(4),H1(4),MATER,NX,BETA,	001770
		*K,LAMRDA,SIR,S1T,S2P,S2T,	001780
		*DEN,CP,R,EXPER,PW,R1,Z1,R2,IPLOT,PROBNO,TICU,XLEN,YLEN,SCALEX,	001790
		*SCALEY1,SCALEY2,XTITLE(5),YTITLE1(5),YTITLE2(5),NAME	001800
20		EQUVALENCE (11,DATAIN)	001810
		DATA (DATAIN(I,1),I=1,92)/7*2,80,20,3*1,0,1,2,11,100,4,6,6,3,	001820
		*4,0,1,1,5546,1,1092,0035,5,5,1292,2*0,001,4*0,0,3*015,	001830
		*3HKCL,1,47,4,8E-4,00653,10,6,34E-5,05E-5,1E-5,1E-5,1,98,	001840
		*491,1,25R,1H1,24,7,91,11,1,1,4H7204,5,20,9,30,1,1,	001850
25		*10HTIME(SECON,3HDC),3*1H,10HTEMP-DEGC,10H ABOVE AMB,	001860
		*3*1H,10HMEAN TEMP,10H ABOVE AMR,3*1H,7HBARRETT,	001870
		*10HADIAL DIS,10HTANCE,RHO,4H(CM),1H,1H,10HAXIAL DIST,	001880
		*10HANCE,7-(CM,1H),1H,1H /	001890
30		DATA (DATAIN(I,2),I=1,92)/2H11,2H12,2H13,2H14,2H15,	001900
		*2H16,2H17,1HM,1HN,2H41,2H42,4HICNT,2H1U,2H1Q,2HNO,3HNMx,	001910
		*4H1UUN,5HICARD,6HTPOINT,5HIPNCH,5HITAP3,5HITAP4,4HRHO1,	001920
		*5HRHO12,4HZED1,5H7ED1,2,5HUTAU0,5HTAUMX,6HTAUOFF,3HSIG,	001930
		*2HQ0,2HI0,3HFPS,5HG1(1),5HG1(2),5HG1(3),5HG1(4),5HH1(1),	001940
		*5HH1(2),5HH1(3),5HH1(4),8HMATERIAL,8HREF,IND,4HBETA,	001950
35		*9HTHER,CAND,6HLAMRDA,3HS1R,3HS1T,3HS2P,3HS2T,	001960
		*7HDEFNSITY,9HSPCE,AEAT,6HRADIUS,5HEXPER,	001970
		*3HPWR,3HR1,3H71,3HR2,4HPI,TIY,2N,6HPROBNO,4HTICU,	001980
		*4HXLEN,4HYLEN,7HX-SCALE,8HY1-SCALE,8HY2-SCALE,6HXTITLE,	001990
40		*1H2,1H3,1H4,1H5,7HYTITLE1,1H2,1H7,1H4,1H5,7HYTITLE2,1H2,	002000
		*1H3,1H4,1H5,8HOPEATOR,3HAT1,3HXT2,3HXT3,	002010
		*3HXT4,3HXT5,3HYT1,3HYT2,3HYT3,3HYT4,3HYT5/	002020
		DATA (DATAIN(I,3),I=1,92)/22*0,19*1,-1,11*1,-1,1,4*0,	002030
		*-1,4*1,26*-1/	002040
		I1=I2=I3=I4=I5=I6=I7=2	002050
45		ICAOD=5	002060
		INDIC=0	002070
		IPRINT=6	002080
		ITAP3=3	002090
		ITAP4=4	002100
50		M=80	002110
		N=20	002120
		M1=M1=1	002130
		ICNT=1	002140
		IU=0	002150
55		IQ=1	002160
		N0=2	002170
		NMX=11	002180
		IRUN=100	002190
		RHO1=0,	002200
60		RHO12=1,	002210
		ZED1=-.5546	002220
		ZED2=1,1092	002230
		UTAU0=.0015	002240
		TAUXX=5,0	002250
65		TAUOFF=5,0	002260
		SIG=.1292	002270
		QQ=10=0,	002280
		EOS=.001	002290
		G1(1)=G1(2)=G1(3)=G1(4)=0,	002300
70		H1(1)=0,	002310
		H1(2)=H1(3)=H1(4)=.0113	002320
		MATER=10=KCL	002330
		NX=i,47	002340
		BETA=4,8F=4	002350
			002360

75	K=.0653	002370
	DFN=1.999	002380
	CD=.691	002390
	R=1.258	002400
	EXP=R=1.014#2	002410
80	T0=24.7	002420
	R1=21	002430
	Z1=11	002440
	R2=1	002450
	IPLOT=1	002460
85	NAME=10HARRRETT	002470
	POOPNO=10H7204	002480
	TICU=.5	002490
	XLEN=20.	002500
	YLEN=9E0	002510
90	SCALEX=12E0	002520
	SCALEY1=.2E0	002530
	SCALEY2=.2E0	002540
	XTITLE(1)=10HTIME(SECND	002550
	XTITLE(2)=10HDS1	002560
95	YTITLE(1)=10HTEMP-DEGC	002570
	YTITLE(2)=10H ABOVE AMR	002580
	YTITLE(3)=10HMEAN TEMP.	002590
	YTITLE(4)=10H ABOVE AMR.	002600
100	1210 CALL GETDATA (DATAIN,92,4,5,6,3,100,300,INDIC)	002610
	WRITE(ITAP3) DATAIN	002620
	NF=N	002630
	M1=M+1	002640
	N1=N+1	002650
105	M2=M1+1	002660
	N2=N1+1	002670
	C	002680
	C.....CALCULATE THE INCREMENT ARRAY. E(I)...	002690
	C	002700
	RM=M	002710
110	RN=N	002720
	E(1)=RHO12/RM	002730
	E(2)=E(1)	002740
	E(3)=ZEN12/RN	002750
	E(4)=E(3)	002760
115	DRHO=E(1)	002770
	DZEN=E(3)	002780
	NSE=0	002790
	C	002800
	C.....INITIALIZE U,USTAR,Q,UPRIM,A,B,C,D.....	002810
120	C	002820
	DO 20 I = 1,M2	002830
	UPRIM(I) = 0.	002840
	A(I) = 0.	002850
125	B(I) = 0.	002860
	C(I) = 0.	002870
	D(I) = 0.	002880
	DO 20 J = 1,N2	002890
	U(I,J) = 0	002900
	USTAR(I,J) = 0.	002910
130	20 Q(I,J) = 0.	002920
	C	002930
	C	002940
	USTAR,Q,UPRIM,A,B,C,D. INITIALIZED TO ZERO. U = U0	002950
	DO 21 I = 1,M1	002960
	DO 21 J = 1,N1	002970
135	21 UFIN(I,J) = 0	002980
	C	002990
	C	003000
	C	003010
	C	003020
140	DO 17 J = 1,N1	003030
	JJ = J - 1	003040
	ZJ = JJ	003050
	17 ZFIN(J) = ZED1 + 7J*DNZED	003060
145	C	003070
	C	003080
	C	003090
	DO 18 I=1,M1	003100
	II = I - 1	003110

150	RT = II	003120
	18 RFI(I) = RH01 + RI*DRHO	003130
	C	003140
	C	003150
	C	003160
155	DO 46 I = 1,M2	003170
	II = 2*I-3	003180
	RI = II	003190
	RI = RI/2.	003200
	46 RH0(I) = RH01 + RI*DRHO	003210
160	WRITE(IPRINT,290) (I,RH0(I),I=1,M2)	003220
	C	003230
	C	003250
	C	003240
	C	003260
165	DO 55 J = 1,N2	003270
	II = 2*J-3	003280
	RJ = II	003290
	RJ = RJ/2.	003300
	55 ZED(J) = ZED1 + RJ*DRZED	003310
	WRITE(IPRINT,292) (J,ZED(J),J=1,N2)	003320
170	C	003330
	C	003340
	C	003350
	GO TO (2,3), I3	003360
175	2 WRITE(IPRINT,260) U	003370
	WRITE(IPRINT,260) USTAR	003380
	WRITE(IPRINT,260) O	003390
	WRITE(IPRINT,260) UPRIM	003400
	WRITE(IPRINT,260) A	003410
	WRITE(IPRINT,260) B	003420
180	WRITE(IPRINT,260) C	003430
	WRITE(IPRINT,260) D	003440
	WRITE(IPRINT,260) UFIN	003450
	3 IF(IU,EO,0) GO TO 32	003460
	READ(ICADD,225) U	003470
185	32 IF(IQ,EO,0) GO TO 34	003480
	IF(IQ,EO,1) GO TO 31	003490
	READ(ICADD,225) Q	003500
	GO TO 34	003510
	33 CALL GAUSS(IPRINT,SIG,RHO*M2,N2,0,00)	003520
190	34 GO TO (35,36), I4	003530
	35 WRITE(IPRINT,260) U	003540
	WRITE(IPRINT,260) ((O(I,J),I=2,M1),J=2,N1)	003550
	36 NN = 0	003560
195	C	003570
	WRITE(IPRINT,280)	003580
	C	003590
	RETURN	003600
	C	003610
200	210 FORMAT(6F12.5)	003620
	220 FORMAT(7I5,T71,I5,I5)	003630
	225 FORMAT(7F10.3)	003640
	260 FORMAT(140,10(E10,3,1X))	003650
	280 FORMAT(140,*END OF DATAIT*)	003660
	290 FORMAT(140,*I,RH0(I) =*,5(15,F8.4))	003670
205	292 FORMAT(140,*J,ZED(J) =*,5(15,F8.4))	003680
	330 FORMAT(11I5,T71,I5,I5)	003690
	331 FORMAT(7I5,T71,I5,I5)	003700
	335 FORMAT(5F12.5,T71,I5,I5)	003710
210	336 FORMAT(4F12.5,T71,I5,I5)	003720
	END	

A.3 Subroutine CYLTMP

1	SUBROUTINE CYLTMP	003730
	REAL LMDA, MU	003740
	COMMON/BLOCK1/	003750
	* T1,T2,T3,T4,T5,T6,T7,M,N,M1,N1,ICNT,IU,IQ,NQ,NMX,TRUN.	003760
5	*ICARD,IPPOINT,IPNCH,ITAP3,ITAP4,RHO1,RHO12,ZED1,ZED12,UTAU.	003770
	*TAUHX,TAUOFF,SIG,ON,UN, EPS,G1(4),H1(4),MATER,NX,BETA.	003780
	*K,LAMDA,SIR,SIT,S2P,S2T.	003790
	*DFN,CP,R,EXPER,PW,R1,Z1,R2,IPLT,PROBNO,TICU,XLEN,YLEN,SCALEX.	003800
	*SCALEY1,SCALEY2,XTITLE(5),YTITLE1(5),YTITLE2(5),NAME	003810
10	COMMON A(82),B(82),C(82),D(82),UPRIM(82),RHO(82),RFIN(82).	003820
	*U(82,22),USTAR(82,22),O(82,22),UFIN(82,22),USPLN(82,22).	003830
	*ZFIN(22),ZED(22),F(4),G(4),H(4),LMDA,MU,NN,M1,N1,M2,N2,NF	003840
	DIMENSION F1(82),F2(82),X(82),Y(82),SS(82),SS1(82),SS2(82).	003850
	*OIJ(82),YIJ(82),RRR(82),XRR(82),ZZZ(22),XZ(22),T(1)	003860
15	HF(X,Y) = (2.-X*Y)/(2.+X*Y)	003870
	GF(X,Y,Z) = 2.*Y*Z/(2.+X*Y)	003880
	DO I2 I = 1,4	003890
	G(I) = G1(I)	003900
20	H(I) = H1(I)	003910
	WRITE(IPPOINT,255) E	003920
	DRHO = E(1)	003930
	DZEN = E(3)	003940
	C	003950
	C.....NOW WE RELOAD ARRAYS H AND G, USING FUNCTIONS HF AND GF	003960
25	C	003970
	DO I0 I = 1,4	003980
	G(I) = GF(H(I),E(1),G(I))	003990
	H(I) = HF(H(I),E(1))	004000
	C	004010
30	DO I I=1,M1	004020
	RRR(I)=RFIN(I)	004030
	DO I I=1,N1	004040
	ZZZ(I)=ZFIN(I)	004050
	C.....WE NOW WRITE OUT THE NEW VALUES OF ARRAYS G AND H.	004060
35	C	004070
	WRITE(IPRINT,250) G	004080
	WRITE(IPPOINT,245) H	004090
	TAU = 0.	004100
	ICNTR = 0	004110
40	NF = 0	004120
	TFIN = 0.0	004130
	MS=0	004140
	IF (TAUOFF .GE. TAUHX) MS=1	004150
	C	004160
45	C.....MAIN ENTRY FOR NEW I.A.D. CYCLE.....	004170
	C	004180
	55 DTAU=DTAU0	004190
	40 IF (NN.GE.NMX) GO TO 45	004200
	IF (N1.EQ. 0) GOTO 45	004210
50	C	004220
	C	004230
	C	004240
	RNN = NN	004250
	RNO = NQ	004260
55	REX = RNN/RNO	004270
	DTAU = DTAU0*2.**DEX	004280
	C	004290
	C.....INCREMENT TAU,NN,ICNTR.....	004300
	C	004310
60	45 GOTO (330,340,360,330) MS	004320
	340 IF (TAU+2E0*DTAU .LT. TAUOFF) GOTO 330	004330
	MS=1	004340
	DTAU=(TAUOFF-TAU)/2E0	004350
	GOTO 330	004360
65	360 MS=4	004370
	DO 350 J=1,N2	004380
	DO 350 I=1,M2	004390
	O(I,J)=0E0	004400
	350 CONTINUE	004410
70	G(1)=G(2)=G(3)=G(4)=0.	004420
	NN=n	004430
	GOTO 55	004440
	330 TAU=TAU+DTAU	004450
	NN = NN + 1	004460
75	ICNTR = ICNTR + 1	004470
	LMDA = DTAU/DRHO**2	004480
	MU = DTAU/DZED**2	004490
	GO TO (47,48),I2	004500
	47 WRITE(IPPOINT,265) TAU,LMDA,MU,NN,NQ,ICNT,ICNTR	004510

80	48 DO 50 I = 2,M1	004520
	U(I,1) = H(3)*U(I,2)+G(3)	004530
	U(I,N2) = H(4)*U(I,N1)+G(4)	004540
	A(I) = LMDA*(1.-F(I))/2./RHO(I)	004550
	B(I) = -(2.*LMDA+1.)	004560
85	50 C(I) = LMDA*(1.+E(I))/2./RHO(I)	004570
	C	004580
	C COMPLETE THE BORDERING OF THE COMPUTATION LATTICE	004590
	C	004600
	DO 13 J = 2,N1	004610
90	U(I,J) = H(1)*U(2,J)+G(1)	004620
	13 U(M2,J) = H(2)*U(M1,J)+G(2)	004630
	C	004640
	C ...TOUCH UP OF COEFFICIENTS B(I).....	004650
	B(2) = B(2) + A(2)*H(1)	004660
95	B(M1) = B(M1) + C(M1)*H(2)	004670
	DO 70 J = 2,N1	004680
	DO 60 I = 2,M1	004690
	60 D(I) = -MU*(U(I,J,1)-2.*U(I,J)+U(I,J-1))-DTAU*Q(I,J)-U(I,J)	004700
	C	004710
100	C... TOUCH UP OF THE D COEFFICIENTS.....	004720
	C	004730
	D(2) = D(2) - A(2)*G(1)	004740
	D(M1) = D(M1) - C(M1)*G(2)	004750
	CALL TRIDAG(2,M1,A,B,C,D,UPRIM)	004760
105	C	004770
	C...WE HAVE JUST SOLVED THE TRIDIAGONAL EQUATIONS.....	004780
	C...THE RESULTS ARE STORED IN UPRIM.. THE CONTENTS OF UPRIM..	004790
	C...MUST NOW BE TRANSFERRED TO COLUMN J OF ARRAY USTAR.....	004800
	C	004810
110	DO 63 KK = 2,M1	004820
	GO TO (63,64), I3	004830
	63 WRITE(IPRINT,285) KK,A(KK),B(KK),C(KK),D(KK),UPRIM(KK)	004840
	64 DO 70 K = 2,M1	004850
	70 USTAR(K,J) = UPRIM(K)	004860
115	C	004870
	C	004880
	C CALCULATE U ON BOUNDARY AND EVEN LATTICE POINTS BY	004890
	C RENROW INTERNAL SPLINE EXTRAPOLATION TO BOUNDARY POINTS.	004900
	C	004910
120	IF (ICNTR.GT.1) GO TO 16	004920
	NF = NF+1	004930
	TFIN = TAU - DTAU	004940
	C	004950
125	C RENROW MODIFICATION OF SPLINE INTERPOLATION BEGINS AT THIS POINT	004960
	C IT CONSISTS OF EXTRAPOLATIONS TO THE BOUNDARY, USING SLOPE SSU	004970
	C AND VALUE SS AT INTERIOR POINTS RHO(2),RHO(M1),ZED(2),ZEN(N1).	004980
	C OTHER CALCULATIONS ARE MADE BY THIRD ORDER SPLINE INTERPOLATION	004990
	C AND THE ACCURACY OF THE INTERPOLATION IS CONTROLLED BY THE	005000
	C CHOICE OF OF EPS	005010
130	C	005020
	C THE FIRST STEP IN THE PROCESS IS SPLINE INTERPOLATION OF U(I,J)	005030
	C RELATIVE TO RHO-VALUES. INDEX I.	005040
	C	005050
135	DO 160 I = 2,M1	005060
	160 X(I-1) = RHO(I)	005070
	DO 161 J = 1,M1	005080
	161 X(I,J)=RHO(J)	005090
	X(I,1) = RHO(2)	005100
	X(I,M1) = RHO(M1)	005110
140	DO 162 J = 2,N1	005120
	DO 163 I = 2,M1	005130
	163 Y(I-1) = U(I,J)	005140
	C	005150
145	C IF (I.GT.1) GO TO 1	005160
	C WRITE(IPRINT,21)	005170
	C WRITE(IPRINT,200) X	005180
	C WRITE(IPRINT,200) Y	005190
	C WRITE(IPRINT,200) XD	005200
150	C 1 CALL SPLNT(M,M1,EPS,X,Y,XR,SS,SS1,SS2,QUA)	005210
	CALL SPLNT(M,M1,EPS,X,Y,XR,SS,SS1,SS2,QUA)	005220
	C	005230
	C SS AND SS1 ARE USED AT THE END POINTS IN THE BB VERSION.	005240
	C	005250
	DO 164 KS = 1,M1	005260


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155      164 USPLN(KS,J) = SS(KS)                                005270
C      EXTRAPOLATION TO BOUNDARY, USING SS AND SS1            005280
      USPLN (1,J) = SS(1)+(RFIN(1)-RHO(2))*SS1(1)              005290
      USPLN (M1,J) = SS(M1)+(RFIN(M1)-RHO(M1))*SS1(M1)         005300
162      CONTINUE                                              005310
165      C                                                     005320
C      WE NOW HAVE EVEN RHO-INTERPOLATED VALUES OF U. WE NEED EVEN 005330
C      ZED-INTERPOLATED VALUES OF U TO INSERT IN UFIN(I,J,K). 005340
C      THE FOLLOWING STEP DOES SPLINE INTERPOLATION IN THE ZED-DIRECTION 005350
C      005360
165      C      005370
      DO 166 I = 2,N1                                          005380
      166 X(I-1) = ZED(I)                                       005390
      DO 167 J = 1,N1                                          005400
      167 X7(I) = Z77(J)                                         005410
170      X7(M1) = ZED(N1)                                       005420
      DO 168 I = 1,M1                                          005430
      DO 169 I = 2,N1                                          005440
      169 Y(I-1) = USPLN(I,I)                                   005450
C      005460
C      IF(Y.GT.1) GO TO 2                                       005470
C      WRITE(IPRINT,210) X                                       005480
C      WRITE(IPRINT,200) X                                       005490
C      WRITE(IPRINT,200) Y                                       005500
C      WRITE(IPRINT,200) X7                                       005510
180      C      005520
      2 CALL SPLNT(N,N1,EDS,X,Y,XZ,SS,SS1,SS2,QUA)             005530
      CALL SPLNT(N,N1,EDS,X,Y,XZ,SS,SS1,SS2,QUA)             005540
C      005550
C      THE INTERPOLATED RESULT IS NOW STORED IN UFIN           005560
185      C      005570
      DO 170 J = 1,N1                                          005580
      UFIN(I,J) = SS(I)                                         005590
C      005600
      170 EXTRAPOLATION TO BOUNDARY, USING SS AND SS1          005610
      UFIN(I,1) = SS(1)+(ZFIN(I)-ZED(2))*SS1(1)              005620
      UFIN(I,N1) = SS(N1)+(ZFIN(N1)-ZED(N1))*SS1(N1)          005630
190      168 CONTINUE                                           005640
C      005650
C      THIS COMPLETES THE CALCULATION OF UFIN(I,J) FOR THE CURRENT 005660
C      VALUE OF K = NF BY THIRD ORDER SPLINE INTERPOLATION AND 005670
C      EXTRAPOLATION TO THE BOUNDARIES.                        005680
195      C      005690
      DO 130 I = 1,M1                                          005700
      DO 132 J = 1, N1                                          005710
      132 YH(I) = UFIN(I,J)                                       005720
      T(I) = ZFIN(I)                                             005730
      CALL SPLNT(N1,I,EDS,ZFIN,YH,I,SS,SS1,SS2,QUA)           005740
      130 F1(I) = QUA(N1)                                         005750
C      005760
C      THIS COMPLETES THE CALCULATION OF F1                     005770
205      C      005780
      DO 136 I = 1,M1                                          005790
      YH(I) = F1(I)*RFIN(I)                                       005800
      136 T(I) = OFIN(I)                                           005810
      CALL SPLNT(M1,I,EDS,OFIN,YH,I,SS,SS1,SS2,QUA)           005820
210      DO 138 I = 2,M1                                          005830
      138 F2(I) = QUA(I1)/ZFIN(I1)**2                          005840
      F2(I) = A.5*F1(I)                                         005850
C      005860
C      THIS COMPLETES THE CALCULATION OF F2                     005870
215      C      005880
      WRITE(IIPRINT,210) NF,TFIN,PFIN,ZFIN,UFIN,F1,F2          005890
C      005900
C      IF I1 = 1 TYPE OUT F1 AND F2.                            005910
C      IF I5 = 1 TYPE OUT UFIN.                                005920
220      C      005930
      IF(I1.EQ.2.AND.I5.EQ.2) GO TO 170                       005940
      IF(I1.NE.1) GO TO 171                                       005950
      WRITE(IPRINT,300) I                                         005960
      DO 173 I = 1,M1.5                                           005970
      173 WRITE (IPRINT,341) I,F1(I),F2(I)                      005980
225      171 IF(I5.NE.1) GO TO 170                               005990
      WRITE(IPRINT,382) I                                         006000
      DO 174 I = 1,M1.5                                           006010
      174 WRITE(IPRINT,383) I,(UFIN(I,J),J=1,N1,5)

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230 170 CONTINUE
C THE RECORD OF THE SPLINE CALCULATION AND INTEGRATION HAVE BEEN
C WRITTEN AS THE NEXT RECORD ON TAPE 3.
C..... THIS IS THE END OF THE FIRST HALF OF THE I.A.D. CYCLE..
C..... THE INTERMEDIATE ARRAY USTAR HAS BEEN CALCULATED.....
235 C
      16 TAU = TAU + DTAU
      NN = NN + 1
C
C.....APPLY THE RHO BOUNDARY CONDITIONS.....
240 C
      DO 90 J = 2,N1
      USTAR(1,J) = H(1)*USTAR(2,J)*G(1)
      USTAR(M2,J) = H(2)*USTAR(M1,J)*G(2)
      A(J) = MU
245      R(J) = -(2.*MU+1.)
      80 C(J) = MU
C
C.....COEFFICIENT B TOUCH UP....
C
      9(2) = R(2) + A(2)*H(3)
      B(N1) = R(N1) + C(N1)*H(4)
250 C
C.....CALCULATION OF COEFFICIENTS D .....
C
      DO 100 I = 2,M1
      DO 90 J = 2,N1
      D(J) = -LMDA*(USTAR(I+1,J)-2.*USTAR(I,J)+USTAR(I-1,J))
      D(J) = D(J) - LMDA*DQDQ/2./RHO(I)*(USTAR(I+1,J)-USTAR(I-1,J))
      90 D(J) = D(J) - DTAU*D(I,J) - USTAR(I,J)
255 C
C..... TOUCH UP OF THE D COEFFICIENTS....
C
      D(2) = D(2) - A(2)*G(3)
      D(N1) = D(N1) - C(N1)*G(4)
260 C
C.....CALL TRIDAG TO SOLVE THE TRIDIAGONAL SYSTEM OF EQUATIONS..
C.....THE RESULT WILL BE RETURNED IN UPRIM ARRAY.....
C
      CALL TRIDAG(2,N1,A,R,C,D,UPRIM)
      DO 93 KK = 2,N1
      GO TO (97,94),I3
270      97 WRITE(IPRINT,285)KK,A(KK)*B(KK)+C(KK)*D(KK),UPRIM(KK)
      94 DO 100 J = 2,N1
      100 U(I,J) = UPRIM(J)
275      IF(ICNTR,LT,ICNT) GO TO 40
C
C.....AT EACH RETURN TO 40 BEGINS ANOTHER I.A.D. CYCLE..
C
      ICNTR = 1
      GO TO (111,112),I7
280      111 CONTINUE
      WRITE(IPRINT,274) TAU,DTAU
      DO 110 I = 2,M1,M2
      WRITE(IPRINT,275) I,RHO(I)
285      110 WRITE(IPRINT,320) (U(I,J),J=2,N1,N1)
      112 CONTINUE
      IF(TAU,LE,TAUMX) GO TO 40
      WHEN TAU EXCEEDS TAUMX, THIS SUBROUTINE RETURNS TO THE MAIN PROGRAM
C TEMOS, AFTER PRINTING <TAU,GT,TAUMX - CYLTMPT RET TO TEMPS<
C.....END OF I.A.D. CYCLE .....
290      WRITE(IPRINT,11)
      RETURN
      11 FORMAT(1H0,*TAU,GT,TAUMX - CYLTMPT RET TO TEMPS*)
      200 FORMAT(1H0,10F10.4)
      210 FORMAT(1H0,*DEBUGK X,Y,XX*)
295      245 FORMAT(1H0,*H1,H2,H3,H4 =*,4(E10.3,3X))
      250 FORMAT(1H0,*G1,G2,G3,G4 =*,4(E10.3,3X))
      255 FORMAT(1H0,*F1,F2,E1,E4 =*,4(E10.3,3X))
      265 FORMAT(1H0,*TAU,LMDA,MU,NN,N0,ICNT,INCTR =*,3(E10.3,3X)/415)
300      270 FORMAT(1H0,*TAU = *,F10.3,*DTAU = *,E10.3)
      275 FORMAT(1H0,*I,RHO =*,15,F10.4)
      285 FORMAT(1H0,I5,3X,5(F10.3,3X))
      320 FORMAT(1H ,10(E10.3,3X))
      380 FORMAT (/1H0,* ,17X,*F1(I)*.8X,*F2(I)*./)

```

305

```

181 FORMAT (1H0,15,2(3X,F10.3))
182 FORMAT (1H0,*,10X,*UFIN(I,J) FROM J= 1 TO N1 *//)
183 FORMAT (1H0,15,10(3X,F10.3)//1H0,10X,9(3X,E10.3)//
*,1H0,23X,4(3X,E10.3))
END

```

```

006770
006780
006790
006800
006810

```

A.4 Subroutine TRIDAG

```

1      SUBROUTINE TRIDAG (IF,L,A,B,C,D,V)
C
C      THE SUBROUTINE FOR SOLVING A SYSTEM OF LINEAR SIMULTANEOUS
C      EQUATIONS HAVING A TRIDIAGONAL COEFFICIENT MATRIX.
5      C      THE EQUATIONS ARE NUMBERED FROM IF THROUGH L, AND THEIR
C      SUB-DIAGONAL, DIAGONAL, AND SUPER-DIAGONAL COEFFICIENTS ARE
C      STORED IN ARRAYS A,B,C. THE COMPUTED SOLUTION VECTOR
C      V(IF),...,V(L) IS STORED IN ARRAY V.
C
10     DIMENSION A(1),B(1),C(1),U(1),V(1),BETA(82),GAMMA(82)
C
C      ...COMPUTE ARRAYS BETA AND GAMMA.....
C
15     BETA(IF) = B(IF)
      GAMMA(IF) = D(IF)/BETA(IF)
      IFP1 = IF + 1
      DO 1 I = IFP1,L
        BETA(I) = B(I) - A(I)*C(I-1)/BETA(I-1)
        GAMMA(I) = (D(I)-A(I)*GAMMA(I-1))/BETA(I)
20     C
C      ...COMPUTE FINAL SOLUTION VECTOR V .....
C
      V(L) = GAMMA(L)
      LAST = L
      DO 2 K = 1,LAST
        I = L-K
25     2 V(I) = GAMMA(I) - C(I)*V(I+1)/BETA(I)
      RETURN
30     C
      END

```

```

006820
006830
006840
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006990
007000
007010
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007040
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007070
007080
007090
007100
007110

```

A.5 Subroutine GAUSS

1	SUBROUTINE GAUSS(IPRINT,SIG,RHO,M,N,Q,Q0)	007120
	DIMENSION RHO(1),Q(M,N)	007130
	IF(SIG.EQ.0.) GO TO 20	007140
	STG2 = STG**2	007150
5	IF(Q0.GE..001) GO TO 5	007160
1000	Q0=.5/SIG2	007170
5	M1 = M-1	007180
	N1=N-1	007190
	DO 10 I = 2,M1	007200
10	RHO2 = RHO(I)**2	007210
	QTEST=.5*RHO2/STG2	007220
	IF (QTEST .GT. 220.) 1020,1030	007230
1020	Q0=.5	007240
	GO TO 1040	007250
1030	Q0=Q0*EXP(-QTEST)	007260
1040	CONTINUE	007270
	DO 10 J = 2,N1	007280
	Q(I,J) = Q0	007290
	RETURN	007300
20	20 WRITE(IPRINT,100)	007310
	100 FORMAT(1H0,*SIG = 0. DEFAULT OPTION IS Q = 0*)	007320
	RETURN	007330
	END	007340

A.6 Subroutine SPLNI

1	C SUBROUTINE SPLNI(N,M,EPS,X,Y,I,SS,SS1,SS2,QUA)	007350
	C	007360
	C FIND THIRD ORDER SPLINE FCT FOR A FCT Y(X) GIVEN AT THE	007370
	C POINTS (X(I),Y(I))	007380
5	C FOLLOWING CHAP. 9 OF VOL 2 OF RALSTON + WILF	007390
	C	007400
	C N = NO. OF GIVEN DATA POINTS	007410
	C M = NO. OF SPECIFIED ARGUMENTS T(I) FOR WHICH THE SPLINE	007420
	C SS, ITS FIRST DER, SS1 AND SECOND DER, SS2 ARE TO BE COMPUTED	007430
10	C EPS = ERROR TOLERANCE IN ITERATIVE STEPS	007440
	C X = ARRAY OF STRICTLY INCREASING ABSCISSAS	007450
	C Y = ARRAY OF FCT VALUES	007460
	C T = ARRAY OF DESIRED ABSCISSAS	007470
	C SS = ARRAY OF SPLINE VALUES, SS1, SS2 DERIVATIVES	007480
15	C QUA = ARRAY OF VALUES OF INTEGRAL FROM X(1) TO X(N)	007490
	C LIMITATIONS N NOT LARGER THAN 50	007500
	C	007510
	DIMENSION X(1),Y(1),T(1),SS(1),SS1(1),SS2(1),QUA(1)	007520
	DIMENSION H (82),H2(82),DELY(82),B(82),DELSY(82)	007530
20	DIMENSION S2(82),C(82),S3(82)	007540
	DATA OMEGA/1.07179687	007550
	N1=N-1	007560
	DO 51 I=1,N1	007570
	H(I)=X(I+1)-X(I)	007580
25	51 DELY(I)=(Y(I+1)-Y(I))/H(I)	007590
	DO 4 I=2,N1	007600
	H2(I)=H(I-1)*H(I)	007610
	B(I)=.5*H(I-1)/H2(I)	007620
	DELSY(I)=(DELY(I)-DELY(I-1))/H2(I)	007630
30	S2(I)=2.*DELSY(I)	007640
	C(I)=3.*DELSY(I)	007650
	S2(I)=0.	007660
	S2(N)=0.	007670
	5 ETA=0.	007680
35	DO 10 I=2,N1	007690
	W=(C(I)-B(I)*S2(I-1)-(.5-B(I))*S2(I+1)-S2(I))*OMEGA	007700
	IF (ABS(W)-ETA) 10,10,9	007710
	9 ETA=ABS(W)	007720
	10 S2(I)=S2(I)+W	007730

40	13	IF (ETA-FPS) 14.5,5	007740
	14	DO 53 I=1,N1	007750
	53	S3(I)=(S2(I+1)-S2(I))/H(I)	007760
	15	DO 41 J=1,M	007770
	16	I=1	007780
45	54	IF (T(J)-X(I)) 58,17,55	007790
	55	IF (T(J)-X(N1)) 57,59,59	007800
	56	IF (T(J)-X(I)) 60,17,57	007810
	57	I=I+1	007820
		GO TO 56	007830
50	59	WRITE (5,44) J	007840
	44	FORMAT (14,24HTH ARGUMENT OUT OF RANGE)	007850
		GO TO 61	007860
	50	I=N	007870
	60	I=I-1	007880
55	17	HT1=T(J)-X(I)	007890
		HT2=T(J)-X(I+1)	007900
		PROD=HT1*HT2	007910
		S3(I)=S2(I)+HT1*S3(I)	007920
		DELS=(S2(I)+S2(I+1)+S3(I))/6.	007930
60		S3(I)=Y(I)+HT1*DELY(I)+PROD*DELS	007940
		S3(I)=DELY(I)+(HT1+HT2)*DELS+PROD*S3(I)/6.	007950
	61	CONTINUE	007960
	20	QUA(I) = 0.0	007970
		DO 42 I=1,N1	007980
65	62	QUA(I+1)=QUA(I)+.5*H(I)*(Y(I)+Y(I+1))-H(I)**3*(S2(I)+S2(I+1))/24.	007990
		RETURN	008000
		END	008010

A.7 Subroutine GETDATA

1	SUBROUTINE GETDATA(DATIN,NV,IIN,IOUT1,IOUT2,IINI,ISIZE +*,ISIZET,INDIC)		008020
	C THE MAIN PURPOSE OF THIS SUBROUTINE IS TO INPUT CHARACTER STRING OR		008030
	C NUMERICAL DATA IN A CONVERSATIONAL MODE I.E. FOR INPUTTING DATA		008040
5	C TO PROGRAMS BEING RUN UNDER INTERCOM.		008050
	C IT ALSO MAY BE USED FOR BATCH PROCESSING-IN WHICH CASE THE DATA		008060
	C SHOULD APPEAR 6 VALUES TO A CARD, DATA WHICH IS NOT TO BE CHANGED		008070
	C SHOULD BE REPLACED BY BLANKS, FOR BATCH ALL OR SOME OF THE DATA MAY		008080
	C BE REPLACED BY USING AN EOP AFTER THE LAST DATA TO BE INPUTTED.		008090
10	C THE SUBROUTINE ASSUMES THAT DEFAULT VALUES HAVE BEEN ASSIGNED		008100
	C AND WILL PRINT OUT THESE DEFAULT VALUES BEFORE ASKING FOR DATA INPUT.		008110
	C IT ASKS FOR NEW VALUES BY PRINTING OUT THE NAMES OF THE DATA AND THEN		008120
	C SKIPPING A LINE, VALUES TO BE ASSIGNED TO THE NAMES SHOULD BE		008130
	C ENTERED STARTING IN THE SAME COLUMN AS THE START OF THE NAME.		008140
15	C EACH DATUM IS ASSIGNED 10 COLUMNS AND UP TO 6 ITEMS MAY BE INPUTTED		008150
	C IN A SINGLES ROW.		008160
	C ARGUMENTS*****		008170
	C DATIN (DIMENSION (NV,7) WHERE NV IS THE TOTAL # OF DATA		008180
	C TO BE INPUTTED)		008190
20	C NAME,VALUE,CODE WHERE-		008200
	C NAME=> NAME BY WHICH THE DATUM IS IDENTIFIED TO THE USER (IT MAY OR		008210
	C MAY NOT BE EQUAL TO THE FORTRAN VARIABLE NAME TO BE ASSIGNED TO THE		008220
	C DATUM.)		008230
25	C VALUE=> NUMERICAL OR CHARACTER STRING VALUE TO BE ASSIGNED (THE DATUM)		008240
	C CODE=> HOW THE DATUM IS TO BE INTERPRETED		008250
	C -1=> CHARACTER STRING		008260
	C 0=> INTEGER		008270
	C 1=> FLOATING POINT NUMBER		008280
30	C NV TOTAL NUMBER OF DATUM TO BE INPUTTED		008290
	C IIN FILE NO. FOR INPUTTING		008300
	C IOUT1 PRIMARY OUTPUT FILE		008310
	C IOUT2 SECONDARY OUTPUT FILE		008320
	C ISIZE=> SIZE OF FIRST DIMENSION OF DATIN		008330
			008340
			008350

35	DIMENSION DATAIN(IST7ET),IA(6)	008360
	COMMON/SENSE/IINN,IOUTNN,INDICC	008370
	INTEGER DATAIN,F	008380
	EXTERNAL SSWTCH	008390
	CALL ERRSET(KOUNT,20000)	008400
40	KOUNT1=KOUNT	008410
	IF (INDIC.NE.0) 200,210	008420
200	ISW=2	008430
	LL=0	008440
	L=INDIC-1	008450
45	GOTO 1055	008460
210	CONTINUE	008470
	ISW=1	008480
	IDOL=0000000000000000005B	008490
	IINN=IIN	008500
50	IOUTNN=IOUT1	008510
	IOUT=IOUT1	008520
	ISN=1	008530
	IRLANK=10H	008540
	CALL SSWTCH(IIN,ISW,10HREAD DATA ,5HFILE-),RETURNS(1060)	008550
55	IF (ISW.EQ. 1) 1300,1290	008560
1300	WRITE (IOUT1,17) IIN	008570
	REWIND IIN	008580
	READ(IIN) DATAIN	008590
	REWIND IIN	008600
60	IF (EOF(IIN)) 1400,1290	008610
1400	WRITE (IOUT1,24) IIN	008620
1290	CONTINUE	008630
	CALL SSWTCH(0,ISW,10HDEFAULTS L,5HISTED),RETURNS(1060)	008640
	IF (ISW.NE. 1) GOTO 1150	008650
65	WRITE (IOUT1,1)	008660
1140	DO 110 I=1,NV	008670
	II=I*SIZE+1	008680
	III=1	008690
	IT2=II+I*SIZE	008700
70	IF (DATAIN(IT2)) 1020,1030,1040	008710
1020	WRITE (IOUTT,2) DATAIN(II),DATAIN(III)	008720
	GOTO 110	008730
1030	WRITE (IOUTT,3) DATAIN(II),DATAIN(III)	008740
	GOTO 110	008750
75	1040 WRITE (IOUTT,4) DATAIN(II),DATAIN(III)	008760
110	CONTINUE	008770
	GOTO (1150,1130) ISN	008780
1150	CALL SSWTCH(0,ISW,10HNAME-VALUE,5H MODE),RETURNS(1060)	008790
	IF (ISW.EQ. 1) 1270,1050	008800
80	1050 L=1	008810
	ISW=2	008820
	LL=0	008830
1055	L=L+LL	008840
	IF (L.GT. NV) GOTO 1060	008850
85	1310 WRITE (IOUT1,18) DATAIN(I*SIZE+L)	008860
	LL=L	008870
	DO 100 J=1,6	008880
	IA(J)=10H	008890
90	100 CONTINUE	008900
	READ(IIN,10) (IA(J),J=1,6)	008910
	IF (EOF(IIN)) 1320,1070	008920
1320	INDICC=1	008930
	GOTO 1060	008940
95	1070 IF (IA(1).EQ. IRLANK) GOTO 1055	008950
	DO 180 J=1,6	008960
	DO 180 K=1,10	008970
	IF (MXGETX(IA(J),K+1).EQ. IDOL) GOTO 1270	008980
100	180 CONTINUE	008990
	DO 190 J=1,6	009000
	JR=L+J-1	009010
	F=DATAIN(JR+2*ISIZE)	009020
	IF (F) 1090,1100,1110	009030
1090	IF (IA(J).NE. IRLANK) DECODE(10,11,IA(J)) DATAIN(JR)	009040
	GOTO 1080	009050
105	1100 CALL RJUST(IA(J))	009055
	IF (IA(J).NE. IRLANK) DECODE(10,12,IA(J)) DATAIN(JR)	009060
	GOTO 1080	009070
	1110 CALL RJUST(IA(J))	009075
	IF (IA(J).NE. IRLANK) DECODE(10,13,IA(J)) DATAIN(JR)	009080
110	1080 IF (IA(J).EQ. IRLANK) GOTO 1081	009090
	190 CONTINUE	009100
	1081 LL=L-1	009110
	IF (INDIC.NE.0) LL=1000	009120
	IF (KOUNT.EQ. KOUNT1) GOTO 1055	009130

115	KOUNT1=KOUNT	009140
	WRITE(IOUT1,25)	009150
1270	WRITE(IOUT1,23)	009160
1250	WRITE(IOUT1,8)	009170
	DO 150 I=1,6	009180
120	IA(I)=104	009190
150	CONTINUE	009200
	READ(IIN,10) (IA(I),I=1,6)	009210
	IF (EOF(IIN)) 1330,1385	009220
1330	INDTCC=1	009230
125	GOTO 1060	009240
1085	IT=IA(I)	009250
	IF (IT.EQ. IBLANK) GOTO 1060	009260
	DO 130 I=1,NV	009270
	J=I+ISIZE	009280
130	IF (II.EQ. DATAIN(J)) GOTO 1160	009290
130	CONTINUE	009300
	WRITE(IOUT1,16)	009310
	GOTO 1270	009320
1160	F=DATAIN(J+ISIZE)	009330
135	JJ=J-ISIZE	009340
	IF (F) 1170,1180,1190	009350
1170	DO 160 I=2,6	009360
	IF (IA(I).EQ. IBLANK .AND. I.GT.2) GOTO 1240	009370
	DECODE(10,11,IA(I)) DATAIN(JJ:I-2)	009380
140	160 CONTINUE	009390
	GOTO 1240	009400
	1180 CALL RJUST(IA(2))	009405
	DECODE(10,12,IA(2)) DATAIN(JJ)	009410
	GOTO 1240	009420
145	1190 CALL RJUST(IA(2))	009425
	DECODE(10,13,IA(2)) DATAIN(JJ)	009430
1240	IF (KOUNT.EQ. KOUNT1) GOTO (1250,1310) ISW	009440
	KOUNT1=KOUNT	009450
	WRITE(IOUT1,25)	009460
150	GOTO 1250	009470
1060	WRITE(IOUT1,14)	009480
	IF (IOUT2.EQ. 0) GOTO 1190	009490
	WRITE(IOUT2,15)	009500
	IOUT1=IOUT2	009510
155	ISN=2	009520
	GOTO 1140	009530
	1130 INDTCC=INDTCC	009540
	RETURN	009550
160	1 FORMAT(/.* THE DEFAULT INPUT DATA ARE*)	009560
	2 FORMAT(1X,A10,*,*,A10,*,*)	009570
	3 FORMAT(1X,A10,*,*,I10)	009580
	4 FORMAT(1X,A10,*,*,G16.6)	009590
	5 FORMAT(///)	009600
165	6 FORMAT(/.* ENTER DATA. START IN COL. BENEATH START OF NAME*)	009610
	7 FORMAT(8X,6A10)	009620
	8 FORMAT(8X)	009630
	10 FORMAT(6A10)	009640
	11 FORMAT(A10)	009650
	12 FORMAT(I10)	009660
170	13 FORMAT(E10.0)	009670
	14 FORMAT(/.* DATA INPUT COMPLETE*)	009680
	15 FORMAT(/.* THE INPUT DATA VALUES ARE*/)	009690
	16 FORMAT(1X,* TRY AGAIN*)	009700
175	17 FORMAT(/.* READING DATA FROM *.15)	009710
	18 FORMAT(1X,A10,*,*)	009720
	23 FORMAT(8X,*NAME VALUE.....*)	009730
	24 FORMAT(1X,* FILE*.15.* IS EMPTY*)	009740
	25 FORMAT(1X,* WRONG DATA TYPE-TRY AGAIN*)	009750
	END	009760

A.8 Subroutine SSWTCH

1	SUBROUTINE SSWTCH(I,J,M),RETURNS(M)	009770
	COMMON/SENSE/IIN,IOUT,INDIC	009780
	IF (I.EQ.0) GOTO 100	009790
	WRITE(IOUT,1) M1,M2,I	009800
5	GOTO 110	009810
	100 WRITE(IOUT,2) M1,M2	009820
	110 READ(IIN,3) JJ	009830
	J=2	009840
	IF (J.EQ.1HY) J=1	009850
10	INDIC=END(IIN)	009860
	IF (INDIC) 1000,1010	009870
	1000 RETURN M	009880
	1010 RETURN	009890
	1 FORMAT(1X,A10,A5,I2,*,*)	009900
15	2 FORMAT(1X,A10,A5,*,*)	009910
	3 FORMAT(A1)	009920
	END	009930

A.9 Subroutine RJUST

1	SUBROUTINE RJUST(I)	009940
	DIMENSION LC(9)	009950
	DATA (LC=77555555555555555555,77775555555555555555,	009960
	*77777555555555555555,77777755555555555555,	009970
5	*77777777555555555555,77777777755555555555,	009980
	*77777777777555555555,77777777777755555555,	009990
	*77777777777777555555)	010000
	LR=1	010010
	IRITS=0	010020
10	DO 100 I=1,9	010030
	IRITS=IRITS+6	010040
	LR=ACK(IRITS),OR,LR	010050
	IF (LR.EQ.LC(I)) GOTO 110	010060
	100 CONTINUE	010070
15	GOTO 120	010080
	110 L=SHIFT(I,IBITS)	010090
	120 RETURN	010100
	END	010110

Appendix B

Fortran Listings for TIKIRK Program, Options No. 1 and No. 2 Only

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B.1 Main Program TIKIRK

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1      PROGRAM TIKIRK(TAPE4=80/80,TAPE5=80/80,TAPE3,TAPE7,TAPE8,      000100
      *TAPE6=80/80,OUTPUT=80)      000110
C THIS PROGRAM CAN BEST BE DESCRIBED AS THE I/O INTERFACE FOR FUNCTION      000120
C SUBROUTINE IKIRK WHICH COMPUTES THE KIRKHOFF INTENSITY FUNCTION AS      000130
5 C DESCRIBED IN AFCL-72-0565.      000140
C THE INPUT FALLS INTO THREE CLASSES*      000150
C 1) INPUT HAVING TO DO WITH PROPERTIES OF THE WINDOW MATERIAL AND      000160
C THE LASER BEAM, NAMELY* (QUANTITIES CDS UNLESS OTHERWISE INDICATED)      000170
C SIG => VALUE OF SIGMA IN GAUSSIAN BEAM      000180
10 C LAMBDA => WAVELENGTH OF THE LIGHT BEAM IN MICRONS      000190
C P => TOTAL BEAM POWER      000200
C D => WINDOW RADIUS      000210
C RETA => BULK ABSORPTION COEFFICIENT      000220
C K => THERMAL CONDUCTIVITY      000230
15 C NX => INDEX OF REFRACTION      000240
C S1R => S SUB-1, SUB-RHO      000250
C S1T => S SUB-1, SUB-THETA      000260
C S2R => S SUB-2, SUB-RHO      000270
C S2T => S SUB-2, SUB-THETA      000280
20 C T => TIME AT WHICH IKIRK IS TO BE EVALUATED      000290
C 2) INPUT HAVING TO DO WITH THE EVALUATION DOMAIN OF THE FUNCTION      000300
C IKIRK, NAMELY*      000310
C X0 => GAUSSIAN FOCAL DISTANCE (METERS)      000320
C X1 => MINIMUM X-VALUE FOR FUNCTION EVALUATION (METERS)      000330
25 C X2 => MAXIMUM X-VALUE FOR FUNCTION EVALUATION (METERS)      000340
C RHOD1 => MINIMUM RADIUS VALUE FOR FUNCTION EVALUATION      000350
C RHOD2 => MAXIMUM RADIUS VALUE FOR FUNCTION EVALUATION      000360
C NP => NUMBER OF EVALUATION POINTS IN THE RADIAL DIRECTION      000370
C NP => NUMBER OF EVALUATION POINTS IN THE AXIAL (X) DIRECTION      000380
30 C TIM => ARRAY (10 TO 10) OF TIME VALUES FOR FUNCTION EVALUATION      000390
C (TIME VALUES SHOULD BE IN INCREASING SEQUENCE)      000400
C UMIN => MINIMUM U-VALUE FOR FUNCTION EVALUATION (SEE MODE)      000410
C UMAX => MAXIMUM U-VALUE FOR FUNCTION EVALUATION      000420
C VMIN => MINIMUM V-VALUE FOR FUNCTION EVALUATION      000430
35 C VMAX => MAXIMUM V-VALUE FOR FUNCTION EVALUATION      000440
C 3) INPUT HAVING TO DO WITH PROGRAM CONTROL, NAMELY*      000450
C FDS1 => ERROR VALUE FOR INTERPOLATION OF THE TEMPERATURE      000460
C FUNCTION OUTPUTTED BY TEMPS AND INTERPOLATED BY IBM SCI. SUB. ALI.      000470
C MNT => NUMBER OF TEMPERATURE FUNCTION POINTS TO BE USED IN      000480
40 C THE INTERPOLATION (DEFAULT=6)      000490
C IPRINT => USED TO CONTROL DEBUG OUTPUT (1 CAUSES DEBUG OUTPUT)      000500
C (2 CAUSES WINDOW TEMPERATURE DISTRIBUTION SUITABLE FOR      000510
C DISPLAY TO BE OUTPUT)      000520
C NGRIS => NUMBER OF FUNCTION VALUES FOR GAUSSIAN INTEGRATION      000530
45 C MODE => IF MODE=1 THEN THE INTENSITY FUNCTION IS EVALUATED AT      000540
C EQUI-SPACED X AND RHOD-PRIME VALUES; IF MODE=2 IT IS EVALUATED AT      000550
C EQUI-SPACED U AND V VALUES.      000560
C I2 => IF 1 USE IKIRK, IF 2 USE IKIRKP      000570
C (NOTE THAT IKIRKP SHOULD ONLY BE USED ON THE AXES      000580
50 C FOR CONSTANT TEMPERATURE WINDOW)      000590
C ALL THE ABOVE MENTIONED DATA IS OBTAINED BY TWO CALLS TO THE      000600
C INTERACTIVE INPUT SUBROUTINE GETDATA DESCRIBED IN PML TM-16. IN THE      000610
C FIRST CALL ALL DATA IN THE FIRST CATEGORY IS OBTAINED. IN THE      000620
C SECOND CALL ALL DATA IN THE SECOND AND THIRD CATEGORIES ARE      000630
55 C OBTAINED. AN EXCEPTION TO THIS IS I2 (CONTROLS USE OF      000640
C IKIRK AND IKIRKP) WHICH IS OBTAINED ON THE FIRST CALL TO GETDATA.      000650
C FOR A LISTING OF DEFAULT INPUT DATA IT IS RECOMMENDED THAT      000660
C TIKIRK BE RUN INTERACTIVELY UNDER INTERCOM AFTER GIVING THE COMMAND      000670
C CONNECT(TAPE4,TAPE5).      000680
60 C THE MAIN OUTPUT OF TIKIRK IS A SEQUENCE OF UNFORMATTED RECORDS      000690
C OF INTENSITY VALUES WITH CORRESPONDING DOMAIN VALUES. EACH RECORD      000700
C CONSISTS OF THE FOLLOWING SEQUENCE OF VALUES*      000710
C RECORD NO., NUMBER(NP) OF INTENSITY VALUES IN THE AXIAL DIRECTION.      000720
C AXIAL COORDINATE X OR U, TIME VALUE (T) IN SECONDS, NUMBER (NP)      000730
65 C OF INTENSITY VALUES IN THE RADIAL DIRECTION, MINIMUM RADIAL      000740
C COORDINATE RHOD1 OR VMIN, MAXIMUM RADIAL COORDINATE RHOD2 OR      000750
C VMAX, NP INTENSITY VALUES.      000760
C FOR EACH VALUE OF T, NP RECORDS ARE OUTPUTTED CORRESPONDING TO THE      000770
C NP X EVALUATION POINTS. THE RECORD NUMBER RUNS FROM 1 TO NP FOR      000780
70 C EACH TIME VALUE.      000790
C THERE ARE SIX FILES ASSOCIATED WITH THIS PROGRAM (NOT INCLUDING FILE      000800
C OUTPUT). THE FILES ARE REFERRED TO IN THE PROGRAM AND ASSOCIATED      000810
C SUBROUTINES AS IT3,IT4,IT5,IT6,IT7,IT8. THE FILE VALUES ARE IN TURN      000820
C ASSIGNED TO THE USUAL FORTRAN *TAPEN* BY A DATA STATEMENT AND PROGRAM      000830

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	C ASSOCIATION IT IS NECESSARY TO CHANGE EITHER OR BOTH THE DATA AND	000850
	C PROGRAM STATEMENTS.	000860
	C THESE FILES SERVE THE FOLLOWING PURPOSES:	000870
	C IT3 => FILE OUTPUTTED BY PROGRAM TEMPS	000880
80	C IT4 => INTERACTIVE INPUT FILE (SEE GETDATA)	000890
	C IT5 => INTERACTIVE OUTPUT FILE (SEE GETDATA)	000900
	C IT6 => LISTING OF ALL INPUT PARAMETERS AND DEBUG OUTPUT	000910
	C IT7 => UNFORMATTED INTENSITY VALUES. ALSO MAY BE USED TO INSERT	000920
	C IT8 => UNFORMATTED TEMPERATURE DISTRIBUTION VALUES	000930
85	C SUITABLE FOR DISPLAY PURPOSES	000940
	C PREASSIGNED DATA IN CATEGORIES 2 AND 3	000950
	C IN ADDITION TO THE ABOVE FACTS, THE USER SHOULD BE AWARE OF TWO	000960
	C PROGRAM "CONSTANTS". THE FIRST UNDER THE VARIABLE NAME NT IS THE NUM-	000970
	C BER OF TIME VALUES PERMITTED. AT PRESENT THIS IS SET TO 100 (THE	000980
90	C DIMENSION OF THE TIME ARRAY TIM). ALSO NOTE THAT ALL THE TIME	000990
	C DEFAULT VALUES ARE ZERO EXCEPT THE FIRST AND THAT THE PROGRAM STOPS	001000
	C AS SOON AS A SUCCEEDING TIME VALUE IS LESS THAN THE PRECEDING	001010
	C TIME VALUE.	001020
	C THE SECOND "CONSTANT" HAS TO DO WITH THE SIZE OF THE RECORD OUTPUTTED	001030
95	C BY TEMPS. THE SUBROUTINE RTAPE3 READS THE TEMPS OUTPUT UNDER THE	001040
	C ASSUMPTION THAT ALL "AXIAL" ARRAYS ARE OF DIMENSION 82 AND "AXIAL"	001050
	C ARRAYS ARE OF DIMENSION 22. SEE COMMENTS WITHIN SUBROUTINE RTAPE3.	001060
	C THE INTENSITY FUNCTION TKIRK IS DEFINED EXPLICITLY AS A FUNCTION OF	001070
	C THE NON-DIMENSIONAL VARIABLES U AND V AND IMPLICITLY AS A FUNCTION	001080
100	C OF NON-DIMENSIONAL TIME TAU THROUGH THE TIME DEPENDANT FUNCTIONS	001090
	C PHI-THETA AND PHI-RHO AS DEFINED IN THE ABOVE REFERENCE. THESE	001100
	C VARIABLES ARE PASSED THROUGH AN ARGUMENT LIST. ALL "AXIAL" ARRAYS	001110
	C REQUIRED FOR EVALUATION OF TKIRK ARE PASSED THROUGH BLOCK COMMON	001120
	C "PHIRLK". THESE PARAMETERS ARE:	001130
105	C CS1P => C*S1P (SEE TKIRK COMMENTS)	001140
	C CS2P => C*S2P "	001150
	C CS1T => C*S1T "	001160
	C CS2T => C*S2T "	001170
	C XS => STARTING ARGUMENT FOR FUNCTIONS F1,F2 (SEE FUNCTION	001180
110	C PHI COMMENTS)	001190
	C DX => INTERVAL BETWEEN EQUI-SPACED ARGUMENTS OF F1,F2.	001200
	C NF => NUMBER OF VALUES OF F1,F2	001210
	C MNNT => MNT (SEE INPUT DATA)	001220
	C EPSI => EPSI "	001230
	C F1(200) => HOLDS VALUES OF F1 FROM TEMPS	001240
115	C F2(200) => HOLDS VALUES OF F2 FROM TEMPS	001250
	C HOLD => STORES PHI-THETA (PHI-RHO AND PHI-THETA ARE EVALUATED	001260
	C SIMULTANEOUSLY)	001270
	C A => 1/SQRT(2)/SIG (=ALPHA IN THE ABOVE REFERENCE)	001280
120	C KE => WAVE NUMBER	001290
	C TLAST => STORES TIME VALUE READ FROM TEMPS RECORD	001300
	C TNEXT => "	001310
	C IERR => ERROR INDICATOR FOR RTAPE3 (INDICATES OUT OF RANGE	001320
	C TIME OR OUT OF SEQUENCE TIME)	001330
125	C IP => DEBUG OUTPUT "SWITCH"	001340
	C MPI => ENF	001350
	C ISW => SWITCH FOR GAUSSIAN INTEGRATION. WHEN ISW=1 THEN THE	001360
	C X-VALUES FOR GAUSSIAN INTEGRATION ARE FOUND.	001370
	C NGAUSS => NUMBER OF POINTS USED IN THE GAUSSIAN INTEGRATION	001380
130	C (NOTE THAT IS NGAUSS IS CHANGED THEN THE GAUSSIAN INTEGRATION	001390
	C SUBROUTINE MUST ALSO BE CHANGED.)	001400
	C RAI => WINDOW RADIUS	001401
	C NP1 => NUMBER OF TEMPERATURE SAMPLES IN AXIAL DIRECTION	001402
	C (USED FOR OUTPUTTING DISPLAY COMPATIBLE	001403
	C TEMPERATURE DATA)	001404
135	C C3 => CONSTANT TO DIMENSIONALIZE TEMPERATURE DATA	001405
	C FOR DISPLAY	001406
	C C1 => CONSTANT USED TO DIMENSIONALIZE TIME FOR	001407
	C REAL K,TKIRK,LAMBDA,NX,KE	001410
140	C REAL IKIRKP	001420
	C LOGICAL S	001430
	C DIMENSION BUF(100)	001440
	C COMMON/ITLES/IT3,IT4,IT5,IT6,IT7,IT8	001450
	C COMMON/PHIRLK/CS1P,CS2P,CS1T,CS2T,XS,NX,NF,MNNT,EPP,F1(200),	001460
145	C *F2(200),HOLD,A,KE,TLAST,TLAST,TNEXT,IERR,IP,MPI,ISW,NGAUSS,	001470
	C *RAI,NP1,C3,C1	001480
	C INTEGER DATIN(100,3),DATIN1(100,3)	001490
	C COMMON/BLOCK2/X1,X2,RHO1,RHO2,MP,NP,TIM(10),EPSI	001500
	C TEMPERATURE DISPLAY	001508

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150 *MINT,IPDNT,NGAUS,MODE,IMIN,IMAX,VMIN,VMAX,DUM(20),MSKIP,NSKIP
COMMON/BLOCK1/
* T1,T2,T3,T4,T5,T6,T7,M,N,MI,NI,ICNT,IU,IO,N0,NMX,TRUN.
*ICAD,IPDINT,IPNCH,ITAP1,ITAP2,RHO1,RHO2,ZED1,ZED2,UTAU.
*TAU,X,TAUOFF,SIG,QA,UA, EPS,G1(4),H1(4),MATER,NX,BETA.
155 *K,LAMRDA,SIR,SIT,S2P,S2T.
*QFN,CP,R,EXPER,DW,R1,T1,R2,IPL0T,PROBNO,TICU,XLEN,YLEN,SCALEX.
*SCALEY1,SCALEY2,XTITLE(5),YTITLE(5),YTITLE2(5),NAME
EQUIVALENCE (I1,DATIN1),(X0,DATIN1)
DATA (DATIN(I,1),I=1,92)/7*2,80,20,3*1,0,1,2,11,100,4*6,0,3.
160 *4.0,1.0,5546,1.1002,0035,5,5,1202,2*0,001,4*0,0,3*015.
*3HKL,1.47,4.8E-4,0453,10.6,34E-5,05E-5,1E-5,1E-5,1.98.
*691,1.258,1H1,24,7,81,11,1,1,4H7204,5,20,9,30,1,1.
*10HIME(SFCON,3HDS),3*1H,10HIMP-DEGC,10H ABOVE AMR,
*3*1H,10HMFAN TEMP,10H ABOVE AMR,3*1H,7HBARRETT,
165 *10HAXIAL DIST,10HANCE,RHO,4HICM,1H,1H,10HAXIAL DIST.
*10HANCE,7-(CM,1H),1H,1H /
DATA (DATIN(I,2),I=1,92)/2H11,2H12,2H13,2H14,2H15,
2H16,2H17,1HM,1HN,2HMT,2HNI,4HICNT,2HTU,2HTG,2HNO,3HNM,
*4HIDUN,5HICARD,6HTPINT,5HIPNCH,5HITAP3,5HITAP4,4HRO1,
170 *5HRO12,4HZED1,5H7ED12,5HTAUU,5HTAUMX,6HTAUOFF,3HSIG,
*2HQA,2HUA,3HEPS,5HG1(1),5HG1(2),5HG1(3),5HG1(4),5HH1(1),
*5HH1(2),5HH1(3),5HH1(4),8HMATERIAL,8HDEF,IND,4HBETA,
*9HTER,CAND,6HLAMRDA,3HSIR,3HSIT,3HS2P,3HS2T,
*7HOFNCTY,9HSPEC,HEAT,6HRADIUS,5HEXPER,
175 *3HPUR,3HR1,3HT1,3H2,3H3,3H4,3H5,3H6,3H7,3H8,3H9,3H10,3H11,3H12,3H13,3H14,3H15,3H16,3H17,3H18,3H19,3H20,3H21,3H22,3H23,3H24,3H25,3H26,3H27,3H28,3H29,3H30,3H31,3H32,3H33,3H34,3H35,3H36,3H37,3H38,3H39,3H40,3H41,3H42,3H43,3H44,3H45,3H46,3H47,3H48,3H49,3H50,3H51,3H52,3H53,3H54,3H55,3H56,3H57,3H58,3H59,3H60,3H61,3H62,3H63,3H64,3H65,3H66,3H67,3H68,3H69,3H70,3H71,3H72,3H73,3H74,3H75,3H76,3H77,3H78,3H79,3H80,3H81,3H82,3H83,3H84,3H85,3H86,3H87,3H88,3H89,3H90,3H91,3H92,3H93,3H94,3H95,3H96,3H97,3H98,3H99,3H100,3H101,3H102,3H103,3H104,3H105,3H106,3H107,3H108,3H109,3H110,3H111,3H112,3H113,3H114,3H115,3H116,3H117,3H118,3H119,3H120,3H121,3H122,3H123,3H124,3H125,3H126,3H127,3H128,3H129,3H130,3H131,3H132,3H133,3H134,3H135,3H136,3H137,3H138,3H139,3H140,3H141,3H142,3H143,3H144,3H145,3H146,3H147,3H148,3H149,3H150,3H151,3H152,3H153,3H154,3H155,3H156,3H157,3H158,3H159,3H160,3H161,3H162,3H163,3H164,3H165,3H166,3H167,3H168,3H169,3H170,3H171,3H172,3H173,3H174,3H175,3H176,3H177,3H178,3H179,3H180,3H181,3H182,3H183,3H184,3H185,3H186,3H187,3H188,3H189,3H190,3H191,3H192,3H193,3H194,3H195,3H196,3H197,3H198,3H199,3H200,3H201,3H202,3H203,3H204,3H205,3H206,3H207,3H208,3H209,3H210,3H211,3H212,3H213,3H214,3H215,3H216,3H217,3H218,3H219,3H220,3H221,3H222,3H223,3H224,3H225,3H226,3H227,3H228,3H229,3H230,3H231,3H232,3H233,3H234,3H235,3H236,3H237,3H238,3H239,3H240,3H241,3H242,3H243,3H244,3H245,3H246,3H247,3H248,3H249,3H250,3H251,3H252,3H253,3H254,3H255,3H256,3H257,3H258,3H259,3H260,3H261,3H262,3H263,3H264,3H265,3H266,3H267,3H268,3H269,3H270,3H271,3H272,3H273,3H274,3H275,3H276,3H277,3H278,3H279,3H280,3H281,3H282,3H283,3H284,3H285,3H286,3H287,3H288,3H289,3H290,3H291,3H292,3H293,3H294,3H295,3H296,3H297,3H298,3H299,3H300,3H301,3H302,3H303,3H304,3H305,3H306,3H307,3H308,3H309,3H310,3H311,3H312,3H313,3H314,3H315,3H316,3H317,3H318,3H319,3H320,3H321,3H322,3H323,3H324,3H325,3H326,3H327,3H328,3H329,3H330,3H331,3H332,3H333,3H334,3H335,3H336,3H337,3H338,3H339,3H340,3H341,3H342,3H343,3H344,3H345,3H346,3H347,3H348,3H349,3H350,3H351,3H352,3H353,3H354,3H355,3H356,3H357,3H358,3H359,3H360,3H361,3H362,3H363,3H364,3H365,3H366,3H367,3H368,3H369,3H370,3H371,3H372,3H373,3H374,3H375,3H376,3H377,3H378,3H379,3H380,3H381,3H382,3H383,3H384,3H385,3H386,3H387,3H388,3H389,3H390,3H391,3H392,3H393,3H394,3H395,3H396,3H397,3H398,3H399,3H400,3H401,3H402,3H403,3H404,3H405,3H406,3H407,3H408,3H409,3H410,3H411,3H412,3H413,3H414,3H415,3H416,3H417,3H418,3H419,3H420,3H421,3H422,3H423,3H424,3H425,3H426,3H427,3H428,3H429,3H430,3H431,3H432,3H433,3H434,3H435,3H436,3H437,3H438,3H439,3H440,3H441,3H442,3H443,3H444,3H445,3H446,3H447,3H448,3H449,3H450,3H451,3H452,3H453,3H454,3H455,3H456,3H457,3H458,3H459,3H460,3H461,3H462,3H463,3H464,3H465,3H466,3H467,3H468,3H469,3H470,3H471,3H472,3H473,3H474,3H475,3H476,3H477,3H478,3H479,3H480,3H481,3H482,3H483,3H484,3H485,3H486,3H487,3H488,3H489,3H490,3H491,3H492,3H493,3H494,3H495,3H496,3H497,3H498,3H499,3H500,3H501,3H502,3H503,3H504,3H505,3H506,3H507,3H508,3H509,3H510,3H511,3H512,3H513,3H514,3H515,3H516,3H517,3H518,3H519,3H520,3H521,3H522,3H523,3H524,3H525,3H526,3H527,3H528,3H529,3H530,3H531,3H532,3H533,3H534,3H535,3H536,3H537,3H538,3H539,3H540,3H541,3H542,3H543,3H544,3H545,3H546,3H547,3H548,3H549,3H550,3H551,3H552,3H553,3H554,3H555,3H556,3H557,3H558,3H559,3H560,3H561,3H562,3H563,3H564,3H565,3H566,3H567,3H568,3H569,3H570,3H571,3H572,3H573,3H574,3H575,3H576,3H577,3H578,3H579,3H580,3H581,3H582,3H583,3H584,3H585,3H586,3H587,3H588,3H589,3H590,3H591,3H592,3H593,3H594,3H595,3H596,3H597,3H598,3H599,3H600,3H601,3H602,3H603,3H604,3H605,3H606,3H607,3H608,3H609,3H610,3H611,3H612,3H613,3H614,3H615,3H616,3H617,3H618,3H619,3H620,3H621,3H622,3H623,3H624,3H625,3H626,3H627,3H628,3H629,3H630,3H631,3H632,3H633,3H634,3H635,3H636,3H637,3H638,3H639,3H640,3H641,3H642,3H643,3H644,3H645,3H646,3H647,3H648,3H649,3H650,3H651,3H652,3H653,3H654,3H655,3H656,3H657,3H658,3H659,3H660,3H661,3H662,3H663,3H664,3H665,3H666,3H667,3H668,3H669,3H670,3H671,3H672,3H673,3H674,3H675,3H676,3H677,3H678,3H679,3H680,3H681,3H682,3H683,3H684,3H685,3H686,3H687,3H688,3H689,3H690,3H691,3H692,3H693,3H694,3H695,3H696,3H697,3H698,3H699,3H700,3H701,3H702,3H703,3H704,3H705,3H706,3H707,3H708,3H709,3H710,3H711,3H712,3H713,3H714,3H715,3H716,3H717,3H718,3H719,3H720,3H721,3H722,3H723,3H724,3H725,3H726,3H727,3H728,3H729,3H730,3H731,3H732,3H733,3H734,3H735,3H736,3H737,3H738,3H739,3H740,3H741,3H742,3H743,3H744,3H745,3H746,3H747,3H748,3H749,3H750,3H751,3H752,3H753,3H754,3H755,3H756,3H757,3H758,3H759,3H760,3H761,3H762,3H763,3H764,3H765,3H766,3H767,3H768,3H769,3H770,3H771,3H772,3H773,3H774,3H775,3H776,3H777,3H778,3H779,3H780,3H781,3H782,3H783,3H784,3H785,3H786,3H787,3H788,3H789,3H790,3H791,3H792,3H793,3H794,3H795,3H796,3H797,3H798,3H799,3H800,3H801,3H802,3H803,3H804,3H805,3H806,3H807,3H808,3H809,3H810,3H811,3H812,3H813,3H814,3H815,3H816,3H817,3H818,3H819,3H820,3H821,3H822,3H823,3H824,3H825,3H826,3H827,3H828,3H829,3H830,3H831,3H832,3H833,3H834,3H835,3H836,3H837,3H838,3H839,3H840,3H841,3H842,3H843,3H844,3H845,3H846,3H847,3H848,3H849,3H850,3H851,3H852,3H853,3H854,3H855,3H856,3H857,3H858,3H859,3H860,3H861,3H862,3H863,3H864,3H865,3H866,3H867,3H868,3H869,3H870,3H871,3H872,3H873,3H874,3H875,3H876,3H877,3H878,3H879,3H880,3H881,3H882,3H883,3H884,3H885,3H886,3H887,3H888,3H889,3H890,3H891,3H892,3H893,3H894,3H895,3H896,3H897,3H898,3H899,3H900,3H901,3H902,3H903,3H904,3H905,3H906,3H907,3H908,3H909,3H910,3H911,3H912,3H913,3H914,3H915,3H916,3H917,3H918,3H919,3H920,3H921,3H922,3H923,3H924,3H925,3H926,3H927,3H928,3H929,3H930,3H931,3H932,3H933,3H934,3H935,3H936,3H937,3H938,3H939,3H940,3H941,3H942,3H943,3H944,3H945,3H946,3H947,3H948,3H949,3H950,3H951,3H952,3H953,3H954,3H955,3H956,3H957,3H958,3H959,3H960,3H961,3H962,3H963,3H964,3H965,3H966,3H967,3H968,3H969,3H970,3H971,3H972,3H973,3H974,3H975,3H976,3H977,3H978,3H979,3H980,3H981,3H982,3H983,3H984,3H985,3H986,3H987,3H988,3H989,3H990,3H991,3H992,3H993,3H994,3H995,3H996,3H997,3H998,3H999,3H1000,3H1001,3H1002,3H1003,3H1004,3H1005,3H1006,3H1007,3H1008,3H1009,3H1010,3H1011,3H1012,3H1013,3H1014,3H1015,3H1016,3H1017,3H1018,3H1019,3H1020,3H1021,3H1022,3H1023,3H1024,3H1025,3H1026,3H1027,3H1028,3H1029,3H1030,3H1031,3H1032,3H1033,3H1034,3H1035,3H1036,3H1037,3H1038,3H1039,3H1040,3H1041,3H1042,3H1043,3H1044,3H1045,3H1046,3H1047,3H1048,3H1049,3H1050,3H1051,3H1052,3H1053,3H1054,3H1055,3H1056,3H1057,3H1058,3H1059,3H1060,3H1061,3H1062,3H1063,3H1064,3H1065,3H1066,3H1067,3H1068,3H1069,3H1070,3H1071,3H1072,3H1073,3H1074,3H1075,3H1076,3H1077,3H1078,3H1079,3H1080,3H1081,3H1082,3H1083,3H1084,3H1085,3H1086,3H1087,3H1088,3H1089,3H1090,3H1091,3H1092,3H1093,3H1094,3H1095,3H1096,3H1097,3H1098,3H1099,3H1100,3H1101,3H1102,3H1103,3H1104,3H1105,3H1106,3H1107,3H1108,3H1109,3H1110,3H1111,3H1112,3H1113,3H1114,3H1115,3H1116,3H1117,3H1118,3H1119,3H1120,3H1121,3H1122,3H1123,3H1124,3H1125,3H1126,3H1127,3H1128,3H1129,3H1130,3H1131,3H1132,3H1133,3H1134,3H1135,3H1136,3H1137,3H1138,3H1139,3H1140,3H1141,3H1142,3H1143,3H1144,3H1145,3H1146,3H1147,3H1148,3H1149,3H1150,3H1151,3H1152,3H1153,3H1154,3H1155,3H1156,3H1157,3H1158,3H1159,3H1160,3H1161,3H1162,3H1163,3H1164,3H1165,3H1166,3H1167,3H1168,3H1169,3H1170,3H1171,3H1172,3H1173,3H1174,3H1175,3H1176,3H1177,3H1178,3H1179,3H1180,3H1181,3H1182,3H1183,3H1184,3H1185,3H1186,3H1187,3H1188,3H1189,3H1190,3H1191,3H1192,3H1193,3H1194,3H1195,3H1196,3H1197,3H1198,3H1199,3H1200,3H1201,3H1202,3H1203,3H1204,3H1205,3H1206,3H1207,3H1208,3H1209,3H1210,3H1211,3H1212,3H1213,3H1214,3H1215,3H1216,3H1217,3H1218,3H1219,3H1220,3H1221,3H1222,3H1223,3H1224,3H1225,3H1226,3H1227,3H1228,3H1229,3H1230,3H1231,3H1232,3H1233,3H1234,3H1235,3H1236,3H1237,3H1238,3H1239,3H1240,3H1241,3H1242,3H1243,3H1244,3H1245,3H1246,3H1247,3H1248,3H1249,3H1250,3H1251,3H1252,3H1253,3H1254,3H1255,3H1256,3H1257,3H1258,3H1259,3H1260,3H1261,3H1262,3H1263,3H1264,3H1265,3H1266,3H1267,3H1268,3H1269,3H1270,3H1271,3H1272,3H1273,3H1274,3H1275,3H1276,3H1277,3H1278,3H1279,3H1280,3H1281,3H1282,3H1283,3H1284,3H1285,3H1286,3H1287,3H1288,3H1289,3H1290,3H1291,3H1292,3H1293,3H1294,3H1295,3H1296,3H1297,3H1298,3H1299,3H1300,3H1301,3H1302,3H1303,3H1304,3H1305,3H1306,3H1307,3H1308,3H1309,3H1310,3H1311,3H1312,3H1313,3H1314,3H1315,3H1316,3H1317,3H1318,3H1319,3H1320,3H1321,3H1322,3H1323,3H1324,3H1325,3H1326,3H1327,3H1328,3H1329,3H1330,3H1331,3H1332,3H1333,3H1334,3H1335,3H1336,3H1337,3H1338,3H1339,3H1340,3H1341,3H1342,3H1343,3H1344,3H1345,3H1346,3H1347,3H1348,3H1349,3H1350,3H1351,3H1352,3H1353,3H1354,3H1355,3H1356,3H1357,3H1358,3H1359,3H1360,3H1361,3H1362,3H1363,3H1364,3H1365,3H1366,3H1367,3H1368,3H1369,3H1370,3H1371,3H1372,3H1373,3H1374,3H1375,3H1376,3H1377,3H1378,3H1379,3H1380,3H1381,3H1382,3H1383,3H1384,3H1385,3H1386,3H1387,3H1388,3H1389,3H1390,3H1391,3H1392,3H1393,3H1394,3H1395,3H1396,3H1397,3H1398,3H1399,3H1400,3H1401,3H1402,3H1403,3H1404,3H1405,3H1406,3H1407,3H1408,3H1409,3H1410,3H1411,3H1412,3H1413,3H1414,3H1415,3H1416,3H1417,3H1418,3H1419,3H1420,3H1421,3H1422,3H1423,3H1424,3H1425,3H1426,3H1427,3H1428,3H1429,3H1430,3H1431,3H1432,3H1433,3H1434,3H1435,3H1436,3H1437,3H1438,3H1439,3H1440,3H1441,3H1442,3H1443,3H1444,3H1445,3H1446,3H1447,3H1448,3H1449,3H1450,3H1451,3H1452,3H1453,3H1454,3H1455,3H1456,3H1457,3H1458,3H1459,3H1460,3H1461,3H1462,3H1463,3H1464,3H1465,3H1466,3H1467,3H1468,3H1469,3H1470,3H1471,3H1472,3H1473,3H1474,3H1475,3H1476,3H1477,3H1478,3H1479,3H1480,3H1481,3H1482,3H1483,3H1484,3H1485,3H1486,3H1487,3H1488,3H1489,3H1490,3H1491,3H1492,3H1493,3H1494,3H1495,3H1496,3H1497,3H1498,3H1499,3H1500,3H1501,3H1502,3H1503,3H1504,3H1505,3H1506,3H1507,3H1508,3H1509,3H1510,3H1511,3H1512,3H1513,3H1514,3H1515,3H1516,3H1517,3H1518,3H1519,3H1520,3H1521,3H1522,3H1523,3H1524,3H1525,3H1526,3H1527,3H1528,3H1529,3H1530,3H1531,3H1532,3H1533,3H1534,3H1535,3H1536,3H1537,3H1538,3H1539,3H1540,3H1541,3H1542,3H1543,3H1544,3H1545,3H1546,3H1547,3H1548,3H1549,3H1550,3H1551,3H1552,3H1553,3H1554,3H1555,3H1556,3H1557,3H1558,3H1559,3H1560,3H1561,3H1562,3H1563,3H1564,3H1565,3H1566,3H1567,3H1568,3H1569,3H1570,3H1571,3H1572,3H1573,3H1574,3H1575,3H1576,3H1577,3H1578,3H1579,3H1580,3H1581,3H1582,3H1583,3H1584,3H1585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	120	XMIN=RHOP1	002310
		XMAX=RHOP2	002320
230	140	CONTINUE	002330
		A=.5/SIG	002340
		C=P.*(NX**2+1)/2./NX	002350
		C=C*R*BETA/3.14159/K	002360
235		CS10=C*S1R	002370
		CS20=C*S2R	002380
		CS1T=C*S1T	002390
		CS2T=C*S2T	002400
		RSQ=R*R	002410
240		X0=X0*100.	002420
		X1=X1*100.	002430
		X2=X2*100.	002440
		C1=X/RSQ/DEN/CP	002450
		DELY=(X2-X1)/(AMAX0(1,NP-1))	002460
245		DELPH0=(RHOP2-RHOP1)/(AMAX0(1,MP-1))	002470
		DELV=(VMAX-VMIN)/(AMAX0(1,MP-1))	002480
		DELU=(UMAX-UMIN)/(AMAX0(1,NP-1))	002490
		RAD=R	002500
		NP1=N+1	002510
250		C3=C/R	002520
		X0I=1./X0	002530
		NREC=0	002540
		IT=1	002550
		TR=T+TIM(I)	002560
255		IF (T.LT. 0.) GOTO 2000	002570
		IF (TP.EQ.2) WRITE(ITR) DATATN	002580
	1000	T=T+C1	002590
		WRITE(ITS,2) T	002600
		IF (T.GT. TAUMX) GOTO 2000	002610
260		X1T=X1	002620
		X1I=1./X1T	002630
		U=UMIN	002640
		DO 100 I=1,NP	002650
		CX=(X0*X1I)**2	002655
265		IF (S) U=KE*RSQ*(X0I-X1I)	002660
		RHOP=RHOP1	002670
		V=VMIN	002680
		DO 110 J=1,MP	002690
		IF (S) V=KE*R*X1I*RHOP	002700
270		GOTO (220,200) 12	002710
	220	BUF(J)=CX*IKIRKP(I,V,T)	002720
		GOTO 210	002730
	200	BUF(J)=CX*IKIRK(U,V,T)	002740
	210	RHOP=RHOP+DELRHO	002750
275		V=V+DELV	002760
	110	CONTINUE	002770
		P=U	002774
		IF (S) P=X1T	002776
		WRITE (ITT) I,NP,D,TR,MP,XMIN,XMAX,(BUF(J),J=1,MP)	002780
280		CALC PRT(RUF,MODE,I,TT,MP,NP,MSKIP,NSKIP,RHOP1,	002790
		*DELPH0,VMIN,DELV,X1T,U,TR,T,ITT)	002800
		NREC=NREC+1	002810
		X1T=X1T+DELY	002820
		X1I=1./X1T	002830
285		U=U+DELU	002840
	100	CONTINUE	002850
		IT=IT+1	002860
		IF (IT.GT. NT) GOTO 2000	002870
		TR=T+TIM(IT)	002880
290		IF (T.GT. TIM(IT-1)) GOTO 1000	002890
	2000	WRITE(ITS,1) NREC	002900
	1	FORMAT(IX,* THE NUMBER OF RECORDS IS=*,I10)	002910
	2	FORMAT(IX,* NEW VALUE OF TAU IS*,E13.5)	002920
	3	FORMAT(IX,I6.4E12.4)	002930
	4	FORMAT(IX,4E13.5)	002940
295	5	FORMAT(IX,I6.4G12.4,1(/,5X,5G13.5))	002950
		END	002960

B.2 Function IKIRK

```

1      REAL FUNCTION IKIRK(U,V,T)                                002970
C      FUNCTION IKIRK IS THE KIRKHOFF INTENSITY FUNCTION DESCRIBED IN 002990
C      HENDON,B. AND GIANINO,C. OPTICAL PERFORMANCE EVALUATION OF 003000
C      INFRARED TRANSMITTING WINDOWS AFRL-72-0565. ASSUMING A GAUSSIAN 003010
C      SHAPED UNPOLARIZED SOURCE. THE INTENSITY FUNCTION CAN BE WRITTEN* 003020
5      C IKIRK(U,V)=2(A!2/(1-EXP(-A!2)))!2*(I(0,1,DX)(FW*FX)!12+ 003030
C      I(0,1,DX)(FW*FY)!12 003040
C      WHERE* 003050
C      FW(Y,II)=EXP(-(A*X)!2)*EXP(-I*U*X!2/2) 003060
10      C FX(X,V)=X*J0(X*V)*EXP(I*K*PHIR(X))-FZ(X,V) 003070
C      FY(X,V)=X*J0(X*V)*EXP(I*K*PHI(X))+FZ(X,V) 003080
C      FZ(X,V)=I(X*V)*(EXP(I*K*PHIR(X))-EXP(I*K*PHI(X)))/(V) 003090
C      A=1/SQRT(2)/SIG**2 003100
C      K=WAVE NO. (OMEGA/C) 003110
15      C NOTATION* 003120
C      ! => EXPONENTIATION 003130
C      I => IMAGINARY 003140
C      I(0,1,DX)(.) MEANS INTEGRATION OF THE FUNCTION WITHIN (.) W.R.T.X 003150
C      OVER THE INTERVAL (0,1). 003160
20      C I0 AND I1 ARE BESSEL FUNCTIONS OF THE FIRST KIND,ZEROth AND FIRST 003170
C      ORDER RESPECTIVELY. 003180
C      PHIR(X) AND PHIT(X) ARE THE FUNCTIONS PHI-SUPERSCRIPT-RHO AND PHI- 003190
C      SUPERSCRIPT-THETA RESPECTIVELY IN THE ABOVE REFERENCE. 003200
C      THESE FUNCTIONS ARE GIVEN BY* 003210
25      C PHIR(X)=C*S10*F1(X)+4*C*S2R*F2(X) 003220
C      PHIT(X)=C*S1T*F1(X)+4*C*S2T*F2(X) 003230
C      WHERE* 003240
C      C=R!3*P0*RETA/KT 003250
C      R=WINDOW RADIUS (CM) 003260
30      C P0=MEAN INCIDENT POWER DENSITY (WATTS/CM!2) 003270
C      RETA=BULK ABSORPTION COEFFICIENT (1/CM) 003280
C      KT=THERMAL CONDUCTIVITY (WATTS/CM DEG C) 003290
C      S1R,S2R,S1T,S2T ARE MATERIAL CONSTANTS DEFINED IN THE ABOVE REF. 003300
C      F1,F2 ARE THE FUNCTIONS DELTRAP-PRIME(X) AND 003310
35      C (1/X!2)I(0,X,DS) (DELTRAP-PRIME(S)) 003320
C      GIVEN IN THE ABOVE REFERENCE AND WHICH ARE PROVIDED AT SELECTED 003330
C      ARGUMENTS BY PROGRAM @TEMP50. 003340
C      ***** 003350
C      COMMON/PHIRLK/CS10,CS2R,CS1T,CS2T,XS,NZ,NF,MINT,EPS,F1(200), 003360
40      *F2(200),HOLD,A,K,TLAST,TNEXT,IERR,IP,MPI,ISW,N, 003370
C      *RAD,NP1,C3,C1 003380
C      COMMON/FILES/IT3,IT4,IT5,IT6,IT7,IT8 003390
C      COMPLEX Q1,EXPR,EXPT,FX,FY,FZ,FW 003400
45      REAL J0,I1 003410
C      REAL K 003420
C      DIMENSION XA(100),Y0(100),YI(100),ZR(100),ZI(100) 003430
C      A2=A*A 003440
C      IF (A2.GT. 220.) 1020,1030 003450
50      1020 CONST=2.*A2*A2 003460
C      GOTO 1040 003470
1030 CONST=2.*(A2/(1.-EXP(-A2)))**2 003480
1040 UN2=U/2*F0 003490
C      IF ISW=1 THEN THE ARRAY OF POINTS FOR GAUSSIAN INTEGRATION 003500
C      MUST BE FOUND 003510
55      GOTO (1050,1060) ISW 003520
1050 ISW=2 003530
C      CALL DQ624A(0E0,1F0,XA) 003540
C      IF (IP.EQ. 1) WRITE(IT6,1) (XA(I),I=1,N) 003550
60      1060 CALL RTAPE3(T) 003560
C      IF (IERR.NE. 0) GOTO 2000 003570
C      DO 100 I=1,N 003580
C      X=XA(I) 003590
C      X2=X*X 003600
C      XV=X*V 003610
65      FW=EXP(-A2*X2)*CEXP(CMPLX(0E0,-UN2*X2)) 003620
C      EXPR=CEXP(CMPLX(0F0,K*PHIR(X))) 003630
C      EXPT=CEXP(CMPLX(0F0,K*PHIT(X))) 003640
C      IF (V.EQ. 0.) FZ=(EXPR-EXPT)*X/2. 003650
C      IF (V.NE. 0.) FZ=(EXPR-EXPT)*J1(XV)/V 003660
70      Q1=X*J0(XV) 003670
C      FX=Q1*EXPR-FZ 003680
C      FY=Q1*EXPT+FZ 003690
C      Q1=FW*FX 003700
C      YR(T)=REAL(Q1) 003710

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75	YI(Y)=AIMAG(QI)	003720
	QI=F*FY	003730
	ZP(Y)=REAL(QI)	003740
	ZI(Y)=AIMAG(QI)	003750
100	CONTINUE	003760
80	1 FJR=AT(5(1X,G12.5))	003770
	CALL DDG24R(0E0,1F0,YP,YRI)	003780
	CALL DDG24R(0E0,1F0,YI,YII)	003790
	CALL DDG24R(0E0,1F0,ZP,ZRI)	003800
	CALL DDG24R(0E0,1F0,ZI,ZII)	003810
85	IKIDK=CONST*(YRI*YRI+YII*YII+ZRI*ZRI+ZII*ZII)	003820
2000	RETURN	003830
	END	003840

B.3 Function PHI

1	FUNCTION PHI(X)	003850
	C IF SWT=.F. THEN PHIP(X)=C*S1R*F1(X)+4*S2R*F2(X) IS FOUND	003860
	C IF SWT=.T. THEN PHIT(X)=C*S1T*F1(X)+C*S2T*F2(X) IS FOUND	003870
	C WHERE C=B13*20*BETA/KAPDA (SEE CALLING SUBROUTINE)	003880
5	C THE PROGRAM IS DESIGNED TO BE CALLED IN THE ORDER .F., .T. FOR A	003890
	C GIVEN VALUE OF X IN ORDER TO ELIMINATE DOUBLE CALLS TO THE INTERPOLATI	003900
	C ROUTINE	003910
	C THE ARRAYS F1,F2 CONTAIN THE FUNCTION VALUES TO BE INTERPOLATED	003920
	C F1(1)=XS,F1(2)=XS+DX),....,F1(NF). ETC AS PROVIDED BY TEMPS.	003930
10	C THE IRLM SCI. SUB. ATSE (P. 251) RETURNS MINT FUNCTION VALUES AND	003940
	C ARGUMENTS TO BE USED FOR INTERPOLATION IN ARRAYS ARG.VAL RESPECTIVELY.	003950
	C GIVEN THE ARGUMENT X,ETC.	003960
	C (THE ARGUMENT ICOL IN ATSE IS 1 IF THE FUNCTION IS STORED IN A	003970
	C 1-DIMENSIONAL ARRAY)	003980
15	C THE IRLM SCI. SUB. ALI(P,241) DOES AITKEN-LAGRANGE INTERPOLATION	003990
	C ON (ARG.VAL) AND RETURNS THE RESULTING VALUE Y. EPS IS AN ABSOLUTE	004000
	C ERROR FIGURE AND IER IS AN ERROR FLAG.	004010
	COMMON/PHIRLK/CS1P,CS2P,CS1T,CS2T,XS,DX,NF,MINT,EPS,F1(200),	004020
	*F2(200),HOLD,A,KE,TLAST,TNEXT,IERR,IP,MPI,ISW,N,	004030
20	*RAD,NP1,C3,C1	004040
	C HOLD IS USED TO STORE PHIT(.T.,X)	004050
	DIMENSION ARG(20),VAL(20)	004060
	1010 CALL ATSE(X,XS,DX,F1,NF,1,ARG,VAL,MINT)	004070
	CALL ALI(X,ARG,VAL,Y1,MINT,EPS,IER)	004080
25	CALL ATSE(X,XS,DX,F2,NF,1,ARG,VAL,MINT)	004090
	CALL ALI(X,ARG,VAL,Y2,MINT,EPS,IER)	004100
	PHI=CS1P*Y1+4E0*CS2P*Y2	004110
	HOLD=CS1T*Y1+4E0*CS2T*Y2	004120
30	2000 RETURN	004130
	END	004140

B.4 Function J0

1	REAL FUNCTION J0(X)	004150
	C 10 IS THE BESSEL FUNCTION OF THE FIRST KIND, ZEROth ORDER. SEE	004160
	C HANDBOOK OF MATHEMATICAL FUNCTIONS-AMS 55. FOR VALUES OF THE ARGUMENT	004170
	C 1=5 EQUATION 9.1.12 IS USED, OTHERWISE 9.4.3 IS USED.	004180
5	DIMENSION FACT(20)	004190
	DATA MT//	004200
	IF(X.GT.5.) GO TO 1	004210
	IF(X.NE.0) GO TO 2	004220
	MT=1	004230
10	FACT(1)=1.0	004240
	DO 3 I=2,20	004250
	FACT(I)=FACT(I-1)*FLOAT(I*1)	004260
	3 CONTINUE	004270
	DO 4 I=2,20	004280
15	FACT(I)=1.0/FACT(I)	004290
	4 CONTINUE	004300
	2 CONTINUE	004310
	ANSP=0.0	004320
	ANSN=0.0	004330
20	ARG=0.25*X*X	004340
	ARGH=ARG	004350
	DO 5 I=1,19,2	004360
	ANSN=ANSN+ARGU*FACT(I)	004370
	J=I.1	004380
25	ARGH=ARGH*ARG	004390
	ANSP=ANSP+ARGU*FACT(I)	004400
	ARGH=ARGH*ARG	004410
	5 CONTINUE	004420
	J0=1.0*(ANSP-ANSN)	004430
30	RETURN	004440
	1 CONTINUE	004450
	T0X=3.0/X	004460
	F7=.79789456-.0000077*T0X-.0055274*T0X**2-.00009512*T0X**3+	004470
	1.00137277*T0X**4-.00072805*T0X**5+.00014476*T0X**6	004480
35	THZ=X-.74539816-.04166397*T0X-.00003954*T0X**2+.00262573*T0X**3-	004490
	1.00154125*T0X**4-.00029933*T0X**5+.00013558*T0X**6	004500
	J0=FZ*COS(THZ)/SQRT(X)	004510
	RETURN	004520
	END	004530

B.5 Function J1

1	REAL FUNCTION J1(X)	004540
	C 11 IS THE BESSEL FUNCTION OF THE FIRST KIND, FIRST ORDER. SEE	004550
	C HANDBOOK OF MATHEMATICAL FUNCTIONS-AMS 55. FOR VALUES OF THE	004560
	C ARGUMENT 1=1 EQUATION 9.1.10 IS USED, OTHERWISE 9.4.4 IS USED.	004570
5	DIMENSION FACT(20)	004580
	DATA MT//	004590
	IF(X.GT.10.) GO TO 1	004600
	IF(X.NE.0) GO TO 2	004610
	MT=1	004620
10	FACT(1)=2.0	004630
	DO 3 I=2,20	004640
	FACT(I)=FACT(I-1)*FLOAT(I*(I+1))	004650
	3 CONTINUE	004660
	DO 4 I=1,20	004670
15	FACT(I)=1.0/FACT(I)	004680
	4 CONTINUE	004690
	2 CONTINUE	004700
	ANSP=0.0	004710
	ANSN=0.0	004720

	ARG=0.5*X	004730
	ARG=0.25*X*X	004740
	ARGH=ARG	004750
	DO I=1,19,2	004760
	ANSN=ANSN+ARGH*FACT(I)	004770
25	I=I+1	004780
	ARGH=ARGH*ARG	004790
	ANSN=ANSN+ARGH*FACT(I)	004800
	ARGH=ARGH*ARG	004810
	5 CONTINUE	004820
30	J1=ARGS*(1.0*(ANSN-ANSN))	004830
	RETURN	004840
	1 CONTINUE	004850
	TAX=3.0/Y	004860
	F1=7.7784456+.00000156*TAX+.01659667*TAX**2+.00017105*TAX**3	004870
35	I=.00249511*TAX**4+.00117653*TAX**5-.00020033*TAX**6	004880
	TH1=X-2.75619449+.12499612*TAX+.00005650*TAX**2-.00631870*TAX**3	004890
	I+.00074348*TAX**4+.00079824*TAX**5-.00029166*TAX**6	004900
	II=I*COS(TH1)/SQRT(X)	004910
	RETURN	004920
40	END	004930

B.6 Subroutine RTAPE3

	SUBROUTINE RTAPE3(T)	004940
	COMMON/PHIRLK/CS1,CS2P,CS1T,US2T,XS,DX,NF,MINT,EPS,F1(200),	004950
	*F2(200),HOLD,A,KF,TLAST,TNEXT,IERR,IP,MPI,ISW,N,	004960
	*RAI,NO1,C3,C1	004970
5	COMMON/FILES/IT3,IT4,IT5,IT6,IT7,IT8	004980
	DIMENSION F1M(82),F2M(82),F1P(82),F2P(82),RFIN(82),ZF1N(22),	004990
	*UF1P(82,22),UF1N(82,22)	005000
	DATA ISW/0/	005010
	C RTAPE3 CAN BE USED AS A GENERAL PURPOSE SUBROUTINE FOR LINEARLY	005020
	C INTERPOLATING FUNCTION VALUES BETWEEN RECORDS, I.E. ASSUME	005030
10	C RECORD N INCLUDES THE INFORMATION TN,F(1:TN),F(2:TN),.....	005040
	C AND RECORD N+1 INCLUDES TN+1,F(1:TN+1),F(2:TN+1),.....	005050
	C THEN IF TN=TN+1 IS GIVEN, THE QUANTITIES F(1:T),F(2:T),.....	005060
	C ARE RETURNED WHERE*	005070
15	C F(1:T)=F(1:TN)+C*(F(1:TN+1)-F(1:TN)); C=(T-TN)/(TN+1-TN), ETC.	005080
	C IT IS ASSUMED THAT THE PARAMETER I INCREASES WITH INCREASING RECORD	005090
	C NUMBER AND NO FILE REWINDS ARE PERMITTED, I.E. RTAPE3 SHOULD BE CALLED	005100
	C WITH INCREASING VALUES OF T ONLY.	005110
20	C RTAPE3 RECOGNIZES TWO ERROR CONDITIONS WHICH SHOULD BE CHECKED FOR IN	005120
	C THE CALLING PROGRAM. IF IERR=0 THEN NO ERROR HAS OCCURRED. IF IERR=1	005130
	C THEN THE TIME VALUE IS LESS THAN THE TIME VALUE OF THE PRECEDING CALL	005140
	C TO RTAPE3. IF IERR=2 THEN THE TIME VALUE IS GREATER THAN THE TIME VALUE	005150
	C ASSOCIATED WITH THE LAST INPUT RECORD.	005160
25	C THE PRESENT VERSION OF RTAPE3 EACH OUTPUT RECORD (FROM TEMP5) IS	005170
	C ASSUMED TO BE IN THE FORM*	005180
	C NF,TFIN,RFIN(82),ZF1N(22),UF1N(82,22),F1(82),F2(82)	005190
	C WHERE TFIN IS THE TIME VALUE AND F1(82),F2(82) ARE THE DESIRED	005200
	C FUNCTION VALUES CORRESPONDING TO TFIN.	005210
30	C RTAPE3 ALSO OUTPUTS THE DIMENSIONALIZED (AND LINEARLY INTERPOLATED	005220
	C IN TIME WINDOW TEMPERATURE FUNCTION IN A FORM SUITABLE FOR USE WITH	005230
	C DISPLAY, PROVIDED IPRINT=2.	005240
	IF IERR=0	005250
	TV=TFIN	005255
	IF (ISW) 1115,1100	005260
35	1100 ISW=1	005270
	READ(IT3) NG,TLAST,TFIN,ZFIN,UF1N,F1M,F2M	005280
	TT=TLAST	005290
	QMIN=ZF1N(1)*RAI	005300
	RMAX=ZF1N(MPI)*RAI	005310
40	IF (EOF(IT3)) 1110,1120	005320
	1110 IERR=2	005330
	GOTO 2000	005340
	1120 IF (T-TLAST) 1130,1140,1140	005350
	1130 IERR=1	005360

45	GOTO 2000	005370
	1140 READ(IT3) NG,TNEXT,RFIN,ZFIN,UFINP,F1P,F2P	005380
	1115 IF (T.LT. TT) GOTO 1010	005400
	1000 IFRD=1	005410
	GOTO 2000	005420
50	C IF T.EQ. LASTT THEN NOTHING MORE TO DO	005430
	1010 IF (T.EQ. TT) GOTO 2000	005440
	C IF T.LT. TNEXT THEN A READ IS NOT REQUIRED	005450
	IF (T.LT. TNEXT) GOTO 1040	005460
	1030 READ(IT3) NG,TLAST,RFIN,ZFIN,UFINM,F1M,F2M	005470
55	IF (EOF(IT3)) 1040,1050	005480
	1040 IFRD=2	005490
	GOTO 2000	005500
	1050 IF (T.LE. TLAST) GOTO 1080	005510
	READ(IT3) NG,TNEXT,RFIN,ZFIN,UFINP,F1P,F2P	005520
60	IF (EOF(IT3)) 1060,1070	005530
	1060 IFRD=2	005540
	GOTO 2000	005550
	1070 IF (T.LE. TNEXT) GOTO 1020	005560
	GOTO 1030	005570
65	1020 C=(T-TLAST)/(TNEXT-TLAST)	005580
	DO 100 I=1,MPI	005590
	F1(I)=F1M(I)+C*(F1P(I)-F1M(I))	005600
	F2(I)=F2M(I)+C*(F2P(I)-F2M(I))	005610
	100 CONTINUE	005620
70	GOTO(2000,120) IP	005630
	120 DO 130 I=1,NPI	005640
	UFINP(I)=ZFIN(I)	005650
	DO 140 J=1,MPI	005660
	RFIN(J)=C3*(UFINM(J,I)+C*(UFINP(J,I)-UFINM(J,I)))	005670
75	140 CONTINUE	005680
	WRITE(IT0) I,NPI,II,TM,MPI,RMTN,RMAX,(RFIN(J),J=1,MPI)	005690
	130 CONTINUE	005700
	GOTO 2000	005710
	1080 TTEMP=TLAST	005720
80	TLAST=TNEXT	005730
	TNEXT=TTEMP	005740
	DO 110 I=1,MPI	005750
	FT=F1M(I)	005760
	F1M(I)=F1P(I)	005770
85	F1P(I)=FT	005780
	FT=F2M(I)	005790
	F2M(I)=F2P(I)	005800
	F2P(I)=FT	005810
	110 CONTINUE	005820
90	GOTO(1020,150) IP	005830
	150 DO 160 I=1,NPI	005840
	DO 160 J=1,MPI	005850
	FT=UFINM(J,I)	005860
	UFINM(J,I)=UFINP(I,I)	005870
95	UFINP(I,I)=FT	005880
	160 CONTINUE	005890
	GOTO 1020	005900
	2000 TT=T	005910
	RETURN	005920
100	END	005930

B.7 Subroutine ALI

1	C	SUBROUTINE ALI(X,ARG,VAL,Y,NDIM,EPS,IER)	005940
	C	005950
5	C	SUBROUTINE ALI	005960
	C	PURPOSE	005970
	C	TO INTERPOLATE FUNCTION VALUE Y FOR A GIVEN ARGUMENT-VALUE	005980
	C	X USING A GIVEN TABLE (ARG,VAL) OF ARGUMENT AND FUNCTION	005990
10	C	VALUES.	006000
	C	USAGE	006010
	C	CALL ALI (X,ARG,VAL,Y,NDIM,EPS,IER)	006020
15	C	DESCRIPTION OF PARAMETERS	006030
	C	X - THE ARGUMENT VALUE SPECIFIED BY INPUT.	006040
	C	ARG - THE INPUT VECTOR (DIMENSION NDIM) OF ARGUMENT	006050
	C	VALUES OF THE TABLE (NOT DESTROYED).	006060
20	C	VAL - THE INPUT VECTOR (DIMENSION NDIM) OF FUNCTION	006070
	C	VALUES OF THE TABLE (DESTROYED).	006080
	C	Y - THE RESULTING INTERPOLATED FUNCTION VALUE.	006090
	C	NDIM - AN INPUT VALUE WHICH SPECIFIES THE NUMBER OF	006100
	C	POINTS IN TABLE (ARG,VAL).	006110
25	C	EPS - AN INPUT CONSTANT WHICH IS USED AS UPPER ROUND	006120
	C	FOR THE ABSOLUTE ERROR.	006130
	C	IER - A RESULTING ERROR PARAMETER.	006140
	C	REMARKS	006150
30	C	(1) TABLE (ARG,VAL) SHOULD REPRESENT A SINGLE-VALUED	006160
	C	FUNCTION AND SHOULD BE STORED IN SUCH A WAY, THAT THE	006170
	C	DISTANCES $ABS(ARG(I)-X)$ INCREASE WITH INCREASING	006180
	C	SUBSCRIPT I. TO GENERATE THIS ORDER IN TABLE (ARG,VAL),	006190
35	C	SUBROUTINES ATSG, AISM OR ATSE COULD BE USED IN A	006200
	C	PREVIOUS STAGE.	006210
	C	(2) NO ACTION RESIDES ERROR MESSAGE IN CASE NDIM LESS	006220
	C	THAN 1.	006230
40	C	(3) INTERPOLATION IS TERMINATED EITHER IF THE DIFFERENCE	006240
	C	BETWEEN TWO SUCCESSIVE INTERPOLATED VALUES IS	006250
	C	ABSOLUTELY LESS THAN TOLERANCE EPS, OR IF THE ABSOLUTE	006260
	C	VALUE OF THIS DIFFERENCE STOPS DIMINISHING, OR AFTER	006270
	C	(NDIM-1) STEPS. FURTHER IT IS TERMINATED IF THE	006280
45	C	PROCEDURE DISCOVERS TWO ARGUMENT VALUES IN VECTOR ARG	006290
	C	WHICH ARE IDENTICAL. DEPENDENT ON THESE FOUR CASES,	006300
	C	ERROR PARAMETER IER IS CODED IN THE FOLLOWING FORM	006310
	C	IER=0 - IT WAS POSSIBLE TO REACH THE REQUIRED	006320
	C	ACCURACY (NO ERROR).	006330
	C	IER=1 - IT WAS IMPOSSIBLE TO REACH THE REQUIRED	006340
	C	ACCURACY BECAUSE OF ROUNDING ERRORS.	006350
50	C	IER=2 - IT WAS IMPOSSIBLE TO CHECK ACCURACY BECAUSE	006360
	C	NDIM IS LESS THAN 2, OR THE REQUIRED ACCURACY	006370
	C	COULD NOT BE REACHED BY MEANS OF THE GIVEN	006380
	C	TABLE. NDIM SHOULD BE INCREASED.	006390
55	C	IER=3 - THE PROCEDURE DISCOVERED TWO ARGUMENT VALUES	006400
	C	IN VECTOR ARG WHICH ARE IDENTICAL.	006410
	C	SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED	006420
	C	NONE	006430
60	C	METHOD	006440
	C	INTERPOLATION IS DONE BY MEANS OF AITKENS SCHEME OF	006450
	C	LAGRANGE INTERPOLATION. ON RETURN Y CONTAINS AN INTERPOLATED	006460
	C	FUNCTION VALUE AT POINT X, WHICH IS IN THE SENSE OF REMARK	006470
65	C	(3) OPTIMAL WITH RESPECT TO GIVEN TABLE. FOR REFERENCE, SEE	006480
	C	F. R. HILDERRAND, INTRODUCTION TO NUMERICAL ANALYSIS,	006490
	C	MCGRAW-HILL, NEW YORK/TORONTO/LONDON, 1956, PP. 47-50.	006500
70	C	006510
	C	DIMENSION ARG(1),VAL(1)	006520
	C	IER=2	006530
	C		006540
	C		006550
	C		006560
	C		006570
	C		006580
	C		006590
	C		006600
	C		006610
	C		006620
	C		006630
	C		006640
	C		006650
	C		006660
	C		006670

75		DFLT2=0.	006680
		IF (NDIM-1) 9.7.1	006690
	C		006700
	C	START OF AITKEN-LOOP	006710
	1	DO 4 J=2,NDIM	006720
80		DFLT1=DFLT2	006730
		IFND=J-1	006740
		DO 2 I=1,IFND	006750
		H=ARG(I)-ARG(J)	006760
		IF (H) 2.13.2	006770
85	2	VAL(J)=(VAL(I)*(X-ARG(J))-VAL(J)*(X-ARG(I)))/H	006780
		DFLT2=ABS(VAL(J)-VAL(IFND))	006790
		IF (I=2) 6.6.3	006800
	3	IF (DFLT2-EPS) 10.10.4	006810
	4	IF (I=5) 6.5.5	006820
90	5	IF (DFLT2-DFLT1) 6.11.11	006830
	6	CONTINUE	006840
	C	END OF AITKEN-LOOP	006850
	C		006860
	7	J=NDIM	006870
95	8	Y=VAL(J)	006880
	9	RETURN	006890
	C		006900
	C	THERE IS SUFFICIENT ACCURACY WITHIN NDIM-1 ITERATION STEPS	006910
	10	IFR=0	006920
100		GOTO 8	006930
	C		006940
	C	TEST VALUE DELT2 STARTS OSCILLATING	006950
			006960
	11	IFR=1	006970
105	12	J=IFND	006980
		GOTO 8	006990
	C		007000
	C	THERE ARE TWO IDENTICAL ARGUMENT VALUES IN VECTOR ARG	007010
	13	IFR=3	007020
110		GOTO 12	007030
		END	007040

B.8 Subroutine ATSE

1		SUBROUTINE ATSE (X,ZS,DZ,F,IROW,ICOL,ARG,VAL,NDIM)	007050
	C		007060
	C	007070
	C		007080
5	C	SUBROUTINE ATSE	007090
			007100
	C		007110
	C	PURPOSE	007120
	C	NDIM POINTS OF A GIVEN TABLE WITH EQUIDISTANT ARGUMENTS ARE	007130
10	C	SELECTED AND ORDERED SUCH THAT	007140
	C	ABS(ARG(I)-Y).GE.ABS(ARG(J)-X) IF I.GT.J.	007150
	C		007160
	C	USAGE	007170
	C	CALL ATSE (X,ZS,DZ,F,IROW,ICOL,ARG,VAL,NDIM)	007180
15	C		007190
	C	DESCRIPTION OF PARAMETERS	007200
	C	X - THE SEARCH ARGUMENT.	007210
	C	ZS - THE STARTING VALUE OF ARGUMENTS.	007220
	C	DZ - THE INCREMENT OF ARGUMENT VALUES.	007230
20	C	F - IN CASE ICOL=1, F IS THE VECTOR OF FUNCTION VALUES	007240
	C	(DIMENSION IROW).	007250
	C	IN CASE ICOL=2, F IS AN IROW BY 2 MATRIX. THE FIRST	007260
	C	COLUMN SPECIFIES THE VECTOR OF FUNCTION VALUES AND	007270
	C	THE SECOND THE VECTOR OF DERIVATIVES.	007280
25	C	IROW - THE DIMENSION OF EACH COLUMN IN MATRIX F.	007290
	C	ICOL - THE NUMBER OF COLUMNS IN F (I.E. 1 OR 2).	007300
	C	ARG - THE RESULTING VECTOR OF SELECTED AND ORDERED	007310
	C	ARGUMENT VALUES (DIMENSION NDIM).	007320
	C	VAL - THE RESULTING VECTOR OF SELECTED FUNCTION VALUES	007330

30	C	(DIMENSION NDIM) IN CASE ICOL=1. IN CASE ICOL=2.	007340
	C	VAL IS THE VECTOR OF FUNCTION AND DERIVATIVE VALUES	007350
	C	(DIMENSION 2*NDIM) WHICH ARE STORED IN PATHS (I.E.	007360
	C	EACH FUNCTION VALUE IS FOLLOWED BY ITS DERIVATIVE	007370
	C	VALUE).	007380
35	C	NDIM - THE NUMBER OF POINTS WHICH MUST BE SELECTED OUT OF	007390
	C	THE GIVEN TABLE.	007400
	C		007410
	C	REMARKS	007420
	C	NO ACTION IN CASE IROW LESS THAN 1.	007430
40	C	IF INPUT VALUE NDIM IS GREATER THAN IROW, THE PROGRAM	007440
	C	SELECTS ONLY A MAXIMUM TABLE OF IROW POINTS. THEREFORE THE	007450
	C	USER OUGHT TO CHECK CORRESPONDENCE BETWEEN TABLE (ARG,VAL)	007460
	C	AND ITS DIMENSION BY COMPARISON OF NDIM AND IROW, IN ORDER	007470
	C	TO GET CORRECT RESULTS IN FURTHER WORK WITH TABLE (ARG,VAL).	007480
45	C	THIS TEST MAY BE DONE BEFORE OR AFTER CALLING	007490
	C	SUBROUTINE ATSF.	007500
	C		007510
	C	SUBROUTINE ATSF ESPECIALLY CAN BE USED FOR GENERATING THE	007520
	C	TABLE (ARG,VAL) NEEDED IN SUBROUTINES ALI, AMI, AND ACFI.	007530
50	C		007540
	C	SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED	007550
	C	NONE	007560
	C		007570
	C	METHOD	007580
55	C	SELECTION IS DONE BY COMPUTING THE SUBSCRIPT J OF THAT	007590
	C	ARGUMENT, WHICH IS NEXT TO X.	007600
	C	AFTERWARDS NEIGHBOURING ARGUMENT VALUES ARE TESTED AND	007610
	C	SELECTED IN THE ABOVE SENSE.	007620
60	C	007630
	C		007640
	C		007650
	C		007660
	C		007670
	C		007680
65	C	DIMENSION F(1),ARG(1),VAL(1)	007690
	C	IF(IROW-1)19,17,1	007700
	C	CASE DZ=0 IS CHECKED OUT	007710
	C	1 IF(DZ)2,17,2	007720
	C	2 N=NDIM	007730
70	C		007740
	C	IF N IS GREATER THAN IROW, N IS SET EQUAL TO IROW.	007750
	C	IF(N-IROW)4,4,3	007760
	C	3 N=IROW	007770
	C		007780
75	C	COMPUTATION OF STARTING SUBSCRIPT J.	007790
	C	4 J=(Y-ZS)/DZ+1.5	007800
	C	IF(J)5,5,6	007810
	C	5 J=1	007820
	C	6 IF(I-IROW)8,8,7	007830
80	C	7 J=IROW	007840
	C		007850
	C	GENERATION OF TABLE ARG,VAL IN CASE DZ.NE.0.	007860
	C	8 II=1	007870
	C	JL=	007880
85	C	JR=	007890
	C	DO 16 I=1,N	007900
	C		007910
	C	ARG(I)=75+FLOAT(II-1)*DZ	007920
	C	IF(ICOL=2)9,10,10	007930
90	C	9 VAL(I)=F(II)	007940
	C	GOTO 11	007950
	C	10 VAL(2*I-1)=F(II)	007960
	C	III=II+IROW	007970
	C	VAL(2*I)=F(III)	007980
95	C	11 IF(I-JR-IROW)12,15,12	007990
	C	12 IF(I-JL-1)13,14,13	008000
	C	13 IF((ARG(I)-X)*DZ)14,15,15	008010
	C	14 JR=JR+1	008020
	C	IF=IF+1	008030
100	C	GOTO 16	008040
	C	15 IL=IL+1	008050
	C	IF=IF-JL	008060
	C	16 CONTINUE	008070
	C	RETURN	008080

105	C	CASE NZ=^	008100
	C		008110
		17 ARG(1)=ZS	008120
		VAL(1)=F(1)	008130
		IF (ICOL=2) 19,19,19	008140
110		19 VAL(2)=F(2)	008150
		19 RETURN	008160
		END	

B.9 Subroutine DQG24A

1	C	SUBROUTINE DQG24A (XL,XU,FA)	008170
	C	008180
	C		008190
5	C	SUBROUTINE DQG24	008200
	C		008210
	C	PURPOSE	008220
	C	TO COMPUTE INTEGRAL(FCT(X), SUMMED OVER X FROM XL TO XU)	008230
	C		008240
	C		008250
10	C	USAGE	008260
	C	CALL DQG24 (XL,XU,FCT,Y)	008270
	C	PARAMETER FCT REQUIRES AN EXTERNAL STATEMENT	008280
	C		008290
	C	DESCRIPTION OF PARAMETERS	008300
15	C	XL - DOUBLE PRECISION LOWER BOUND OF THE INTERVAL.	008310
	C	XU - DOUBLE PRECISION UPPER BOUND OF THE INTERVAL.	008320
	C	FCT - THE NAME OF AN EXTERNAL DOUBLE PRECISION FUNCTION	008330
	C	SUBPROGRAM USED.	008340
	C	Y - THE RESULTING DOUBLE PRECISION INTEGRAL VALUE.	008350
20	C		008360
	C	REMARKS	008370
	C	NONE	008380
	C		008390
	C	SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED	008400
25	C	THE EXTERNAL DOUBLE PRECISION FUNCTION SUBPROGRAM FCT(X)	008410
	C	MUST BE FURNISHED BY THE USER.	008420
	C		008430
	C	METHOD	008440
	C	EVALUATION IS DONE BY MEANS OF 24-POINT GAUSS QUADRATURE	008450
30	C	FORMULA, WHICH INTEGRATES POLYNOMIALS UP TO DEGREE 47	008460
	C	EXACTLY. FOR REFERENCE, SEE	008470
	C	V.T.KRYLOV, APPROXIMATE CALCULATION OF INTEGRALS,	008480
	C	MACHILLAN, NEW YORK/LONDON, 1962, PP.100-111 AND 317-340.	008490
	C		008500
35	C	008510
	C		008520
	C		008530
	C		008540
	C		008550
40	C	DIMENSION FA(1)	008560
		FA=RD0*(XU-XL)	008570
		R=XU-XL	008580
		C=.4975916099985106900*R	008590
		FA(1)=A+C	008600
45		FA(2)=A-C	008610
		C=.4873642779856547500*R	008620
		FA(3)=A+C	008630
		FA(4)=A-C	008640
		C=.4691372760011663800*R	008650
50		FA(5)=A+C	008660
		FA(6)=A-C	008670
		C=.4432077635022005200*R	008680
		FA(7)=A+C	008690
		FA(8)=A-C	008700
55		C=.4100019929869514600*R	008710
		FA(9)=A+C	008720
		FA(10)=A-C	008730

	C=.7700620957892771900*R	008750
	XA(11)=A+C	008760
60	XA(12)=A-C	008770
	C=.7240468259684877900*R	008780
	XA(13)=A+C	008790
	XA(14)=A-C	008800
65	C=.7727117356944197700*R	008810
	XA(15)=A+C	008820
	XA(16)=A-C	008830
	C=.716894753813225700*R	008840
	XA(17)=A+C	008850
	XA(18)=A-C	008860
70	C=.7575213398480816000*R	008870
	XA(19)=A+C	008880
	XA(20)=A-C	008890
	C=.75559433736808150-1*R	008900
	XA(21)=A+C	008910
75	XA(22)=A-C	008920
	C=.720284464313028130-1*R	008930
	XA(23)=A+C	008940
	XA(24)=A-C	008950
80	RETURN	008960
	END	

B.10 Subroutine DQG24B

1	C	SUBROUTINE DQG24B(XI,XII,FCT,Y)	008970
	C	008980
	C		008990
5	C	SUBROUTINE DQG24	009000
	C		009010
	C	PURPOSE	009020
	C	TO COMPUTE INTEGRAL(FCT(X), SUMMED OVER X FROM XI TO XII)	009030
	C		009040
	C		009050
10	C	USAGE	009060
	C	CALL DQG24 (XI,XII,FCT,Y)	009070
	C	PARAMETER FCT REQUIRES AN EXTERNAL STATEMENT	009080
	C		009090
	C	DESCRIPTION OF PARAMETERS	009100
15	C	XI - DOUBLE PRECISION LOWER BOUND OF THE INTERVAL.	009110
	C	XII - DOUBLE PRECISION UPPER BOUND OF THE INTERVAL.	009120
	C	FCT - THE NAME OF AN EXTERNAL DOUBLE PRECISION FUNCTION	009130
	C	SUBPROGRAM USED.	009140
	C	Y - THE RESULTING DOUBLE PRECISION INTEGRAL VALUE.	009150
20	C		009160
	C	REMARKS	009170
	C	NONE	009180
	C		009190
	C	SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED	009200
25	C	THE EXTERNAL DOUBLE PRECISION FUNCTION SUBPROGRAM FCT(X)	009210
	C	MUST BE FURNISHED BY THE USER.	009220
	C		009230
	C	METHOD	009240
	C	EVALUATION IS DONE BY MEANS OF 24-POINT GAUSS QUADRATURE	009250
30	C	FORMULA, WHICH INTEGRATES POLYNOMIALS UP TO DEGREE 47	009260
	C	EXACTLY. FOR REFERENCE, SEE	009270
	C	V.I. KRYLOV, APPROXIMATE CALCULATION OF INTEGRALS,	009280
	C	MACMILLAN, NEW YORK/LONDON, 1962, PP.100-111 AND 337-340.	009290
	C		009300
35	C	009310
	C		009320
	C		009330
	C		009340
	C		009350
	C	DIMENSION FCT(1)	

40	C	R=XII-XL	009360
		I=1	009370
		Y=.617061489999350990-2*(FCT(I)+FCT(I+1))	009380
		I=I+2	009390
45		Y=Y+.142456943144469920-1*(FCT(I)+FCT(I+1))	009400
		I=I+2	009410
		Y=Y+.221387194087899030-1*(FCT(I)+FCT(I+1))	009420
		I=I+2	009430
		Y=Y+.296492924577189000-1*(FCT(I)+FCT(I+1))	009440
50		I=I+2	009450
		Y=Y+.366732407055401530-1*(FCT(I)+FCT(I+1))	009460
		I=I+2	009470
		Y=Y+.430050807659766380-1*(FCT(I)+FCT(I+1))	009480
		I=I+2	009490
55		Y=Y+.488993260520069440-1*(FCT(I)+FCT(I+1))	009500
		I=I+2	009510
		Y=Y+.537221350579828170-1*(FCT(I)+FCT(I+1))	009520
		I=I+2	009530
		Y=Y+.577528340268429010-1*(FCT(I)+FCT(I+1))	009540
60		I=I+2	009550
		Y=Y+.608752364619016960-1*(FCT(I)+FCT(I+1))	009560
		I=I+2	009570
		Y=Y+.62918728173414180-1*(FCT(I)+FCT(I+1))	009580
		I=I+2	009590
65		Y=Y*(Y+.639690976733760780-1*(FCT(I)+FCT(I+1)))	009600
		RETURN	009610
		END	009620
			009630

B.11 Function IKIRKP

1	C	REAL FUNCTION IKIRKP(U,V,T)	009640
	C	APRIL 11, 1974	009650
	C	THIS FUNCTION COMPUTES THE KIRKHOFF INTENSITY FUNCTION	009660
	C	ALONG THE U=0 AND/OR V=0 AXIS OF THE PLANE.	009670
5	C	SEE COMMENTS IN IKIRK AND COMPUTE FOR BACKGROUND INFO.	009680
	C	IT IS VALID ONLY FOR CONSTANT TEMPERATURE WINDOWS.	009690
		DIMENSION AA(10)	009700
		COMMON/FILES/IT3,IT4,IT5,IT6,IT7,IT8	009710
		COMMON/VECTOR/VV	009720
10		COMMON/PHIBLK/CS10,CS20,CS30,CS40,CS50,XS,NF,MNNT,EPP,F1(200),	009730
		*F2(200),HOLD,ALPHA,KF,TLAST,TNEXT,IERP,IP,MPI,ISW,NGAUSS,	009740
		*RAD,NP1,C3,C1	009750
		COMPLEX AJ00,CRH00,CTHETA0,A10,A20,A30,A40,A60,A70	009760
		REAL KE	009770
15		DATA (AA(T),T=1,10)/1.0,.9999999958,.49999999206,-.1666663019,	009780
		*.0416573475,-.0087013598,.0013298820,-.0001413161,0.0,0./	009790
		VV=V	009800
		CALL RTAE3(T)	009810
		IF (TERR.NE.0) GOTO 2000	009820
20		CTHETA0=CS10*F1(1)+.4.*CS20*F2(1)	009830
		CTHETA0=CTHETA0*KF	009840
		CRH00=CS10*F1(1)+.4.*CS20*F2(1)	009850
		CRH00=CRH00*KE	009860
25		AJ00=(0.,1.)	009870
		A20=CEXP(AJ00*CRH00)	009880
		A30=CEXP(AJ00*CTHETA0)	009890
		A10=A20-A30	009900
		A=- (ALPHA**2)	009910
30		IF (A .LT. -1000) GOTO 110	009920
		EXPA=EXP(A)	009930
		AS=.2*(A/(1.-EXPA))**2	009940
		GOTO 120	009950
110		EXPA=0.	
		AS=.2.*A*A	

35	120	R=U/2.	009960
		IF (V.EQ.0) GOTO 200	009970
		C=(ALPHA/V)**2	009980
		IF (H.EQ.0) GOTO 100	009990
	200	SINQ=SIN(R)	010000
40		COSQ=COS(R)	010010
		ASQ=A**2	010020
		BSQ=B**2	010030
		A4QREAL=.5*((EXPA*(A*COSB*B*SINB))-A)/(ASQ+BSQ)	010040
		A4QIMAG=-.5*((EXPA*(A*SINB-B*COSB))+B)/(ASQ+BSQ)	010050
45		A4Q=CMPLY(A4QREAL,A4QIMAG)	010060
		A6Q=A1Q/2.*A4Q	010070
		IKIRKP=A5*((CABS(A2Q*A4Q-A6Q))**2+(CABS(A3Q*A4Q+A6Q))**2)	010080
		RETURN	010090
	100	IF (-A.GT..693) GOTO 1000	010095
50		CALL COMPUTE(C,AA,FF1,FF2,IER)	010100
		IF (IER.EQ.2) GOTO 1000	010110
		A7Q=A1Q*FF2	010120
		IKIRKP=A5*((CABS(A2Q*FF1-A7Q))**2+(CABS(A3Q*FF1+A7Q))**2)	010130
		RETURN	010140
55	1000	WRITE (115,10)	010150
	10	FORMAT(/O ALPHA**2 IS OUT OF RANGE*)	010160
	2000	RETURN	010170
		END	010180

B.12 Subroutine COMPUTE

1		SUBROUTINE COMPUTE (C,AA,FU,F1,IER)	010190
	C	THIS SUBROUTINE RETURNS THE APPROXIMATION TO THE INTEGRAL	010200
	C	F0= (1/V)**2* INTEGRAL (Y*J0(Y)*F**(-CY**2))DY) OVER (0,V)	010210
	C	F1=(1/V)**2*INTEGRAL (J1(Y)*F**(-CY**2))DY) OVER (0,V) GIVEN BY	010220
5	C	F0=(1/V)**2*SUM(A(I)*(C**I)*(INTEGRAL(Y** (2I+1)*J0(Y)DY))) AND	010230
	C	F1=(1/V)**2*SUM(A(I)*(C**I)*(INTEGRAL(Y** (2I)*J1(Y)DY))) OVER(0,V)	010240
	C	FOR I=0,1,...,N	010250
	C	WHERE THE A(I) ARE GIVEN (FOR EXAMPLE) IN NBS 55 P. 71	010260
	C	NOTE THAT FOR THE	010270
10	C	APPROXIMATIONS TO BE VALID, 01=C(=.693	010280
		COMMON/VICTOR/V	010290
		DIMENSION AA(1)	010300
		REAL JI	010310
		IER=1	010320
15		I=0	010330
		F0=F1=0.	010340
	110	IF (A(I+1).EQ.0.) GOTO 2000	010350
		F0=F0+AA(I+1)*(C**I)*.JI(0+1)	010360
		F1=F1+AA(I+1)*(C**I)*.JI(1+1)	010370
20		I=I+1	010380
		GOTO 110	010390
	2000	F0=F0/V**2	010400
		F1=F1/V**2	010410
		RETURN	010420
25	1000	IER=2	010430
		RETURN	010440
		END	010450

B.13 Function JI

1	C	DEFN FUNCTION JI(T,N)	010460
		DEFN N1,N2	010470
		COMMON/VICTOR/V	010480
5	C	IF T=1, THEN THIS FUNCTION RETURNS	010490
	C	INTEGRAL((T**2N)JI(T)DT) OVER (0,V)	010500
	C	IF T=0, THEN THIS FUNCTION RETURNS	010510
	C	INTEGRAL((T**(2+1))JI(T)DT) OVER (0,V)	010520
	C	SEE LUKE,Y.L. "INTEGRALS OF BESSEL FUNCTIONS"	010530
10	C	MCGRAW HILL 1962 (P.51)	010540
	C	OR JBS 55 (P.489)	010550
		I1=T+1	010560
		GOTO (110,100) I1	010570
15		100 IF(N.NE.0) GOTO 120	010580
		JI=1.-BESJF(0)	010590
		RETURN	010600
		120 N1=N	010610
		JI=0.*BESJF(2)	010620
		EXP=2*N	010630
20		K21=2	010640
		GOTO 130	010650
		110 N1=(N+1)	010660
		JI=BESJF(1)	010670
		EXP=2*N+1	010680
25		K21=1	010690
		130 N1=N2=1	010700
		N2=N+2	010710
		140 N1=N1+1	010720
		IF(N1.EQ.0) GOTO 2000	010730
30		K21=K21+2	010740
		N1=N1*N1	010750
		N2=N2*N2	010760
		N2=N2+1	010770
		JI=JI+K21*N1/N2*BESJF(K21)	010780
35		GOTO 140	010790
	2000	JI=V**EXP/(N+1)*JI	010800
		RETURN	010810
		END	010820
			010830

B.14 Function BESJF

1	C	FUNCTION BESJF (M)	010840
		COMMON/VICTOR/V	010850
		COMMON/FILES/IT3,IT4,IT5,IT6,IT7,IT8	010860
5		N=M	010870
		D=.001	010880
		CALL RESJ(V,N,B,I,D,IER)	010890
		IER=IER+1	010900
10		GOTO (10,20,30,40,50) IER	010910
	10	BESJF=B.I	010920
		RETURN	010930
20		WRITE (IT5,200)	010940
20	200	FORMAT(* ORDER OF BES FUN NEG,PROGRAM STOP*)	010950
		GOTO 1000	010960
15		30 WRITE (IT5,300)	010970
	300	FORMAT(* ARG OF BES FUN NEG OR ZERO,PROGRAM STOP*)	010980
		GOTO 1000	010990
		40 WRITE (IT5,400)	011000
20	400	FORMAT(* ACCURACY OF BES FUN NOT OBTAINED,PROGRAM CONTINUES*)	011010
		GOTO 10	011020
		50 WRITE (IT5,500)	011030
25	500	FORMAT(* RANGE ERROR IN BES FUN. RANGE ADJUSTED*)	011040
		GOTO 10	011050
	1000	STOP	011060
		END	011070
			011080
			011090
			011100
			011110
			011120

B.15 Function BESJ

1	C	SHRROUTINE BESJ(X,N,R,I,D,IER)	011130
	C	011140
	C		011150
	C	SUBROUTINE BESJ	011160
5	C		011170
	C	PURPOSE	011180
	C	COMPUTE THE J BESSEL FUNCTION FOR A GIVEN ARGUMENT AND ORDER	011190
	C		011200
	C	USAGE	011210
10	C	CALL BESJ(X,N,R,I,D,IER)	011220
	C		011230
	C	DESCRIPTION OF PARAMETERS	011240
	C	X -THE ARGUMENT OF THE J BESSEL FUNCTION DESIRED	011250
	C	N -THE ORDER OF THE J BESSEL FUNCTION DESIRED	011260
15	C	RJ -THE RESULTANT J BESSEL FUNCTION	011270
	C	D -REQUIRED ACCURACY	011280
	C	IER-RESULTANT ERROR CODE WHERE	011290
	C	IER=0 NO ERROR	011300
	C	IER=1 N IS NEGATIVE	011310
20	C	IER=2 X IS NEGATIVE OR ZERO	011320
	C	IER=3 REQUIRED ACCURACY NOT OBTAINED	011330
	C	IER=4 RANGE OF N COMPARED TO X NOT CORRECT (SEE REMARKS)	011340
	C		011350
	C	REMARKS	011360
25	C	N MUST BE GREATER THAN OR EQUAL TO ZERO, BUT IT MUST BE	011370
	C	LESS THAN	011380
	C	20+10*X-X** 2/3 FOR X LESS THAN OR EQUAL TO 15	011390
	C	90+X/2 FOR X GREATER THAN 15	011400
	C		011410
30	C	SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED	011420
	C	NONE	011430
	C		011440
	C	METHOD	011450
35	C	RECURRENCE RELATION TECHNIQUE DESCRIBED BY H. GOLDSTEIN AND	011460
	C	R.M. THALER,"RECURRENCE TECHNIQUES FOR THE CALCULATION OF	011470
	C	BESSEL FUNCTIONS",M.T.A.C.,V.13,PP.102-108 AND I.A. STEGUN	011480
	C	AND M. ABRAKOWITZ,"GENERATION OF BESSEL FUNCTIONS ON HIGH	011490
	C	SPEED COMPUTERS",M.T.A.C.,V.11,1957,PP.255-257	011500
	C		011510
40	C	011520
	C		011530
	C		011540
	C	RJ=.0	011550
	C	IF (N)10,20,20	011560
45	C	10 IER=1	011570
	C	RETURN	011580
	C	20 IF (X)30,30,31	011590
	C	30 IER=2	011600
	C	RETURN	011610
50	C	31 IF (X-15.)32,32,34	011620
	C	32 NTEST=20.+10.*X-X** 2/3	011630
	C	GO TO 36	011640
	C	34 NTEST=90.+X/2.	011650
	C	36 IF (N-NTEST)40,38,38	011660
55	C	38 IER=4	011670
	C	N=NTEST-1	011680
	C	GO TO 41	011690
	C	40 IER=0	011700
	C	41 N1=N+1	011710
60	C	DORECV=.0	011720
	C		011730
	C	COMPUTE STARTING VALUE OF M	011740
	C		011750
	C	IF (Y-5.)50,60,60	011760
65	C	50 MA=Y+6.	011770
	C	GO TO 70	011780
	C	60 MA=1.4*X+60./X	011790
	C	70 MA=N*(FIX(X)/4+2	011800
	C	MZERO=MAX(0,(MA-M))	011810
70	C		011820
	C	SET UPPER LIMIT OF M	011830
	C		011840
	C	MMA=NTEST	011850
100	C	DO 190 M=MZERO,MMA,X,3	011860

75	C	SET F(M),F(M-1)	011870
	C		011880
		FM1=1.0F-28	011890
		FM=0	011900
80		ALPHA=.9	011910
		IF(N=(M/2)*2)120,110,120	011920
	110	IT=-1	011930
		GO TO 130	011940
	120	IT=1	011950
85	130	M2=N-2	011960
		DO 160 K=1,M2	011970
		MKV=K	011980
		RMK=2.*F1/0AT(MK)*FM1/X-FM	011990
		FM=FM1	012000
90		FM1=RMK	012010
		IF(MK=N-1)150,140,150	012020
	140	R1=RMK	012030
	150	IT=-JT	012040
		S=1.JT	012050
95		S=1.JT	012060
	160	ALPHA=ALPHA+RMK*S	012070
		RMK=2.*FM1/X-FM	012080
		IF(N)180,170,180	012090
	170	R1=RMK	012100
100	180	ALPHA=ALPHA+RMK	012110
		R1=R1/ALPHA	012120
		IF(ABS(R1-APREV)-ABS(D*BJ))200,200,190	012130
	190	APREV=R1	012140
		IFP=3	012150
105	200	RETURN	012160
		END	012170
			012180

B.16 Subroutine GETDATA

1		SUBROUTINE GETDATA(DATIN,NV,IIN,IOUT,IOUT2,IIN1,ISIZE	012190
		*,ISIZE1,INDIC)	012200
		C THE MAIN PURPOSE OF THIS SUBROUTINE IS TO INPUT CHARACTER STRING OR	012210
		C NUMERICAL DATA IN A CONVERSATIONAL MODE I.E. FOR INPUTTING DATA	012220
5		C TO PROGRAMS BEING RUN UNDER INTERCOM.	012230
		C IT ALSO MAY BE USED FOR BATCH PROCESSING- IN WHICH CASE THE DATA	012240
		C SHOULD APPEAR 6 VALUES TO A CARD. DATA WHICH IS NOT TO BE CHANGED	012250
		C SHOULD BE REPLACED BY BLANKS. FOR BATCH ALL OR SOME OF THE DATA MAY	012260
		C BE DEFAULTED BY USING AN EOR AFTER THE LAST DATA TO BE INPUTTED.	012270
10		C THE SUBROUTINE ASSUMES THAT DEFAULT VALUES HAVE BEEN ASSIGNED	012280
		C AND WILL PRINT OUT THESE DEFAULT VALUES BEFORE ASKING FOR DATA INPUT.	012290
		C IT ASKS FOR NEW VALUES BY PRINTING OUT THE NAMES OF THE DATA AND THEN	012300
		C SKIPPING A LINE. VALUES TO BE ASSIGNED TO THE NAMES SHOULD BE	012310
		C ENTERED STARTING IN THE SAME COLUMN AS THE START OF THE NAME.	012320
15		C EACH DATUM IS ASSIGNED 10 COLUMNS AND UP TO 6 ITEMS MAY BE INPUTTED	012330
		C IN A SINGLES ROW.	012340
		C ARGUMENTS*****	012350
		C DATIN (DIMENSION (NV,7) WHERE NV IS THE TOTAL # OF DATA	012360
20		C TO BE INPUTTED)	012370
		C DATIN HOLDS THE FOLLOWING INFORMATION ABOUT EACH DATUM-	012380
		C NAME,VALUE,CODE WHERE-	012390
		C NAME => NAME BY WHICH THE DATUM IS IDENTIFIED TO THE USER (IT MAY OR	012400
		C MAY NOT BE EQUAL TO THE FORTRAN VARIABLE NAME TO BE ASSIGNED TO THE	012410
		C DATUM.)	012420
25		C VALUE => NUMERICAL OR CHARACTER STRING VALUE TO BE ASSIGNED (THE DATUM)	012430
		C CODE => HOW THE DATUM IS TO BE INTERPRETED	012440
		C -1 => CHARACTER STRING	012450
		C 0 => INTEGER	012460
		C 1 => FLOATING POINT NUMBER	012470
30		C NV TOTAL NUMBER OF DATUM TO BE INPUTTED	012480
		C IIN FILE NO. FOR INPUTTING	012490
		C IOUT1 PRIMARY OUTPUT FILE	012500
		C IOUT2 SECONDARY OUTPUT FILE	012510
		C ISIZE => SIZE OF FIRST DIMENSION OF DATIN	012520

35	DIMENSION DATAIN(151271),IA(6)	012530
	COMMON/SENSE/IIINNN,IOUTNN,INDICC	012540
	INTEGER DATAIN,=	012550
	EXTERNAL SWITCH	012560
	CALL ERRSET(KOUNT,21000)	012570
40	KOUNT=KOUNT	012580
	IF (INDIC.NE.0) 200,210	012590
200	ISW=2	012600
	LL=	012610
	L=INDIC-1	012620
45	GOTO 1055	012630
210	CONTINUE	012640
	ISW=1	012650
	IOIN=0000000000000100053B	012660
	IIINNN=IIIN	012670
50	IOUTNN=IOUT1	012680
	IOUT=IOUT1	012690
	ISW=1	012700
	IRANK=1-4	012710
	CALL SWITCH(IIIN,ISW,10HREAD DATA,SHFILE-),RETURNS(1060)	012720
55	IF (ISW3.EQ.1) 1310,1290	012730
1300	WRITE (IOUT1,17) IIN	012740
	REWIND IIN	012750
	READ (IIN) DATAIN	012760
	REWIND IIN	012770
60	IF (EOF(IIN)) 1400,1290	012780
1400	WRITE (IOUT1,24) IIN	012790
1290	CONTINUE	012800
	CALL SWITCH(0,ISW,1ANDFFAULTS L,SHISTED),RETURNS(1060)	012810
	IF (ISW4.NE.1) GOTO 1150	012820
65	WRITE (IOUT1,1)	012830
1140	DO 110 I=1,NV	012840
	II=ISIZE+I	012850
	II=I	012860
	II2=II+ISIZE	012870
70	IF (DATAIN(II2)) 1020,1030,1040	012880
1020	WRITE (IOUT1,2) DATAIN(II),DATAIN(II1)	012890
	GOTO 110	012900
1030	WRITE (IOUT1,3) DATAIN(II),DATAIN(II1)	012910
	GOTO 110	012920
75	1040 WRITE (IOUT1,4) DATAIN(II),DATAIN(II1)	012930
	CONTINUE	012940
	GOTO (1150,1130) ISW	012950
	1150 CALL SWITCH(0,ISW,1CHNAME-VALUE,SH MODE),RETURNS(1060)	012960
	IF (ISW5.EQ.1) 1270,1050	012970
80	1050 L=1	012980
	ISW=2	012990
	LL=	013000
	1055 L=L+LL	013010
	IF (L.GT. NV) GOTO 1060	013020
85	1060 WRITE (IOUT1,18) DATAIN(ISIZE*L)	013030
	LL=1	013040
	DO 100 J=1,6	013050
	IA(J)=104	013060
90	100 CONTINUE	013070
	READ (IIN,10) (IA(J),J=1,6)	013080
	IF (EOF(IIN)) 1320,1070	013090
	1320 INDICC=1	013100
	GOTO 1060	013110
95	1070 IF (IA(1).EQ. IRANK) GOTO 1055	013120
	DO 180 J=1,6	013130
	DO 180 K=1,10	013140
	IF (MXGETX(IA(J),K,1).EQ. 1000) GOTO 1270	013150
100	180 CONTINUE	013160
	DO 190 J=1,6	013170
	JP=L+J-1	013180
	F=DATAIN(JP+2*ISIZE)	013190
	IF (F) 1000,1100,1110	013200
105	1090 IF (IA(J).NE. IRANK) DECODE(10,11,IA(J)) DATAIN(JR)	013210
	GOTO 1080	013220
	1100 CALL RJUST(IA(J))	013230
	IF (IA(J).NE. IRANK) DECODE(10,12,IA(J)) DATAIN(JR)	013240
	GOTO 1080	013250
	1110 CALL RJUST(IA(J))	013255
	IF (IA(J).NE. IRANK) DECODE(10,13,IA(J)) DATAIN(JR)	013260
110	GOTO 1080	013270
	100 CONTINUE	013280
	1080 LL=1	013290
	IF (INDIC.NE.0) LL=1000	013300
	IF (KOUNT.EQ. KOUNT1) GOTO 1055	013310

115	KOUNT1=KOUNT	013320
	WRITE(IOUT1,25)	013330
1270	WRITE(IOUT1,23)	013340
1250	WRITE(IOUT1,8)	013350
	DO 150 I=1,6	013360
120	IA(I)=104	013370
150	CONTINUE	013380
	READ(IIN,10) (IA(I),I=1,6)	013390
	IF (EOF(IIN)) 1330,1085	013400
1330	INDICC=1	013410
125	GOTO 1060	013420
1085	II=IA(1)	013430
	IF (II.EQ. 1BLANK) GOTO 1060	013440
	DO 130 I=1,NV	013450
	J=1-ISIZE	013460
130	IF (II.EQ. DATAIN(I)) GOTO 1160	013470
130	CONTINUE	013480
	WRITE(IOUT1,16)	013490
	GOTO 1270	013500
1160	F=DATAIN(J+ISIZE)	013510
135	JJ=J-ISIZE	013520
	IF (F) 1170,1180,1190	013530
1170	DO 160 I=2,6	013540
	IF (IA(I).EQ. 1BLANK) GOTO 1240	013550
	DECODE(11,11,IA(I)) DATAIN(JJ,I-2)	013560
140	CONTINUE	013570
	GOTO 1240	013580
1180	CALL RJUST(IA(2))	013590
	DECODE(11,12,IA(2)) DATAIN(JJ)	013600
	GOTO 1240	013610
145	1190 CALL RJUST(IA(2))	013615
	DECODE(11,13,IA(2)) DATAIN(JJ)	013620
1240	IF (KOUNT.EQ. KOUNT1) GOTO (1250,1310) ISW	013630
	KOUNT1=KOUNT	013640
150	WRITE(IOUT1,25)	013650
	GOTO 1250	013660
1460	WRITE(IOUT1,14)	013670
	IF (IOUT2.EQ. 0) GOTO 1130	013680
	WRITE(IOUT2,15)	013690
	IOUT=IOUT2	013700
155	ISN=2	013710
	GOTO 1140	013720
1130	INDIC=INDICC	013730
	RETURN	013740
1	FORMAT(/,* THE DEFAULT INPUT DATA ARE*)	013750
2	FORMAT(1X,A10,*,*,*,A10,*,*)	013760
3	FORMAT(1X,A10,*,*,*,110)	013770
4	FORMAT(1X,A10,*,*,*,G16,6)	013780
5	FORMAT(///)	013790
6	FORMAT(/,* ENTER DATA. START IN COL. BENEATH START OF NAME*)	013800
7	FORMAT(8X,6A10)	013810
8	FORMAT(8X)	013820
10	FORMAT(6A10)	013830
11	FORMAT(A10)	013840
12	FORMAT(I10)	013850
13	FORMAT(F10,0)	013860
14	FORMAT(/,* DATA INPUT COMPLETE*)	013870
15	FORMAT(/,* THE INPUT DATA VALUES ARE*,/)	013880
16	FORMAT(1X,* TRY AGAIN*)	013890
17	FORMAT(/,1X,* READING DATA FROM *,15)	013900
18	FORMAT(1X,A10,*,*)	013910
23	FORMAT(8X,*NAME VALUE*,*,*,*)	013920
24	FORMAT(1X,* FILE*,15,* IS EMPTY*)	013930
25	FORMAT(1X,* WRONG DATA TYPE-TRY AGAIN*)	013940
	END	013950

B.17 Subroutine PRT

1	SUBROUTINE PRT(RUF,MODE,II,IT,MP,NP,MSKIP,NSKIP,RHOP1,	015000
	*DELPHO,VMIN,DELV,XIT,U,TR,T,T16)	015010
	DIMENSION R(100),RUF(1),D(2)	015020
	DATA ITT/0/	015030
5	IF (ITT.EQ. IT) GOTO 100	015040
	WRITE(ITA,1) TR,T	015050
	DO 130 I=1,MP,MSKIP	015060
	GOTO (110,120) MODE	015070
10	110 R(I)=RHOP1+DELPHO*(I-1)	015080
	GOTO 130	015090
	120 R(I)=VMIN+DELV*(I-1)	015100
	130 CONTINUE	015110
	GOTO (170,180) MODE	015120
15	170 WRITE(ITA,2) (R(I),I=1,MP,MSKIP)	015130
	GOTO 100	015140
	180 WRITE(ITA,3) (R(I),I=1,MP,MSKIP)	015150
	100 GOTO (140,150) MODE	015160
	140 ENCODE(20,4,D) XIT	015170
	GOTO 160	015180
20	150 ENCODE(20,5,D) U	015190
	160 IF (MOD(IT-1,NSKIP).EQ. 0) WRITE(ITA,6) D,	015200
	* (RUF(J), J=1,MP,MSKIP)	015205
	ITT=IT	015210
	1000 RETURN	015220
25	1 FORMAT(// * TIME (SECONDS) = *G12.4* TAU= *G12.4/	015230
	-----)	015240
	2 FORMAT(// * INTENSITIES EVALUATED AT RHO-PRIME=*/(5X,5G13.5))	015250
	3 FORMAT(// * INTENSITIES EVALUATED AT V=*/(5X,5G13.5))	015260
	4 FORMAT(* X= *G13.5)	015270
30	5 FORMAT(* U= *G13.5)	015280
	6 FORMAT(//2A10/(5X,5G13.5))	015290
	END	015300

Appendix C

The Evaluation of $I'(u,0,t)$ and $I'(0,v,t)$ Used in the IKIRKP Option

1. INTRODUCTION

Consider the circumstance when the temperature distribution is constant throughout the window but is a function of time only, viz, $w(t)$. Then, returning to Eq. (16), Volume I, we see that:

$$F1(\rho, t) = \int_{\xi_1}^{\xi_2} w(t) d\xi = (\xi_2 - \xi_1) w(t) = w(t) L/a = F1(t).$$

In a similar fashion, Eq. (17), Volume I, becomes:

$$F2(\rho, t) = \rho^{-2} \int_0^{\rho} d\rho \rho L w(t)/a = L w(t)/2a = F2(t).$$

Equation (18), Volume I, simplifies to:

$$\begin{aligned} \Phi^Y(\rho, t) &= a\Delta T_c \left[S_1^Y w(t) L/a + 4 S_2^Y w(t) L/2a \right] \\ &= L w(t) \Delta T_c \left[S_1^Y + 2 S_2^Y \right] \equiv d^Y(t). \end{aligned}$$

2. EVALUATION OF $I'(u, 0, t)$

For the condition $v = 0$ and u arbitrary, then $J_0(0)=1$ and $\lim_{v \rightarrow 0} J_1(\rho v)/\rho v = 1/2$. Equations (25-27), Volume I, reduce to:

$$f_z(\rho, 0, t) = \rho [\exp(ikd^0) - \exp(ikd^\theta)] / 2 \equiv \rho A_1(t)/2,$$

$$f_x(\rho, 0, t) = \rho \exp(ikd^0) - f_z \equiv \rho A_2(t) - \rho A_1(t)/2,$$

$$f_y(\rho, 0, t) = \rho \exp(ikd^\theta) + f_z \equiv \rho A_3(t) + \rho A_1(t)/2.$$

Then, from Eq. (23), Volume I,

$$\begin{aligned} I'(u, 0, t) &= 2\alpha^4 (1 - \exp(-\alpha^2))^{-2} \left\{ \left| \int_0^1 \exp(-\alpha^2 \rho^2) \exp(-i u \rho^2 / 2) (\rho A_2 - \rho A_1 / 2) d\rho \right|^2 \right. \\ &\quad \left. + \left| \int_0^1 \exp(-\alpha^2 \rho^2) \exp(-i u \rho^2 / 2) (\rho A_3 + \rho A_1 / 2) d\rho \right|^2 \right\}. \end{aligned}$$

$$I'(u, 0, t) = 2\alpha^4 (1 - \exp(-\alpha^2))^{-2} \left\{ \left| (A_2 - A_1/2) \int_0^1 \rho \exp(-\alpha^2 \rho^2) \exp(-i u \rho^2/2) d\rho \right|^2 \right. \\ \left. + \left| (A_3 + A_1/2) \int_0^1 \rho \exp(-\alpha^2 \rho^2) \exp(-i u \rho^2/2) d\rho \right|^2 \right\}.$$

Expressing the integral in terms of sin and cos, we find:

$$\int_0^1 \rho \exp(-\alpha^2 \rho^2) \exp(-i u \rho^2/2) d\rho = \int_0^1 \rho \exp(-\alpha^2 \rho^2) \cos(u \rho^2/2) d\rho \\ - i \int_0^1 \rho \exp(-\alpha^2 \rho^2) \sin(u \rho^2/2) d\rho.$$

Let $a = -\alpha^2$, $b = u/2$ and $y = \rho^2$, to get:

$$\frac{1}{2} \int_0^1 e^{ay} \cos by dy - \frac{i}{2} \int_0^1 e^{ay} \sin by dy = \frac{1}{2} \left\{ \frac{e^a (a \cos b + b \sin b) - a}{a^2 + b^2} \right\} - \\ \frac{i}{2} \left\{ \frac{e^a (a \sin b - b \cos b) + b}{a^2 + b^2} \right\} \equiv A_4.$$

Thus, we get the final result:

$$I'(u, 0, t) = 2\alpha^4 (1 - \exp(-\alpha^2))^{-2} \left\{ \left| (A_2 - A_1/2) A_4 \right|^2 + \left| (A_3 + A_1/2) A_4 \right|^2 \right\}.$$

3. EVALUATION OF $I'(0, v, t)$

Consider when $u = 0$ and v is arbitrary. Then,

$$f_w(\rho) = \exp(-\alpha^2 \rho^2)$$

$$f_z(\rho, v, t) = v^{-1} J_1(\rho v) A_1(t)$$

$$f_x(\rho, v, t) = \rho J_0(\rho v) A_2(t) - f_z$$

$$f_y(\rho, v, t) = \rho J_0(\rho v) A_3(t) + f_z.$$

Inserting these functions into Eq. (23), Volume I, the integral terms become:

$$\begin{aligned} & \left| A_2 \int_0^1 \rho J_0(\rho v) \exp(-\alpha^2 \rho^2) d\rho - A_1 v^{-1} \int_0^1 J_1(\rho v) \exp(-\alpha^2 \rho^2) d\rho \right|^2 \\ & + \left| A_3 \int_0^1 \rho J_0(\rho v) \exp(-\alpha^2 \rho^2) d\rho + A_1 v^{-1} \int_0^1 J_1(\rho v) \exp(-\alpha^2 \rho^2) d\rho \right|^2. \end{aligned}$$

Thus, the integrals to consider are:

$$\int_0^1 \rho J_0(\rho v) \exp(-\alpha^2 \rho^2) d\rho ; \quad v^{-1} \int_0^1 J_1(\rho v) \exp(-\alpha^2 \rho^2) d\rho$$

Let $y = \rho v$ and obtain:

$$v^{-2} \int_0^v y J_0(y) \exp(-\alpha^2 y^2/v^2) dy; \quad v^{-2} \int_0^v J_1(y) \exp(-\alpha^2 y^2/v^2) dy.$$

In order to perform these integrations, consider a polynomial approximation to $\exp(-\alpha^2 y^2/v^2)$. On p. 71 of Abramowitz and Stegun,¹ various approximations to e^{-x} are given, valid for the domain $0 \leq x \leq 0.693$. They all have the generic form: $e^{-x} = 1 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$. Since $\alpha^2 y^2/v^2$ is a maximum at $y = v$ (where $\rho = 1$) for any value of v , we get the condition that $0 \leq \alpha^2 \leq 0.693$. Using the polynomial approximations mentioned above, the typical n -th term from each of the above two integrals will have the form:

$$a_n \alpha^{2n} v^{-(2n+2)} \int_0^v y^{2n+1} J_0(y) dy; \quad a_n \alpha^{2n} v^{-(2n+2)} \int_0^v y^{2n} J_1(y) dy.$$

On p. 480 of Abramowitz and Stegun¹ or p. 51 of Luke,² we find:

$$J_{i_0}^{2n+1}(v) \equiv \int_0^v y^{2n+1} J_0(y) dy = \frac{v^{2n+1}}{n+1} \sum_{k=0}^{\infty} \frac{(2k+1)(-n)_k}{(n+2)_k} J_{2k+1}(v)$$

1. Abramowitz, M., and Stegun, I. A., Editors (1964) Handbook of Mathematical Functions, National Bureau of Standards, Washington, D. C.
2. Luke, Y. L. (1962) Integrals of Bessel Functions, McGraw-Hill Co., New York.

$$J_{i1}^n(v) \equiv \int_0^v y^n J_1(y) dy = \frac{v^{2n}}{n+1} \sum_{k=0} \frac{(2k+2)(1-n)_k}{(n+2)_k} J_{2k+2}(v) \quad (n \neq 0)$$

and

$$\int_0^v J_1(y) dy = 1 - J_0(v)$$

where:

$$(a)_0 = 1$$

$$(a)_k = a \cdot (a+1) \cdot (a+2) \dots (a+k-1)$$

Since $(-n)_k = 0$ for $k = n+1$ and $(1-n)_k = 0$ for $k = n$, the series terminates.

The above results have been coded in a function subroutine JI (i, n) which returns $J_{i0}^{2n+1}(v)$ if $i = 0$ and $J_{i1}^n(v)$ if $i = 1$. It uses the IBM Scientific Subroutine BESJ to compute the $J_{2k+1}(v)$ and $J_{2k+2}(v)$.

Appendix D

**Fortran Listings for the Main Programs in the Alternate TIKIRK
Package Containing All Three Options**

D.1 Modified Main Program TIKIRK

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75 C STATEMENT SUCH THAT IT3 => TAPE3, ETC. THIS TO CHANGE THE
C ASSOCIATION IT IS NECESSARY TO CHANGE EITHER OR BOTH THE DATA AND
C PROGRAM STATEMENTS.
C THESE FILES SERVE THE FOLLOWING PURPOSES:
C IT3 => FILE OUTPUTTED BY PROGRAM TEMPS
80 C IT4 => @INTERACTIVE@ INPUT FILE (SEE GETDATA)
C IT5 => @INTERACTIVE@ OUTPUT FILE (SEE GETDATA)
C IT6 => LISTING OF ALL INPUT PARAMETERS AND DEBUG OUTPUT
C IT7 => UNFORMATTED INTENSITY VALUES. ALSO MAY BE USED TO INSERT
C IT8 => UNFORMATTED TEMPERATURE DISTRIBUTION VALUES
85 C SUITABLE FOR DISPLAY PURPOSES
C PREASSIGNED DATA IN CATEGORIES 2 AND 3
C IN ADDITION TO THE ABOVE FACTS, THE USER SHOULD BE AWARE OF TWO
C PROGRAM @CONSTANTS@. THE FIRST UNDER THE VARIABLE NAME NT IS THE NUM-
C BER OF TIME VALUES PERMITTED. AT PRESENT THIS IS SET TO 10; (THE
90 C DIMENSION OF THE TIME ARRAY TIM). ALSO NOTE THAT ALL THE TIME
C D-Fault VALUES ARE ZERO EXCEPT THE FIRST AND THAT THE PROGRAM STOPS
C AS SOON AS A SUCCEEDING TIME VALUE IS LESS THAN THE PRECEDING
C TIME VALUE.
C THE SECOND @CONSTANT@ HAS TO DO WITH THE SIZE OF THE RECORD OUTPUTTED
95 C BY TEMPS. THE SUBROUTINE RTAPE3 READS THE TEMPS OUTPUT UNDER THE
C ASSUMPTION THAT ALL @AXIAL@ ARRAYS ARE OF DIMENSION 82 AND @AXIAL@
C ARRAYS ARE OF DIMENSION 22. SEE COMMENTS WITHIN SUBROUTINE RTAPE3.
C THE INTENSITY FUNCTION TKIRK IS DEFINED EXPLICITLY AS A FUNCTION OF
C THE NONDIMENSIONAL VARIABLES U AND V AND IMPLICITLY AS A FUNCTION
100 C OF NON-DIMENSIONAL TIME TAU THROUGH THE TIME DEPENDANT FUNCTIONS
C PHI-THETA AND PHI-RHO AS DEFINED IN THE ABOVE REFERENCE. THESE
C VARIABLES ARE PASSED THROUGH AN ARGUMENT LIST. ALL @PARAMETERS@
C REQUIRED FOR EVALUATION OF TKIRK ARE PASSED THROUGH BLOCK COMMON
C @PHIRLK. THESE PARAMETERS ARE:
105 C CS1P => C*SIIP (SEE TKIRK COMMENTS)
C CS2P => C*SI2P "
C CS1T => C*SI1T "
C CS2T => C*SI2T "
C XS => STARTING ARGUMENT FOR FUNCTIONS F1,F2 (SEE FUNCTION
110 C PHI COMMENTS)
C DX => INTERVAL BETWEEN EQUID-SPACED ARGUMENTS OF F1,F2.
C NF => NUMBER OF VALUES OF F1,F2
C MNNT => MINT (SEE INPUT DATA)
C EPS1 => EPS1 "
115 C F1(200) => HOLDS VALUES OF F1 FROM TEMPS
C F2(200) => HOLDS VALUES OF F2 FROM TEMPS
C HOLD => STORES PHI-THETA (PHI-RHO AND PHI-THETA ARE EVALUATED
C SIMULTANEOUSLY)
C A => 1/SQRT(2)/SIG (=ALPHA IN THE ABOVE REFERENCE)
120 C KE => WAVE NUMBER
C TLAST => STORES TIME VALUE READ FROM TEMPS RECORD
C TNEXT => "
C IERR => ERROR INDICATOR FOR RTAPE3 (INDICATES OUT OF RANGE
C TIME OR OUT OF SEQUENCE TIME)
125 C IP => DEBUG OUTPUT @SWITCH@
C MPI => ENF
C ISW => SWITCH FOR GAUSSIAN INTEGRATION. WHEN ISW=1 THEN THE
C X-VALUES FOR GAUSSIAN INTEGRATION ARE FOUND.
C NGAUSS => NUMBER OF POINTS USED IN THE GAUSSIAN INTEGRATION
130 C (NOTE THAT IS NGAUSS IS CHANGED THEN THE GAUSSIAN INTEGRATION
C SUBROUTINE MUST ALSO BE CHANGED.)
C RAD => WINDOW RADIUS
C NPI => NUMBER OF TEMPERATURE SAMPLES IN AXIAL DIRECTION
C (USED FOR OUTPUTTING DISPLAY COMPATIBLE
135 C TEMPERATURE DATA)
C C1 => CONSTANT TO DIMENSIONALIZE TEMPERATURE DATA
C FOR DISPLAY
C C1 => CONSTANT USED TO DIMENSIONALIZE TIME FOR
140 C REFI K,TKIRK,LAMBDA,NX,KE
C REFI TKIPKP,IKIRK1
C LOGICAL S
C DIMENSION BUF(100)
C COMMON/FILES/IT3,IT4,IT5,IT6,IT7,IT8
C COMMON/PHIRLK/CS1P,CS2P,CS1T,CS2T,XS,DX,NF,MNNT,EPP,F1(200),
145 C F2(200),HOLD,A,KE,TLAST,TTNEXT,IERR,IP,MPI,ISW,NGAUSS,
C RAD,NPI,C1,C1,IERR,FERRRM
C INTEGER DATIN(100,3),DATIN1(100,3)
C COMMON/BLOCK2/X0,X1,X2,RHO1,RHO2,MP,NP,TIM(10),EPS1
C TEMPERATURE DISPLAY
150 C *MINT,IPONT,NGAUSS,MODE,UMIN,UMAX,VMIN,VMAX,DUM(20),MSKIP,NSKIP
C COMMON/BLOCK1/
C *T1,T2,T3,T4,T5,T6,T7,M,N,M1,N1,ICNT,IU,IQ,NQ,NM,TUN,
C *ICAD,IPONT,IPNCH,ITAP3,ITAP4,RHO1,RHO2,ZED1,ZED2,DFAU0,
C *TAU,X,TAUOFF,SIG,QQ,UQ, EPS,G1(4),H1(4),MATER,NX,META,

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155 *K,LAMBDA,SIR,SIT,S2P,S2T,
*DEN,CP,R,EXPER,PM,R1,Z1,R2,IPL0T,PROBNO,TICU,XLEN,YLEN,SCALEX,
*SCALEY1,SCALEY2,XTITLE(5),YTITLE1(5),YTITLE2(5),NAME
EQUVALENCE (11,DATAIN(1),XU,DATAIN(1))
DATA (DATAIN(1,1),I=1,92)/7*2,80,20,3*1,0,1,2,11,100,4,6,6,3,
160 *4,3,1,1,5546,1,1092,0035,5,5,1292,2*0,001,4*0,0,3*015,
*34KCL,1,47,4,8E-4,0653,10,6,7,34E-5,05E-5,1E-5,1E-5,1,98,
*491,1,278,1H1,24,7,41,1,1,1,4H7204,5,20,9,30,1,1,1,
*10HTIME (FCON,3HDC),3*1H,10HTEMP-DEGC,10H ABOVE AMB,
*3*1H,10HMEAN TEMP,10H ABOVE AMB,3*1H,7HBARRETT,
165 *10HADIAL DIS,10HTANCE,RHO-4H(CM),1H,1H,10HAXIAL DIST,
*10HANCE,7-1CM,1H,1H,1H /
DATA (DATAIN(1,2),I=1,92)/2HT1,2HT2,2HT3,2HT4,2HT5,
*2HT6,2HT7,1HM,1HN,2HMT,2HNT,4HICNT,2HTU,2HTG,2HNO,3HNM,
*4H1HJ,4H1CAPD,6HTP0INT,5H1PNC,5H1AP3,5H1AP4,4HRH01,
170 *5H0012,4H7E11,4H7E12,5HTAU0,5HTAUM,6HTAUOFF,3HSIG,
*2H0,2H13,3HPS,5HG1(1),5HG1(2),5HG1(3),5HG1(4),5H1(1),
*5H1(2),5H1(3),5H1(4),8HMATERIAL,8HDEF,IND,4HBETA,
*5HTEO,CAND,6HLMRDA,3HS1R,3HS1T,3HS2R,3HS2T,
*7HDEMSITY,9HSPCC,HEAT,6HRADIUS,5HEAPER,
175 *3HR16,2H718,3H2X,9HP1,T71Y,2N,6HPRROBNO,4HTICU,
*4H1EN,4HYLEN,7HYSCALE,8HY1-SCALE,8HY2-SCALE,6HXTITLE,
*1H2,1H3,1H4,1H5,7HYTITLE1,1H2,1H3,1H4,1H5,7HYTITLE2,1H2,
*1H3,1H4,1H5,9HOPEDATOR,
*3HXT1,3HXT2,3HXT3,3HXT4,3HXT5,3HYT1,3HYT2,3HYT3,3HYT4,
180 *3HYT5,
DATA (DATAIN(1,3),I=1,92)/22*0,19*1,-1,11*1,-1,1,4*0,
*-1,4*1,25*-1/
DATA (DATAIN(1,4),I=1,48)/1500,1000,2000,0,0,2,100,100,10,
185 *90,1,0,1,6,1,24,2,-40,0,0,0,10,
*10H1PKHFF,1,10HINTENSITY F,9HFUNCTION,1,1H,1H,10HTIME IN SE,
*5HCONDNS,1H,1H,1H,10HNON-DIMENS,10HTONAL RAD,10HAL DISTANC,
*3HE,V,1H,10HNON-DIMENS,10HTONAL AXIA,10HL DISTANCE,2H*U,1H,5,5/
DATA (DATAIN(1,5),I=1,48)/2HAX0,2HAX1,2HAX2,5HRHOP1,5HRHOP2,2HMP,
190 *2HND,2HT1,2HT2,2HT3,2HT4,2HT5,2HT6,2HT7,2HT8,2HT9,3HT10,
*4H0S1,4H0INT,5HTORNT,5HNGAUS,4HMODE,4HUMIN,4HUMAX,
*4HVIN,4HVMAX,3HST1,3HST2,3HS13,3HST4,3HST5,3HPT1,3HPT2,
*3HPT3,3HPT4,3HPT5,3HYT1,3HXT2,3HXT3,3HXT4,3HXT5,3HYT1,
*3HYT2,3HYT3,3HYT4,3HYT5,5HNSKIP,5HNSKIP/
DATA (DATAIN(1,6),I=1,48)/5*1,2*0,11*1,4*0,4*1,20*-1,2*0/
195 DATA IT3,IT4,IT5,IT6,IT7,IT8,4,5,6,7,8/
DATA IEDM,ERPORA/0,1E-10/
INDIC=0
S=F,
ISW=1
NT=10
200 CALL GETDATA(DATAIN,92,4,5,6,3,100,300,INDIC)
CALL GETDATA(DATAIN,48,4,5,6,7,100,300,INDIC)
IF (MODE,ME,1) GOTO 150
DATAIN(17,1)=10HAXIAL DIS
DATAIN(18,1)=10HTANCE,RHO-
DATAIN(19,1)=10HRTIME (CM)
DATAIN(142,1)=10HAXIAL DIST
DATAIN(143,1)=10HANCE,X (RL
DATAIN(144,1)=10HATIVE TO
205 DATAIN(145,1)=10HRAISS FOCU
DATAIN(146,1)=7HS) (CM)
150 WRITE (IT7) DATAIN
WRITE (IT7) DATAIN
IF (MODE,EO,1) S=Y,
215 DEVID=IT3
READ(IT3)
TLAST=INEXT=0,
KFC=4,2831RE4/LAMBDA
EPO=E051
220 I0=TPONT
NGAISS=NGAHS
XS=,
DX=1,/M
MNNY=MINY
225 MD1=M+1
MF=,P1
IF (S) GOTO 120
XMAX=VMAX
XMIN=VMIN
230 GOTO 140
120 XMIN=PH001
XMAX=PH002
140 CONTINUE
A=,FSIG

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235	C=PI*(NX**2+1)/2./NY	002440
	C=C*R*RETA/3.14159/Y	002450
	CSID=C*SID	002460
	CSPD=C*SPD	002470
	CSIT=C*SIT	002480
240	CSPT=C*SPIT	002490
	RSQ=R*R	002500
	X0=X0*100.	002510
	X1=Y1*100.	002520
	X2=Y2*100.	002530
245	C1=Y/RSQ/DFN/CP	002540
	DFLY=(X2-X1)/(AMAX0(1,NP-1))	002550
	DFLPHQ=(PHQPP-RHQP)/(AMAX0(1,MP-1))	002560
	DFLV=(VMAX-VMIN)/(AMAX0(1,MP-1))	002570
	DFLH=(UMAX-UMIN)/(AMAX0(1,NP-1))	002580
250	RAD=R	002590
	NP1=N+1	002600
	C3=C/R	002610
	X3=1./X0	002620
	NDFC=1	002630
255	IT=1	002640
	TD=T-TIM(1)	002650
	IF (T.LT. 0.) GOTO 2000	002660
	IF (TP.EQ.2) WRITE(ITR) DATATN	002670
260	1000 T=T+C1	002680
	WRITE(ITR,2) T	002690
	IF (T.GT. TAUMX) GOTO 2000	002700
	XIT=X1	002710
	XII=1./XIT	002720
	U=U+IN	002730
265	DO 100 I=1,NP	002740
	CX=X0*X1I**2	002750
	IF (S1 U-KF*RSQ*(X0I-X1I)	002760
	RHQP=RHQP	002770
	V=V+IN	002780
270	DO 110 J=1,MP	002790
	IF (S1 V-KF*R*X1I)*RHQP	002800
	RHFP(J)=CX*IKIRK(U,V,T)	002810
	IF (IEPR.NE. 0) GOTO 2000	002820
275	210 RHQP=RHQP+DELRH	002830
	V=V+DELV	002840
	110 CONTINUE	002850
	WRITE (IT7) J,NP,U,TD,MP,AMIN,XMAX,(RHFP(J),J=1,MP)	002860
	CALL PRT(RHFP,MODE,I,TT,MP,NP,NSKIP,NSKIP,RHOP1,	002870
	*DFLPHQ,VMIN,DELV,XIT,U,TR,I,116)	002880
280	NREC=NREC+1	002890
	XIT=XIT+DELV	002900
	X1I=1./XIT	002910
	U=U+DELU	002920
285	110 CONTINUE	002930
	IT=IT+1	002940
	IF (IT.GT. NT) GOTO 2000	002950
	TD=T-TIM(IT)	002960
	IF (T.GT. TIM(IT-1)) GOTO 1000	002970
290	2000 WRITE(ITR,1) NREC	002980
	WRITE(ITR,6) IEPR,ERRORM	002990
	1 FORMAT(1X,* THE NUMBER OF RECORDS IS=*,110)	003000
	2 FORMAT(1X,* NEW VALUE OF TAU IS=*,E13.5)	003010
	3 FORMAT(1X,E12.4)	003020
	4 FORMAT(1X,E13.5)	003030
295	5 FORMAT(1X,E12.4,7(//5X,E13.5))	003040
	6 FORMAT(* MAX ERROR PARAM= *14* EST ABS. ERROR INTEG.= *E14.4)	003050
	END	

D.2 Major Function IKIRK Pertaining to Option No. 3 (IKIRK1)

1	REAL FUNCTION IKIRK(U,V,T)	014800
	COMMON/PHIRLK/CS1D,CS2R,CS1T,CS2T,XS,NZ,NF,MINT,EPS,F1(200),	014810
	*F2(200),HOLD,A,K,TLAST,TNEXT,IERP,IP,MPI,ISW,N,	014820
5	*RAD,NP1,C3,C1,IERM,FRRORM	014830
	COMMON/HIV/H1,V1	014835
	EXTERNAL FREAL1,FTMAG1,FREAL2,FIMAG2	014840
	DATA AERR,RERR/1E-3,1E-6/	014850
	H1=H	014852
10	V1=V	014854
	A2=A*A	014860
	IF (A2.GT. 220.) 1020,1030	014870
	1020 CONST=2.*A2*A2	014880
	GOTO 1040	014890
15	1030 CONST=2.*(A2/(1.-EXP(-A2)))*A2	014900
	1040 CALL RTAPE3(T)	014910
	IF (IERP.NE. 0) GOTO 2000	014920
	Y1=DCADRE(FREAL1,0.,1.,AERR,RERR,ERROR,IER)	014930
	IF (ERROR.GT. FRRORM) ERROR=ERROR	014940
20	IF (IER.GT. IERM) IERM=IER	014950
	Y1=DCADRE(FIMAG1,0.,1.,AERR,RERR,ERROR,IER)	014960
	IF (ERROR.GT. FRRORM) ERROR=ERROR	014970
	IF (IER.GT. IERM) IERM=IER	014980
	Z1=DCADRE(FREAL2,0.,1.,AERR,RERR,ERROR,IER)	014990
25	IF (ERROR.GT. FRRORM) ERROR=ERROR	015000
	IF (IER.GT. IERM) IERM=IER	015010
	Z1=DCADRE(FIMAG2,0.,1.,AERR,RERR,ERROR,IER)	015020
	IF (ERROR.GT. FRRORM) ERROR=ERROR	015030
	IF (IER.GT. IERM) IERM=IER	015040
30	IKIRK=CONST*(Y1*Y1+Y1*Y1+Z1*Z1+Z1*Z1)	015050
	2000 RETURN	015060
	END	015070

D.3 Function FREAL1

1	FUNCTION FREAL1(X)	015080
	COMMON/HIV/H,V	015090
	COMMON/PHIRLK/CS1D,CS2R,CS1T,CS2T,XS,NZ,NF,MINT,EPS,F1(200),	015100
	*F2(200),HOLD,A,K,TLAST,TNEXT,IERP,IP,MPI,ISW,N,	015110
5	*RAD,NP1,C3,C1,IERM,FRRORM	015120
	COMPLEX Q1,EXPR,EXPT,FX,FY,FZ,FW	015130
	REAL J0,1,K	015140
	A2=A*A	015150
	H02=.5*H	015152
10	ISW=1	015154
	GOTO 100	015156
	ENTBY FIMAG1	015158
	ISW=2	015160
	GOTO 100	015162
15	ENTBY FREAL2	015164
	ISW=3	015170
	GOTO 100	015172
	ENTBY FIMAG2	015174
	ISW=4	015180
20	100 X2=X*X	015182
	XV=X*V	015184
	FW=EXP(-A2*X2)*CEXP(CMPLX(0E0,-H02*X2))	015190
	EXP0=CEXP(CMPLX(0E0,K*PHI(X)))	015200
	EXPT=CEXP(CMPLX(0E0,K*HOLD))	015210
25	IF (V.EQ. 0.) FZ=(EXPR-EXPT)*X/2.	015220
	IF (V.NE. 0.) FZ=(EXPR-EXPT)*J1(XV)/V	015230
	Q1=X*J0(XV)	015240
	GOTO (110,120,130,140) ISW	015242
110	FX=Q1*EXPR-FZ	015250

30	FREAL1=WFAL(FW*FX)	015255
	RETURN	015257
120	FX=01*EXP-FZ	015260
	FREAL1=ATMAG(FW*FX)	015270
	RETURN	015280
35	130 FY=01*EXP+FY	015300
	FREAL1=RFAL(FW*FY)	015310
	RETURN	015320
	140 FY=01*EXP+FY	015340
	FREAL1=ATMAG(FW*FY)	015350
40	RETURN	015390
	END	015400

D.4 Function DCADRE

1	FUNCTION DCADRE (F,A,B,AERR,RERR,ERROR,IER)	015450
	C	015460
	C-DCADRE-----S-----LIBRARY 3-----	015470
	C	015480
5	C FUNCTION - INTEGRATE F(X) FROM A TO B, USING CAUTIOUS	015490
	C ADAPTIVE ROMBERG EXTRAPOLATION.	015500
	C USAGE - FUNCTION DCADRE (F,A,B,AERR,RERR,ERROR,IER)	015510
	C PARAMETERS DCADRE - ESTIMATE OF THE INTEGRAL OF F(X) FROM A TO B.	015520
	C F - A SINGLE-ARGUMENT REAL FUNCTION SUBPROGRAM	015530
10	C SUPPLIED BY THE USER. F MUST BE DECLARED	015540
	C EXTERNAL IN THE CALLING PROGRAM.	015550
	C A,B - THE TWO ENDPOINTS OF THE INTERVAL OF	015560
	C INTEGRATION. (INPUT)	015570
	C AERR - DESIRED ABSOLUTE ERROR IN THE ANSWER. (INPUT)	015580
15	C RERR - DESIRED RELATIVE ERROR IN THE ANSWER. (INPUT)	015590
	C ERROR - ESTIMATED BOUND ON THE ABSOLUTE ERROR OF	015600
	C THE OUTPUT NUMBER, DCADRE.	015610
	C IER - ERROR PARAMETER	015620
	C WARNING ERROR(WITH FIX) = 64 + N	015630
20	C N = 1 IMPLIES THAT ONE OR MORE SINGULARITIES	015640
	C WERE SUCCESSFULLY HANDLED.	015650
	C N = 2 IMPLIES THAT, IN SOME SUBINTERVAL(S),	015660
	C THE ESTIMATE OF THE INTEGRAL WAS ACCEPTED	015670
25	C MERELY BECAUSE THE ESTIMATED ERROR WAS	015680
	C SMALL, EVEN THOUGH NO REGULAR BEHAVIOR	015690
	C WAS RECOGNIZED.	015700
	C TERMINAL ERROR = 128 + N	015710
	C N = 3 -- FAILURE DUE TO INSUFFICIENT	015720
	C INTERNAL WORKING STORAGE.	015730
30	C N = 4 -- FAILURE. THIS MAY BE DUE TO TOO	015740
	C MUCH NOISE IN THE FUNCTION (RELATIVE	015750
	C TO THE GIVEN ERROR REQUIREMENTS) OR	015760
	C DUE TO AN ILL-BEHAVED INTEGRAND.	015770
	C N = 5 INDICATES THAT RERR IS GREATER THAN	015780
35	C 0.1, OR RERR IS LESS THAN 0.0, OR RERR	015790
	C IS TOO SMALL FOR THE PRECISION OF THE	015800
	C MACHINE.	015810
	C PRECISION - SINGLE	015820
	C REQD. IMSL ROUTINES - IERTST	015830
40	C LANGUAGE - FORTRAN	015840
	C-----S-----	015850
	C LATEST REVISION - SEPTEMBER 17, 1974	015860
	C	015870
45	C DIMENSION T(10,10),R(10),AIT(10),DIF(10),RN(4),TS(2049)	015880
	C TREGS(30),BEGIN(30),FINIS(30),EST(30)	015890
	C REGLSV(30)	015900
	C LOGICAL H2CONV,AITKEN,RIGHT,REGLAR,REGLSV	015910
	C REAL LENGTH,JUMPTL	015920
	C DATA ATTLOW,H2TUL,AITTL,JUMPTL,MAXTS,MAXTRL,MAXSTGE	015930
50	C /1.1,15,1,1,01,2049,10,30/	015940
	C DATA RN(1),RN(2),RN(3),RN(4)/	015950
	C .7142005,.3466282,.843751,.1263305/	015960
	C DATA ZERO,PI,HALF,ONE,TWO,FOUR,FOURPS,TEN,HUN	015970
	C /0.0,0.1,0.5,1.0,2.0,4.0,4.5,10.0,100.0/	015980
55	C ALG402 = ALOG10(TWO)	015990
	C CADRE = ZERO	016000
	C ERROR = ZERO	016010

	CHREST = ZERO	016020
	VINT = ZERO	016030
60	ICD = 0	
	LENGTH = ABS(H-A)	016050
	IF (LENGTH.EQ. ZERO) GO TO 215	016060
	IF (RERR.GT. P1.OO. RERR.LI. ZERO) GO TO 210	016070
	IF (AERR.EQ. ZERO.AND. (RERR+HIN).LE. HUN) GO TO 210	016080
65	ERRD = RERR	016090
	ERRA = ABS(AERR)	016100
	STEPMN = (LENGTH/FLOAT(2**MXSIZE))	016110
	STEPMN = AMAX1(LENGTH,ABS(A),ABS(B))*TEN	016120
	STAGE = HALF	016130
70	ISTAGE = 1	016140
	FNSTZE = ZERO	016150
	DOEVER = ZERO	016160
	REGLAR = .FALSE.	016170
75		016180
	REG = A	016190
	FREG = F(REG)*HALF	016200
	TS(1) = FREG	016210
	IREG = 1	016220
80	END = B	016230
	FEND = F(END)*HALF	016240
	TS(2) = FEND	016250
	IEND = 2	016260
	5 RIGHT = .FALSE.	016270
85		016280
		016290
		016300
		016310
		016320
		016330
90		016340
		016350
		016360
		016370
		016380
95		016390
		016400
		016410
		016420
		016430
100		016440
		016450
		016460
		016470
		016480
105		016490
		016500
		016510
		016520
		016530
110		016540
		016550
		016560
		016570
		016580
115		016590
		016600
		016610
		016620
		016630
120		016640
		016650
		016660
		016670
		016680
125		016690
		016700
		016710
		016720
		016730
130		016740
		016750

135	C	GET PRELIMINARY VALUE FOR *VINT*	016760
	C	FROM LAST TRAPEZOID SUM AND UPDATE	016770
	C	THE ERROR REQUIREMENT *ERGOAL*	016780
	C	FOR THIS SUBINTERVAL.	016790
		IT = 1	016800
		VINT = STEP*T(L,1)	016810
		TABTLM = TABS*TFN	016820
		FNSTZE = AMAX1(FNSTZE,ABS(T(L,1)))	016830
140		ERGL = ASTEP*FNSTZE*TFN	016840
		ERGOAL = STAGE*AMAX1(ERRA*ERGL*ABS(CUREST*VINT))	016850
	C	COMPLETE ROW L AND COLUMN L OF *T*	016860
	C	ARRAY.	016870
		FEXTRP = ONE	016880
145		DO 75 I=1,LM1	016890
		FEXTOP = FEXTRP*FOUR	016900
		T(I,1) = T(L,1) - T(L-1,1)	016910
		T(L,1) = T(L,1) + T(I,1)/(FEXTRP-ONE)	016920
		35 CONTINUE	016930
150		ERRR = ASTEP*ABS(T(I,1))	016940
	C	PRELIMINARY DECISION PROCEDURE	016950
	C	IF L = 2 AND T(2,1) = T(1,1),	016960
	C	GO TO 135 TO FOLLOW UP THE	016970
	C	IMPRESSION THAT INTEGRAND IS	016980
155	C	STRAIGHT LINE.	016990
		IF (L.GT. 2) GO TO 40	017000
		IF (TABS*PI*ABS(T(1,2)) .EQ. TABS) GO TO 135	017010
		GO TO 15	017020
160	C	CALCULATE NEXT RATIOS FOR	017030
	C	COLUMNS 1,...,L-2 OF T-TABLE	017040
	C	RATIO IS SET TO ZERO IF DIFFERENCE	017050
	C	IN LAST TWO ENTRIES OF COLUMN IS	017060
	C	ABOUT ZERO	017070
		40 DO 45 I=2,LM1	017080
165		DIFF = ZERO	017090
		IF (TABTLM*ABS(T(I-1,L)) .NE. TABTLM) DIFF = T(I-1,LM1)/T(I-1,L)	017100
		T(I-1,LM1) = DIFF	017110
		45 CONTINUE	017120
		IF (ABS(FOUR-T(I,LM1)) .LE. 2TOL) GO TO 60	017130
170		IF (T(I,LM1) .EQ. ZERO) GO TO 55	017140
		IF (ABS(TWO-ABS(T(I,LM1))) .LT. JUMPTL) GO TO 130	017150
		IF (L .EQ. 3) GO TO 15	017160
		H2CONV = .FALSE.	017170
		IF (ABS((T(I,LM1)-T(I,L-2))/T(I,LM1)) .LE. AITTOL) GO TO 75	017180
175		50 IF (REGULAR) GO TO 55	017190
		IF (L .EQ. 4) GO TO 15	017200
		55 IF (ERRR .GT. ERGOAL .AND. (ERGL*ERRR) .NE. ERGL) GO TO 175	017210
		GO TO 145	017220
	C	CAUTIOUS ROMBERG EXTRAPOLATION	017230
180		60 IF (H2CONV) GO TO 65	017240
		AITKEN = .FALSE.	017250
		H2CONV = .TRUE.	017260
		65 FEXTRP = FOUR	017270
		70 IT = IT + 1	017280
185		VINT = STEP*T(L,IT)	017290
		ERRR = ABS(STEP/(FEXTRP-ONE)*T(IT-1,L))	017300
		IF (ERRR .LE. ERGOAL) GO TO 160	017310
		IF (ERGL*ERRR .EQ. ERGL) GO TO 160	017320
		IF (IT .EQ. LM1) GO TO 125	017330
190		IF (T(IT,LM1) .EQ. ZERO) GO TO 70	017340
		IF (T(IT,LM1) .LE. FEXTRP) GO TO 125	017350
		IF (ABS(T(IT,LM1)/FOUR-FEXTRP)/FEXTRP .LT. AITTOL)	017360
		1 FEXTRP = FEXTOP*FOUR	017370
		GO TO 70	017380
195	C	INTEGRAND MAY HAVE X**ALPHA TYPE	017390
	C	SINGULARITY	017400
	C	RESULTING IN A RATIO OF *SING* =	017410
	C	2*(ALPHA + 1)	017420
		75 IF (T(1,LM1) .LT. AITLOW) GO TO 175	017430
200		IF (AITKEN) GO TO 80	017440
		H2CONV = .FALSE.	017450
		AITKEN = .TRUE.	017460
		80 FEXTRP = T(L-2,LM1)	017470
		IF (FEXTOP .GT. FOUR) GO TO 65	017480
205		IF (FEXTOP .LT. AITLOW) GO TO 175	017490
		IF (ABS(FEXTRP-T(L-2,LM1))/T(1,LM1) .GT. H2TOL) GO TO 175	017500
		SING = FEXTRP	017510
		FEXTM1 = ONE/(FEXTRP - ONE)	017520
		AIT(1) = ZERO	017530

210	DO 85 I=2,L	017540
	AIT(I) = T(I,1) + (T(I,1)-T(I-1,1))*FEXTM1	017550
	R(I) = T(I,1-1)	017560
	DIF(I) = AIT(I) - AIT(I-1)	017570
	85 CONTINUE	017580
215	IT = 2	017590
	90 VINT = STEP*AIT(L)	017600
	ERRER = FERRER*FEXTM1	017610
	IF (ERRER .GT. FPGOAL .AND. (ERGL+ERRER) .NE. ERGL) GO TO 95	017620
	ALPHA = ALOG10(SING)/ALG402 - ONE	017630
220	IFR = MAX0(IFR,55)	017640
	GO TO 160	017650
	95 IT = IT + 1	017660
	IF (IT .EQ. LMI) GO TO 125	017670
	IF (IT .GT. 3) GO TO 100	017680
225	H2NEXT = FOUR	017690
	SINGNX = SING*SING	017700
	100 IF (H2NEXT .LT. SINGNX) GO TO 105	017710
	FEXTRP = SINGNX	017720
	SINGNX = SINGNX*SINGNX	017730
230	GO TO 110	017740
	105 FEXTRP = H2NEXT	017750
	H2NEXT = FOUR*H2NEXT	017760
	110 DO 115 I=IT,LMI	017770
	R(I+1) = ZERO	017780
235	IF (TABTLM+ABS(DIF(I+1)) .NE. TABTLM) R(I+1) = DIF(I)/DIF(I+1)	017790
	115 CONTINUE	017800
	H2TPEX = -H2TOL*FEXTRP	017810
	IF (R(L) - FEXTRP .LT. H2TPEX) GO TO 125	017820
240	IF (R(L-1)-FEXTRP .LT. H2TPEX) GO TO 125	017830
	ERRER = STEP*ABS(DIF(L))	017840
	FEXTM1 = ONE/(FEXTRP - ONE)	017850
	DO 120 I=IT,L	017860
	AIT(I) = AIT(I) + DIF(I)*FEXTM1	017870
	DIF(I) = AIT(I) - AIT(I-1)	017880
245	120 CONTINUE	017890
	GO TO 40	017900
	C CURRENT TRAPEZOID SUM AND RESULTING	017910
	C EXTRAPOLATED VALUES DID NOT GIVE	017920
	C A SMALL ENOUGH *ERRER*.	017930
250	C NOTE -- HAVING PREVER .LT. ERROR	017940
	C IS AN ALMOST CERTAIN SIGN OF	017950
	C BEGINNING TROUBLE WITH IN THE FUNC-	017960
	C TION VALUES. HENCE, A WATCH FOR,	017970
	C AND CONTROL OF, NOISE SHOULD	017980
255	C BEGIN HERE.	017990
	125 FEXTRP = AMAX1(PREVER/ERRER,AITLOW)	018000
	PREVER = ERRER	018010
	IF (L .LT. 5) GO TO 15	018020
	IF (L-IT .GT. 2 .AND. ISTAGE .LT. MXSTGE) GO TO 170	018030
260	ERRER = ERRER/(FEXTRP*(MAXTRL-L))	018040
	IF (ERRER .GT. FPGOAL .AND. (ERGL+ERRER) .NE. ERGL) GO TO 170	018050
	GO TO 15	018060
	C INTEGRAND HAS JUMP (SEE NOTES)	018070
265	130 IF (ERRER .GT. FPGOAL .AND. (ERGL+ERRER) .NE. ERGL) GO TO 170	018080
	C NOTE THAT 2*FN = 2*L	018090
	DIF = ABS(T(I,1))*(FN+FN)	018100
	GO TO 160	018110
	C INTEGRAND IS STRAIGHT LINE	018120
270	C TEST THIS ASSUMPTION BY COMPARING	018130
	C THE VALUE OF THE INTEGRAND AT	018140
	C FOUR *RANDOMLY CHOSEN* POINTS WITH	018150
	C THE VALUE OF THE STRAIGHT LINE	018160
	C INTERPOLATING THE INTEGRAND AT THE	018170
	C TWO END POINTS OF THE SUB-INTERVAL.	018180
275	C IF TEST IS PASSED, ACCEPT *VINT*	018190
	135 SLOPE = (FEND-FBEG)*TWO	018200
	FREQ2 = FBEG+FBEG	018210
	DO 140 I=1,4	018220
	DIFF = ABS(FBEG+RN(I)*STEP) - FBEG2-RN(I)*SLOPE	018230
280	IF (TABTLM+DIFF .NE. TABTLM) GO TO 155	018240
	140 CONTINUE	018250
	GO TO 160	018260
	C NOISE MAY BE DOMINANT FEATURE	018270
285	C ESTIMATE NOISE LEVEL BY COMPARING	018280
	C THE VALUE OF THE INTEGRAND AT	018290

	C		FOUR *RANDOMLY CHOSEN* POINTS WITH	018300
	C		THE VALUE OF THE STRAIGHT LINE	018310
	C		INTERPOLATING THE INTEGRAND AT THE	018320
	C		TWO ENDPPOINTS. IF SMALL ENOUGH.	018330
	C		ACCEPT *VINT*	018340
290		145	SLOPE = (FFND-FREG)*TWO	018350
			FREG2 = FREG+FREG	018360
			I = 1	018370
		150	DIFF = ABS(FIBEG*DN(I)*STEP) - FREG2-DN(I)*SLOPE	018380
295		155	ERRR = AMAX1(ERRR,ASTEP*DIFF)	018390
			IF (ERRR.GT. *RGOAL .AND. (ERGL+ERRR) .NE. ERGL) GO TO 175	018400
			I = I+1	018410
			IF (I.LE. 4) GO TO 150	018420
			IFR = 66	018430
300	C		INTERGRATION OVER CURRENT SUB-	018440
	C		INTERVAL SUCCESSFUL	018450
	C		ADD *VINT* TO *DCADRE* AND *ERRR*	018460
	C		TO *ERDOR*. THEN SET UP NEXT SUB-	018470
	C		INTERVAL, IF ANY.	018480
305		160	CADRE = CADRE + VINT	018490
			ERRR = ERRR + FERR	018500
			IF (RIGHT) GO TO 165	018510
			ISTAGE = ISTAGE + 1	018520
			IF (ISTAGE.EQ. 0) GO TO 220	018530
310			DEGLAP = DEGLSV(ISTAGE)	018540
			RFG = HEGIN(ISTAGE)	018550
			END = FINIS(ISTAGE)	018560
			CHREST = CHREST - FST(ISTAGE+1) + VINT	018570
			IEND = IREG - 1	018580
315			FEND = TS(IEND)	018590
			IREG = IREGS(ISTAGE)	018600
			GO TO 180	018610
		165	CHREST = CHREST + VINT	018620
			STAGE = STAGE+STAGE	018630
320			IEND = IREG	018640
			IREG = IREGS(ISTAGE)	018650
			END = HFG	018660
			RFG = HEGIN(ISTAGE)	018670
			FEND = FREG	018680
325			FREG = TS(IREG)	018690
			GO TO 5	018700
	C		INTEGRATION OVER CURRENT SUBINTERVAL	018710
	C		IS UNSUCCESSFUL. MARK SUBINTERVAL	018720
	C		FOR FURTHER SUBDIVISION. SET UP	018730
	C		NEXT SUBINTERVAL.	018740
330		170	REGLAR = .TRUE.	018750
		175	IF (ISTAGE.EQ. MAXSTAGE) GO TO 205	018760
			IF (RIGHT) GO TO 185	018770
			DEGLSV(ISTAGE+1) = DEGLAR	018780
335			REGN(ISTAGE) = RFG	018790
			IREGS(ISTAGE) = IREG	018800
			STAGE = STAGE*HALF	018810
		180	STAGT = .TRUE.	018820
			RFG = (RFG+END)*HALF	018830
340			IREG = (IREG+IEND)/2	018840
			TS(IREG) = TS(IREG)*HALF	018850
			FREG = TS(IREG)	018860
			GO TO 10	018870
		185	NNLEFT = IREG - IREGS(ISTAGE)	018880
345			IF (IEND>NNLEFT.GE. MAXTS) GO TO 200	018890
			III = IREGS(ISTAGE)	018900
			II = IEND	018910
			DO 190 I=III,IBEG	018920
			II = II + 1	018930
350			TS(II) = TS(II)	018940
		190	CONTINUE	018950
			DO 195 I=IREG,II	018960
			TS(III) = TS(II)	018970
			III = III + 1	018980
355		195	CONTINUE	018990
			IEND = IEND + 1	019000
			IREG = IEND - NNLEFT	019010
			FEND = FREG	019020
			FREG = TS(IREG)	019030
360			FINIS(ISTAGE) = END	019040
			END = HFG	019050
			RFG = HEGIN(ISTAGE)	019060
			REGN(ISTAGE) = END	019070
			DEGLSV(ISTAGE) = DEGLAP	019080

365		ISTAGE = ISTAGE + 1	019090
		RFGIAR = RFGLSV(ISTAGE)	019100
		EST(ISTAGE) = VINT	019110
		CUREST = CUREST + EST(ISTAGE)	019120
		GO TO 5	019130
370	C	FAILURE TO HANDLE GIVEN INTEGRATION PROBLEM	019140
	C		019150
		200 IER = 131	019160
		GO TO 215	019170
		205 IER = 132	019180
		GO TO 215	019190
375		210 IER = 133	019200
		215 CADRE = CUREST + VINT	019210
		220 CADRE = CADRE	019220
		9900 CONTINUE	019230
380		IF (IER.NE.0) CALL UERTST (IER,6HDCADRE)	019240
		9905 RETURN	019250
		END	019260

D.5 Subroutine UERTST

1		SUBROUTINE UERTST (IER,NAME)	019270
	C		019280
	C	UERTST-----LTHRY 3-----	019290
	C		019300
5	C	FUNCTION - ERROR MESSAGE GENERATION	019310
	C	USAGE - CALL UERTST(ITER,NAME)	019320
	C	PARAMETERS IER - ERROR PARAMETER. TYPE + N WHERE	019330
	C	TYPE= 128 IMPLIES TERMINAL ERROR	019340
	C	64 IMPLIES WARNING WITH FIX	019350
	C	32 IMPLIES WARNING	019360
10	C	N = ERROR CODE RELEVANT TO CALLING ROUTINE	019370
	C	NAME - INPUT SCALAR CONTAINING THE NAME OF THE	019380
	C	CALLING ROUTINE AS A 6-CHARACTER LITERAL	019390
	C	STRING.	019400
	C	LANGUAGE - FORTRAN	019410
15	C		019420
	C	LATEST REVISION - AUGUST 1, 1973	019430
	C		019440
		DIMENSION IITP(24),IBIT(4)	019450
20		INTEGER WARN,WARF,IERM,PRINTR	019460
		EQUIVALENCE (TRIT(1),WARN),(IBIT(2),WARF),(IBIT(3),TERM)	019470
		DATA IITP	019480
		10HWARNING .10H	019490
		10HWARNING(WT,10HTH FIX)	019500
		10HTERMINAL .10H	019510
25		10HNON-DEFINE.10H	019520
		TRIT / 32.64,128.0/	019530
		DATA PRINTR/6LOUTPUT/	019540
		IFR2=IER	019550
		IF (IER2.GE. WARN) GO TO 5	019560
30	C	NON-DEFINED	019570
		IFR1=4	019580
		GO TO 20	019590
	5	IF (IER2.LT. TERM) GO TO 10	019600
	C	TERMINAL	019610
35		IFR1=3	019620
		GO TO 20	019630
	10	IF (IER2.LT. WARF) GO TO 15	019640
	C	WARNING(WITH FIX)	019650
		IFR1=2	019660
40		GO TO 20	019670
	C	WARNING	019680
	15	IFR1=1	019690
	C	EXTRACT *N*	019700
	20	IFR2=IER2-IBIT(IEP1)	019710
	C	PRINT ERROR MESSAGE	019720
45		WRITE (PRINTR,25) (IITP(I,IER1),I=1,2),NAME,IER2,IER	019730
	25	FORMAT(24H *** I M S L(UERTST) *** ,2A10,4X,A6,4X,I2,	019740
		1 0H (IER = ,I3,1H))	019750
		RETURN	019760
50		END	019770

D.6 Major Function IKIRK Pertaining to Option No. 1 (IKIRK)

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1      REAL FUNCTION IKIRK(U,V,T)                                000100
C      FUNCTION IKIRK IS THE KIRKHOFF INTENSITY FUNCTION DESCRIBED IN
C      HENDON, B. AND GIANINO, P., OPTICAL PERFORMANCE EVALUATION OF
C      INFRARED TRANSMITTING WINDOWS* AFCL-72-0565. ASSUMING A GAUSSIAN
5      SHAPED UNPOLARIZED SOURCE, THE INTENSITY FUNCTION CAN BE WRITTEN*
C      IKIRK(U,V)=2*(A12/(1-EXP(-A12))) : 2*(1/(0.1,DX) (FW*FX))12+
C      1/(0.1,DX) (FW*FY))12
C      WHERE*
C      FW(X,V)=EXP(-(A*X)12)*EXP(-I*U*X12/2)                    000170
C      FX(X,V)=X*J0(X*V)*EXP(I*K*PHIR(X))-FZ(X,V)              000180
C      FY(X,V)=X*J0(X*V)*EXP(I*K*PHIR(X))+FZ(X,V)              000190
C      FZ(X,V)=1/(X*V)*(EXP(I*K*PHIR(X))-EXP(I*K*PHIT(X)))/(V) 000200
C      A=1/SQRT(2)/SIG**2                                         000210
C      K=WAVE NO. (OMEGA/C)                                       000220
C      NOTATION*                                                  000230
C      ! => EXPONENTIALIZATION                                000240
C      I => IMAGINARY*                                           000250
C      1(0.1,DX) (.) MEANS INTEGRATION OF THE FUNCTION WITHIN (.) W.R.T.X
C      OVER THE INTERVAL (0,1).                                  000260
C      J0 AND J1 ARE BESSEL FUNCTIONS OF THE FIRST KIND, ZEROth AND FIRST
20      ORDER RESPECTIVELY.                                       000270
C      PHIR(X) AND PHIT(X) ARE THE FUNCTIONS PHI-SUPERSCRIPT-RHO AND PHI-
C      S-PERSCRIPT-THETA RESPECTIVELY IN THE ABOVE REFERENCE.  000280
C      THESE FUNCTIONS ARE GIVEN BY*                             000290
C      PHIR(X)=C*S1*F1(X)+4*C*S2*F2(X)                          000300
C      PHIT(X)=C*S1*T*F1(X)+4*C*S2*T*F2(X)                     000310
C      WHERE*                                                    000320
C      C=R13*P0*BETA/KT                                          000330
C      R=WINDOW RADIUS (CM)                                     000340
C      P0=MEAN INCIDENT POWER DENSITY (WATTS/CM12)             000350
C      BETA=BULK ABSORPTION COEFFICIENT (1/CM)                 000360
C      KT=THERMAL CONDUCTIVITY (WATT/(CM DEGC))                000370
C      S1R,S2R,S1T,S2T ARE MATERIAL CONSTANTS DEFINED IN THE ABOVE REF.
C      F1,F2 ARE THE FUNCTIONS DELTRAR-PRIME(X) AND             000380
C      (1/X12)1(0,X,DS) (DELTRAR-PRIME(S))                    000390
35      GIVEN IN THE ABOVE REFERENCE AND WHICH ARE PROVIDED AT SELECTED
C      ARGUMENTS BY PROGRAM TEMPS*.                             000400
C      *****
C      COMMON/PHIRBLK/CS1D,CS2R,CS1T,CS2T,XS,DZ,NF,MINT,EPS,FI(200),
40      *F2(200),HOLD,A,K,TLAST,TNEXT,IERR,IP,MPI,ISW,N,
C      *RAD,NPI,C3,C1,IERM,FRRDRM
C      COMMON/IFILES/IT3,IT4,IT5,IT6,IT7,IT8
C      COMMON/UV/UV,VV
C      COMPLEX O1,EXPR,EXPT,FX,FY,FZ,FW
45      REAL J0,J1
C      REAL K
C      DIMENSION XA(100),YR(100),YI(100),ZR(100),ZI(100)
C      UV=U
C      VV=V
50      A2=A*A
C      IF (A2.GT. 220.) 1020,1030
C      1020 CONST=2.*A2*A2
C      GOTO 1040
C      1030 CONST=2.*(A2/(1.-EXP(-A2)))**2
C      1040 UN2=U/2*E0
55      C IF ISW=1 THEN THE ARRAY OF POINTS FOR GAUSSIAN INTEGRATION
C      MUST BE FOUND
C      GOTO (1050,1060) ISW
C      1050 ISW=2
C      CALL DQG24A(0E0,1F0,XA)
C      IF (IP.EQ. 1) WRITE(IT6,1) (XA(I),I=1,N)
60      CALL RTAPE3(T)
C      IF (IERR.NE. 0) GOTO 2000
C      DO 100 I=1,N
C      X=XA(I)
65      X2=X*X
C      XV=X*V
C      FW=EXP(-A2*X2)*CEXP(CMPLX(0E0,-UN2*X2))
C      EXPD=CEXP(CMPLX(0F0,K*PHI(X)))
C      EXPT=CEXP(CMPLX(0F0,K*PHI(U)))
70      IF (V.EQ. 0.) FZ=(EXPR-EXPT)*X/2.
C      IF (V.NE. 0.) FZ=(EXPR-EXPT)*J1(XV)/V
C      O1=X*J0(XV)
C      FX=O1*EXPR-FZ
000410
000420
000430
000440
000450
000460
000470
000480
000490
000500
000510
000520
000530
000540
000550
000560
000570
000580
000590
000600
000610
000620
000630
000640
000650
000660
000670
000680
000690
000700
000710
000720
000730
000740
000750
000760
000770
000780
000790
000800
000810
000820
000830

```


75	FY=Q1*EXOT*FZ	000840
	Q1=FW*FX	000850
	YQ(T)=RFAL(Q1)	000860
	YT(T)=ATMAG(Q1)	000870
	Q1=FW*FY	000880
80	ZQ(T)=RFAL(Q1)	000890
	ZT(T)=ATMAG(Q1)	000900
100	CONTINUE	000910
1	FORNAT(5I1X,6I2,5I)	000920
	CALL DQG24R(0E0,1F0,YR,YR1)	000930
85	CALL DQG24R(0E0,1F0,YI,YI1)	000940
	CALL DQG24R(0E0,1F0,ZR,ZR1)	000950
	CALL DQG24R(0E0,1F0,ZI,ZI1)	000960
	TKIRK=CONST*(YR1*YR1+YI1*YI1+ZR1*ZR1+ZI1*ZI1)	000970
200	RETURN	000980
90	END	000990

D.7 Major Function IKIRK Pertaining to Option No. 2 (IKIRKP)

1	REAL FUNCTION IKIRK(U,V,T)	009800
	APRIL 11, 1974	009810
	THIS FUNCTION COMPUTES THE KIRKHOFF INTENSITY FUNCTION	009820
	ALONG THE U=0 AND/OR V=0 AXIS OF THE PLANE.	009830
5	SEE COMMENTS IN IKIRP AND COMPUTE FOR BACKGROUND INFO.	009840
	IT IS VALID ONLY FOR CONSTANT TEMPERATURE WINDOWS.	009850
	DIMENSION AA(10)	009860
	COMMON/FILES/IT3,IT4,IT5,IT6,IT7,IT8	009870
	COMMON/VICTOP/VV	009880
10	COMMON/PATHLK/CS10,CS20,CS1T,CS2T,XS,DX,NF,MNNT,EPP,F1(200),	009890
	*F2(200),HOLD,ALPHA,KF,TLAST,TNEXT,TERO,IP,MPI,ISW,NGAUSS,	009900
	*RAD,NP1,C1,C1	009910
	COMPLEX AJ00,CRH00,CTHETA0,A10,A20,A30,A40,A60,A70	009920
	REAL KE	009930
15	DATA (AA(1),I=1,10)/1.0, .99999999958, .4999999206, -.1666663019,	009940
	*.0416573475, -.0083013598, .0013298820, -.0001413161, 0.0, 0./	009950
	VV=V	009960
	CALL RTADF3(T)	009970
	IF (TERR.NF.0) GOTO 2000	009980
20	CTHETA0=CS1T*F1(1)+4.*CS2T*F2(1)	009990
	CTHETA0=CTHETA0*KE	010000
	CRH00=CS1P*F1(1)+4.*CS2P*F2(1)	010010
	CRH00=CRH00*KE	010020
	AJ00=(0.,1.)	010030
25	A20=CEXP(AJ00*CRH00)	010040
	A30=CEXP(AJ00*CTHETA0)	010050
	A10=A20-A30	010060
	A=- (ALPHA**2)	010070
	IF (A .LT. -1000) GOTO 110	010080
30	EXP4=EXP(A)	010090
	AS=2.*(A/(1.-EXP4))**2	010100
	GOTO 120	010110
	110 EXP4=0.	010120
	AS=2.*A*A	010130
35	120 B=U/2.	010140
	IF (U.EQ.0) GOTO 200	010150
	C=(ALPHA/V)**2	010160
	IF (U.EQ.0) GOTO 100	010170
40	200 SINB=SIN(R)	010180
	COSB=COS(R)	010190
	ASQ=A**2	010200
	BSQ=B**2	010210
	A400EAL=.5*((EXP4*(A+COSB*B*SINB))-A)/(ASQ+BSQ)	010220
	A401MAG=-.5*((EXP4*(A*SINB-B*COSB))+B)/(ASQ+BSQ)	010230
45	A40=CMPLX(A40REAL,A401MAG)	010240
	A40=A10/2.*A40	010250
	TKIRKP=AS*((CABS(A20*A40-A60))**2+(CABS(A30*A40+A60))**2)	010260
	RETURN	010270
100	IF (-A .GT. .693) GOTO 1000	010280


```

50      CALL COMPUTE (C,AA,FF1,FF2,IFR)
      IF (IER.F0.2) GOTO 1000
      A70=A10*FF2
      IXICK =A5*((CABS(A20*FF1-A70))**2+(CABS(A30*FF1-A70))**2)
      RETURN
55      1000 WRITE (IT5,10)
      10  FORMAT(/' ALPHA**2 IS OUT OF RANGE')
      2000 RETURN
      END

```

```

010290
010300
010310
010320
010330
010340
010350
010360
010370

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Appendix E

Fortran Listings for DISPLAY Program

E.1 Main Program DISPLAY

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1      PROGRAM DISPLAY(TAPE4=80/80,TAPE5=80/80,TAPE3,OUTPUT=80)
C REVISION---JUNE 11,1976
COMMON Z(103,103),XT(103,103),YT(103,103)
COMMON/BLANK3/NP2,MOD,XMINF,YMINF,DX,DY,SW1,IT6
5      DIMENSION DATA(8)
DIMENSION PROGID(3),CODE(1),DATAIN(103,3),PARM(80)
DIMENSION IND(40),ZIFVS(50),INDEX(4,2)
INTEGER CCODE
LOGICAL FLAG,FLAG1,SW1
10     DATA IT4,IT6,IT3/4,6,3/
DATA XS,YS/0.,0./
DATA (PROGID=7,HISTATINO,7HID 2347,7HDISPLAY)
DATA (CODE=1,1,45.,PARAM4,1,1)
15     BLANK=100
BLANK=100
INLANK=100
C THE FOLLOWING DATA CARDS MUST BE INPUTTED TO TAILOR THE PROGRAM
C FOR THE USER'S PARTICULAR APPLICATION. THE NUMBER IN PARENTHESES IN
C FRONT OF EACH DATUM NAME IS THE CARD COLUMN AT WHICH TO START THE
C DATUM. THE NUMBER IN PARENTHESES FOLLOWING THE DATUM IS THE DEFAULT
20     C VALUE OF THE DATUM. IF THE DEFAULT VALUE IS TO BE USED LEAVE THE
C CORRESPONDING CARD FIELD BLANK.
C CARD 1
C (1) XMAX (100.) MAXIMUM PLOT LENGTH IN INCHES
C (11) YMAX (10.) MAXIMUM PLOT WIDTH IN INCHES
25 C (21) NPT (1.) NUMBER OF POINTS/INCH FOR CONTOURS
C (31) TICU (1.) NUMBER OF INCHES BETWEEN TIC-MARKS
C FOR USER DEFINED X-Y PLOTS
C (41) XLEN (10.) X-Y PLOT COORDINATE FRAME X-SIZE
C (51) YLEN (10.) X-Y PLOT COORDINATE FRAME Y-SIZE
30 C (61) XSCALEY (1.) X-Y PLOT X-SCALE (UNITS/TIC)
C (71) YSCALEY (1.) X-Y PLOT Y-SCALE (UNITS/TIC)
C
C CARD 2
C (11) XMIN (1.) X-Y PLOT XMIN
C (11) YMIN (1.) X-Y PLOT YMIN
35 C (21) NAME (HARDEF1) NAME ON PLOT
C (31) PROBL. # (2344) PLOT PROBLEM NUMBER
C
C CARD 3
C (CARD 3 CONTAINS THE 2-D ARRAY 'INDEX' WHICH IS THE INDEX OF
C LOCATIONS FOR LABELING INFORMATION ASSUMED TO BE CONTAINED IN THE
C LAST DATUM ON THE FILE CONTAINING THE SURFACES. IF THERE IS NO
C SUCH DATA THEN THIS CARD MAY BE LEFT BLANK AND THE LABELING WILL
C NOT BE DONE. INDEX CONSISTS OF PAIRS OF NUMBERS WHEREIN THE FIRST
45 C NUMBER IS THE STARTING LOCATION OF THE LABEL AND THE SECOND NUMBER
C IS THE LENGTH OF THE LABEL.
C IF THE LETTER 'D' IS PLACED IN COLUMN 1 OF CARD 2, THE FOLLOWING
C DEFAULT LOCATIONS ARE USED FOR TITLE INFORMATION-
C (1) INDEX(1,1) (1) SURFACE TITLE
C (6) INDEX(1,2) (20) SURFACE TITLE LENGTH (CHARACTERS)
50 C (11) INDEX(2,1) (4) PARAMETER TITLE
C (16) INDEX(2,2) (33) PARAMETER TITLE LENGTH
C (21) INDEX(3,1) (7) X-TITLE
C (26) INDEX(3,2) (30) X-TITLE LENGTH
55 C (31) INDEX(4,1) (1) Y-TITLE
C (36) INDEX(4,2) (30) Y-TITLE LENGTH
C (41) NDA (2) NUMBER OF 'DATAIN' ARRAYS
C
C CARD 4-CARD 104+2
C CARD 4- CONTAIN THE INDICES OF DATA IN 'DATAIN' WHICH ARE TO
C BE PLOTTED AT THE BEGINNING OF EACH RUN OF DISPLAY. THERE MUST BE
C ONE CARD FOR EACH 'DATAIN' EVEN THOUGH FOR SOME 'DATAIN' NO DATA IS
C TO BE PLOTTED (A BLANK CARD IS ACCEPTABLE). THE INDEX NUMBERS START
65 C IN COLUMNS 1,3,5,7,..... FOR A TOTAL OF UP TO 40 INDICES PER CARD.
C THE DEFAULT IS A BLANK CARD, I.E. NO 'DATAIN' DATA IS TO BE PLOTTED.
DXMAX=100.
DYMAX=10.
DD=10.
TICU=5.
XLEN=10.
YLEN=8.
SCALEX=SCALEY=1.
XMIN=XMINY=0.
IND=X(1,1)=1

```


75	INDEX(1,2)=30	000830
	INDEX(2,1)=4	000840
	INDEX(2,2)=30	000850
	INDEX(3,1)=7	000860
	INDEX(3,2)=30	000870
80	INDEX(4,1)=10	000880
	INDEX(4,2)=30	000890
	NDA=2	000900
	READ(IT4,5) (DATA(I),I=1,8)	000910
	IF (DATA(1) .NE. BLANK) DECODE(10,6,DATA(1)) PXMAX	000920
85	IF (DATA(2) .NE. BLANK) DECODE(10,6,DATA(2)) PYMAX	000930
	IF (DATA(3) .NE. BLANK) DECODE(10,6,DATA(3)) PPI	000940
	IF (DATA(4) .NE. BLANK) DECODE(10,6,DATA(4)) TICU	000950
	IF (DATA(5) .NE. BLANK) DECODE(10,6,DATA(5)) XLEN	000960
	IF (DATA(6) .NE. BLANK) DECODE(10,6,DATA(6)) YLEN	000970
90	IF (DATA(7) .NE. BLANK) DECODE(10,6,DATA(7)) SCALEX	000980
	IF (DATA(8) .NE. BLANK) DECODE(10,6,DATA(8)) SCALEY	000990
	WRITE(IT4,10) PXMAX,PYMAX,PPI,TICU,XLEN,YLEN,SCALEX,SCALEY	001000
	READ(IT4,5) (DATA(I),I=1,8)	001010
	IF (DATA(1) .NE. BLANK) DECODE(10,6,DATA(1)) XMINX	001020
95	IF (DATA(2) .NE. BLANK) DECODE(10,6,DATA(2)) YMINY	001030
	IF (DATA(3) .NE. BLANK) DECODE(10,4,DATA(3)) PROGID(1)	001040
	IF (DATA(4) .NE. BLANK) DECODE(10,4,DATA(4)) PROGID(2)	001050
	WRITE(IT4,10) XMINX,YMINY	001060
	READ(IT4,7) (DATA(I),I=1,8),NUAT	001070
100	IT=1	001080
	DO 01 I=1,4	001090
	DO 01 J=1,2	001100
	IT=I+1	001110
	IF (IT .GT. 1) GOTO 84	001120
105	IF (DATA(I) .EQ. 100) GOTO 85	001130
	IF (DATA(I)) .EQ. BLANK) 92,93	001140
	84 INDEX(I,1)=0	001150
	GOTO 01	001160
	93 CALL RJUST (DATA(IT))	001170
110	DECODE(10,8,DATA(IT)) INDEX(I,J)	001180
	91 CONTINUE	001190
	85 WRITE(IT6,14) (INDEX(I,J),J=1,2),I=1,4)	001200
	C INITIALIZE THE PLOTTER	001210
	CALL PLTIO3(PROGID,PYMAX,PYMAX,1E0)	001220
115	C PLOT DATA BLOCKS	001230
	REWIND IT3	001240
	XPT=0.	001250
	IF (NDAT .EQ. 1) BLANK) GOTO 94	001260
	CALL RJUST(NDAT)	001270
120	DECODE(10,8,NDAT) NDA	001280
	IF (NDA .EQ. 0) GOTO 70	001290
	94 DO 06 I=1,NDA	001300
	READ(IT4,9) (IND(I),I=1,40)	001310
	DO 07 J=1,40	001320
125	IF (IND(I) .EQ. 1) BLANK) 98,99	001330
	98 IND(J)=	001340
	GOTO 97	001350
	99 CALL RJUST(IND(I))	001360
	DECODE(10,8,IND(J)) IND(J)	001370
130	97 CONTINUE	001380
	WRITE(IT6,11) NDA,(IND(K),K=1,40)	001390
	READ(IT3) DATAIN	001400
	CALL FILE (DATAIN,PAPM,IND,100,1,NN)	001410
	CALL PADMPLT(XPT,0E0,1E0,PAPM,1,NN)	001420
135	XPT=XPT+3.	001430
	96 CONTINUE	001440
	70 CALL PLOT(XPT,0,...3)	001450
	C START THE MAIN DISPLAY LOOP. INTERP READS AND INTERPRETS THE DISPLAY	001460
	C COMMANDS. IT RETURNS A FLAG VALUE OF .FALSE. IF THE LAST COMMAND HAS	001470
140	C BEEN READ.	001480
	FLAG=.T.	001490
	INDIC=1	001500
	100 DO 101 K=1,7	001510
	CODE(K)=BLANK	001520
145	101 CONTINUE	001530
	INDIX=0	001540
	XP=.5	001550
	IDEN=2	001560
	CALL INTERP(CCODE,CODE,FLAG,IT4)	001570
150	IF (.NOT. FLAG .AND. INDIC .EQ. 2) GOTO 2000	001580
	IF (CCODE .EQ. 1) WRITE(IT6,15) (CODE(K),K=1,5)	001590
	IF (CCODE .EQ. 2) WRITE(IT6,12) (CODE(K),K=1,4)	001600
	IF (CCODE .EQ. 3) WRITE(IT6,16) (CODE(K),K=1,7)	001610
	FLAG=.T.	001620

155	IF (NDA .LE. 0) GOTO 82	001630
	REWIND IT3	001640
	DO 81 I=1,NDA	001650
	READ(IT3)	001660
81	CONTINUE	001670
160	82 INDIC=2	001680
	ZMINA=1E100	001690
	ZMAXA=-1E100	001700
	NSTART=CODE(2) .00. 0	001710
	NSTART=NSTART-1	001720
165	IF (NSTART .LE. 0) GOTO 72	001730
	DO 74 I=1,NSTART	001740
	CALL RD1(IT3,D1,D2,D3,D4,4,FLAG1,D5,D6,D7,D8,D9)	001750
	IF (.N. FLAG1) GOTO 100	001760
74	CONTINUE	001770
170	72 NSKIP=CODE(1) .0R. 0	001780
	NSKIP=NSKIP-1	001790
	GOTO (110,120,130) CCODE	001800
	C 110 => CONTOUR	001810
	C 120 => PERSPECTIVE	001820
175	C 130 => PLOT	001830
	C CONTOUR- IF CONTOURS ARE TO BE NORMALIZED OVER ALL SURFACES, FIND THE	001840
	C MAX. AND MIN. OVER ALL SURFACES.	001850
110	IF (CODE(4) .EQ. 2H0N .OR. CODE(6) .EQ. 2H0N) GOTO 150	001860
160	CALL RD1(IT3,NP,MP,7MAX,ZMIN,1,FLAG1,TIM,XMIN,XMAX,YMIN,YMAX)	001870
180	WRITE(IT6,13) NP,MP,7MAX,ZMIN,TIM,XMIN,XMAX,YMIN,YMAX,FLAG1	001880
	IF (CODE(4) .EQ. 2HNF .OR. CODE(6) .EQ. 2HNE) GOTO 140	001890
	CALL SKIP(IT3,NSKIP,FLAG1,NP)	001900
	IF (ZMAX .GT. ZMAXA) ZMAXA=ZMAX	001910
	IF (ZMIN .LT. ZMINA) ZMINA=ZMIN	001920
185	IF (FLAG1) GOTO 140	001930
140	REWIND IT3	001940
	FLAG1=.T.	001950
	IF (NDA .LE. 0) GOTO 145	001960
	DO 83 I=1,NDA	001970
190	83 READ(IT3)	001980
	CONTINUE	001990
145	IF (NSTART .LE. 0) GOTO 150	001991
	DO 115 I=1,NSTART	001992
	CALL RD1(IT3,DUM1,DUM2,DUM3,DUM4,4,FLAG1,DUM5,DUM6,DUM7,DUM8,	001994
195	*DUM9)	001996
115	CONTINUE	001998
150	GOTO (155,250,350) CCODE	002000
	C NEXT FILE THE 7-ARRAY, DETERMINE CONTOUR LEVELS AND DRAW THE CONTOUR MA	002010
165	CALL RD1(IT3,NP,MP,7MAX,ZMIN,2,FLAG1,TIM,XMIN,XMAX,YMIN,YMAX)	002020
200	IF (.NOT. FLAG1) GOTO 190	002030
	IF (CODE(4) .EQ. 2H0N) 170,180	002040
170	CALL CLEV(CODE(3),ZMAX,ZMIN,ZLEVS)	002050
	GOTO 190	002060
180	IF (CODE(4) .EQ. 2HNA) 200,210	002070
205	200 ZMAX=ZMAXA	002080
	ZMIN=ZMINA	002090
210	210 C=100./(7MAX-ZMIN)	002100
	DO 220 J=1,MP	002110
	DO 220 I=1,NP	002120
	Z(I,J)=(7(I,J)-ZMIN)*C	002130
220	CONTINUE	002140
	CALL CLEV(CODE(3),100,.0.,ZLEVS)	002150
190	XLEN1=AMTNI((MP-1)/DDT,PYMAX-1.)	002160
	YLEN1=AMTNI((NP-1)/DDT,PYMAX-1.)	002170
215	IF (CODE(5) .EQ. 2HSP .A. INDIX .EQ. 1) GOTO 205	002180
	CALL CFRAME(INDIX,ZMIN,ZMAX,CODE(4),NP,MP,TIM,PPI,100,.6,.0.,	002190
	*XMIN,XMAX,YMIN,YMAX,DATAIN,XLEN1,YLEN1,CCODE)	002200
	INDIX=1	002210
205	SYM=SYMBL(TIM)	002220
220	NX=INDEX(2,2)	002230
	IF (NX .EQ. 0) GOTO 222	002240
	CALL SYMBOL(XLEN1,XP,PYMAX-1,1,.1E0,DATAIN(INDEX(2,1),1),0.,NX)	002250
	GOTO 223	002260
222	CALL SYMBOL(XLEN1,XP,PYMAX-1,1,.1E0,9HPARAMETER,0.,9)	002270
225	223 CALL SYMBOL(999F0,999E0,.1E0,SYM,0E0,10)	002280
	CALL CONTOUR(NP,MP,CODE(3),ZLEVS,BLANK,XLEN1,YLEN1,XP,PYMAX-1,2)	002290
	IF (CODE(5) .NE. 2HSP) GOTO 215	002300
	XP=XP+4.	002310
	IPEN=IPEN+1	002320
230	IF (IPEN .GT. 3) IPEN=1	002330
	CALL NEWPEN(IPEN)	002340
	GOTO 196	002350
215	CALL PLOT(XLEN1+12,.0.,-3)	002360
196	IF (FLAG1) 195,104	002370

235	135	CALL SKIP(IT3,NSKTP,FLAG1,NP)	002380
		IF (FLAG1) 155,104	002390
	146	IF (CODE(5),NE,2HSD) GOTO 100	002400
		CALL NEWDEN(2)	002410
		CALL PLOT(XLEN1,XD,R,.0F0,-3)	002420
240		GOTO 100	002430
		C START OF PERSPECTIVE PLOTS. FIRST FIND ZMAX,ZMIN FOR NORMALIZATION IF	002440
		C NORMALIZATION IS OVER ALL SURFACES.	002450
	120	GOTO 110	002460
	200	DDI=-10.	002470
245		IF (MP,GT, NP) GOTO 390	002480
		XLEN1=5.*MP/FLOAT(NP)	002490
		YLEN1=5.	002500
		GOTO 400	002510
	390	YLEN1=5.*NP/FLOAT(MP)	002520
250		XLEN1=5.	002530
		C THE NEXT TASK IS TO FIND SCALING FACTORS FOR THE DISPLAY BY CALLING	002540
		C FACE WITH A RECTANGLE FUNCTION.	002550
	400	NP1=NP+1	002560
		MP1=MP+1	002570
255		NP2=NP1+1	002580
		MP2=MP1+1	002590
		X2=MP2**2	002600
		Y2=NP2**2	002610
		H=SQRT(X2+Y2)	002620
260		THETA1=.785398164	002630
		THETA2=CODE(3)/180.*3.14159265	002640
		X=.C*MP2*H*COS(THETA2)	002650
		Y=.C*NP2*H*SIN(THETA2)	002660
		CL=.5*H	002670
265		CALL APLACE(XP,YP,XLEN1,YLEN1,CODE(3))	002680
		C THIS SUBROUTINE FINDS THE POINT AT WHICH TO PLACE THE VIEW-ANGLE	002690
		C ARROW	002700
		DO 260 K=1,NP2	002710
		Z(K,1)=7(K,MP2)=0.	002720
270	260	CONTINUE	002730
		DO 270 K=2,MP1	002740
		Z(NP2,K)=Z(1,K)=0.	002750
	270	CONTINUE	002760
		DO 280 I=2,NP1	002770
275		DO 280 J=2,MP1	002780
		Z(I,J)=C1	002790
	280	CONTINUE	002800
		SWI=.F.	002810
		C IF SWI IS OFF (.F.) THEN FACE RETURNS XMIN,YMIN,DX,DY ONLY AND DOES NO	002820
280		C PLOTTING	002830
		CALL FACE(X,Y,H,THETA1,THETA2,0)	002840
		SWI=.T.	002850
		WRITE(IT6,2) XMINF,YMINF,DX,DY	002860
	2	FORMAT(1X,4E15.5)	002870
285		C NOW FILL UP THE Z-ARRAY	002880
	290	CALL RD1(IT3,NP,MP,ZMAX,ZMIN,J,FLAG1,TIM,XMIN,XMAX,YMIN,YMAX)	002890
		IF (.NOT. FLAG1) GOTO 100	002900
		IF (CODE(4),EQ,2HMF) GOTO 300	002910
		ZMIN=ZMINA	002920
290		ZMAX=ZMAXA	002930
		C NOW DRAW LARFLS,ETC.	002940
	30	C=C1/(ZMAX-ZMIN)	002950
		DO 310 J=2,MP1	002960
		DO 310 K=2,NP1	002970
295		Z(K,J)=(Z(K,J)-ZMIN)*C	002980
	310	CONTINUE	002990
		DD=.1*AMAX0(NP,MP)	003000
		CALL CFRAME(INDFX,ZMIN,ZMAX,CODE(4),NP,MP,TIM,PP,C1,6E0,1E0,	003010
		*XMIN,XMAX,YMIN,YMAX,DATIN,XLEN1,YLEN1,CCODE)	003020
300		CALL ARROW(XP,YP,1.,CODE(3),10HVIEW ANGLE,10)	003030
		XPT=XLEN1*4E0	003040
		YPT=-1E0	003050
		CALL PLOT(XPT,YPT,-3)	003060
305		C NOW DRAW PERSPECTIVE DISPLAY	003070
		CALL FACE(X,Y,H,THETA1,THETA2,0)	003080
		CALL PLOT(12F0,0E0,-3)	003090
		IF (FLAG1) 320,104	003100
	320	CALL SKIP(IT3,NSKTP,FLAG1,NP)	003110
		IF (FLAG1) 240,104	003120
310		C START OF X-Y PLOTS. FIRST FIND ZMAX,ZMIN FOR SCALING IF SCALING IS	003130
		C OVER ALL SURFACES	003140
	130	GOTO 110	003150
	350	CALL RD1(IT3,NP,MP,ZMAX,ZMIN,Z,FLAG1,TIM,XMIN,XMAX,YMIN,YMAX)	003160
		IF (.NOT. FLAG1) GOTO 105	003170

315	IF (CODE(6)) .EQ. 2HNF) GOTO 370	003180
	IF (CODE(6)) .EQ. 2HNF) GOTO 370	003190
	ZMIN=ZMTNA	003200
	ZMAX=ZMAXA	003210
320	CONTINUE	003220
	IF (CODE(7)) .NE. 2HSD) XS=YS=0.	003230
	CALL PLOTT1(TICU,SCALXX,SCALYY,XLEN,YLEN,TIM,NP,MP,IT6,INDEX,	003240
	+DATAIN,XMIN,XMAX,YMIN,YMAX,XS,YS,ZMIN,ZMAX,CODE,XMINX,YMINY)	003250
	IF (FLAG1) 380,105	003260
325	CALL SKID(TT3,N-KIP,FLAG1,NP)	003270
	IF (FLAG1) 350,105	003280
105	IF (CODE(7)) .EQ. 2HSD) CALL PLOT(XLEN+6.,0.,-3)	003290
	XS=YS=0.	003300
	GOTO 100	003310
2000	CALL ENDOLT	003320
330	14 FORMAT(1X,2I5,3X,A1,2I5,3X,A2,3XA2)	003330
	15 FORMAT(1X,3I5,3X,A2,3XA2)	003340
	14 FORMAT(1X,A15)	003350
	13 FORMAT(1X,2I10,1X,4G10,2/1X,3G10,2,L10)	003360
	12 FORMAT(1X,2I5,3X,A10,2,3X,A2,3XA2,3XA2)	003370
335	11 FORMAT(1X,I5,4/(1X,I15))	003380
	10 FORMAT(1X,4G10,2/1X,4G10,2)	003390
	9 FORMAT(4A2)	003400
	8 FORMAT(T10)	003410
	7 FORMAT(Q45)	003420
340	6 FORMAT(E10,0)	003430
	5 FORMAT(A410)	003440
	4 FORMAT(A10)	003450
	END	003460

E.2 Subroutine PLOTT1

1	SUBROUTINE PLOTT1(TICU,SCALXX,SCALYY,XLEN,YLEN,TIM,NP,MP,IT6,	003470
	+INDEX,DATAIN,XMINX,XMAXX,YMINY,YMAXY,XS,YS,ZMIN,ZMAX,CODE,	003480
	+XMINX,YMINY)	003490
5	DIMENSION PTITLE(5),TITLE(5),XTITLE(5),YTITLE(5)	003500
	DIMENSION INDEX(4,2),DATAIN(100,3),XARRAY(101),YARRAY(101),CODE(7)	003510
	COMMON Z(103,103)	003520
	C IN THE FIRST PART OF PLOTT1 THE COORDINATE FRAME IS DRAWN AND	003530
	C TITLED. IF CODE(7) IS ON THEN SCALING IS OBTAINED FROM THE USER.	003540
	C OTHERWISE SCALING IS DONE BY SUBROUTINE SCALE.	003550
10	C THE INDEX ARRAY IS USED AS IN SUBROUTINE CFRAME TO OBTAIN VARIOUS	003560
	C TITLING INFORMATION. THE PLOT Y-ARRAY IS OBTAINED FROM Z(I,J) AS	003570
	C YARRAY(I)=Z(I,N) IF CODE(3)=X AND AS YARRAY(I)=Z(N,.) IF CODE(3)	003580
	C =Y. WHERE N STARTS AT CODE(4) AND IS INCREMENTED BY CODE(3). THE	003590
	C CALL PLOTT1 MUST SUPPLY THE FOLLOWING ARGUMENTS-	003600
15	MT=CODE(4) .OR. 0	003610
	IF (CODE(7)) .EQ. 2HSD .A. XSS .NE. 0.) GOTO 430	003620
	XS=YS=0.	003630
370	YMIN=YARRAY(1)=ZMTN	003640
	YMAX=Y(2)=ZMAX	003650
20	CALL SCALE(YARRAY,YLEN,2,1,20.,YMIN1,DELTY)	003660
	IF (CODE(7)) .EQ. 1HX) 380,390	003670
380	XMIN=XMINX	003680
	XMAX=XMAXX	003690
	YMIN=YMINY	003700
25	YMAX=YMAXY	003710
	DELY=(XMAX-XMIN)/AMAX0(1,MP-1)	003720
	DELO=(PMFX-PMIN)/AMAX0(1,NP-1)	003730
	DO 382 I=1,MP	003740
	XARRAY(I)=XMIN+(I-1)*DELY	003750
30	382 CONTINUE	003760
	NX=INDEX(3,2)	003770
	NN=(NX+9)/10	003780
	IF (NX .NE. 0) GOTO 505	003790
	NX=7	003800
35	XTITLE(1)=7HX-VALUE	003810
	GOTO 500	003820
505	IT=INDEX(3,1)	003830
	DO 384 I=1,NN	003840
	XTITLE(I)=DATAIN(IT,I)	003850

40		IT=I+1	003860
384	CONTINUE		003870
500	NT=INDEX(4,2)		003880
	NN=(NT+9)/10		003890
	IF (NT .NE. 0) GOTO 515		003900
	NT=7		003910
45	TTITLE(I)=7HY-VALUE		003920
	GOTO 510		003930
515	IT=INDEX(4,1)		003940
	DO 386 I=1,NN		003950
	TTITLE(I)=DATAIN(IT,1)		003960
50	IT=I+1		003970
386	CONTINUE		003980
510	NDTS=NP		003990
	NLI=NP		004000
55	GOTO 400		004010
300	XMIN=YMIN		004020
	XMAX=YMAX		004030
	PMIN=XMIN		004040
	PMAX=XMAX		004050
60	DELY=(XMAX-XMIN)/AMAX0(1, NP-1)		004060
	DELD=(PMAX-PMIN)/AMAX0(1, NP-1)		004070
	DO 392 I=1, NP		004080
	XAR0AY(I)=XMIN+(I-1)*DELY		004090
392	CONTINUE		004100
65	NX=INDEX(4,2)		004110
	NN=(NX+9)/10		004120
	IF (NX .NE. 0) GOTO 525		004130
	NX=7		004140
	XTITLE(I)=7HY-VALUE		004150
70	GOTO 520		004160
525	IT=INDEX(4,1)		004170
	DO 394 I=1, NN		004180
	XTITLE(I)=DATAIN(IT,1)		004190
	IT=I+1		004200
75	394 CONTINUE		004210
520	NT=INDEX(3,2)		004220
	NN=(NT+9)/10		004230
	IF (NT .NE. 0) GOTO 535		004240
	NT=7		004250
80	TTITLE(I)=7HX-VALUE		004260
	GOTO 530		004270
535	IT=INDEX(3,1)		004280
	DO 396 I=1, NN		004290
	TTITLE(I)=DATAIN(IT,1)		004300
	IT=I+1		004310
85	396 CONTINUE		004320
530	NDTS=NP		004330
	NLI=NP		004340
90	400 CALL SCALE(XARRAY, XI FN, NPIS, 1, 20, XMIN, DELX)		004350
	NY=INDEX(1,2)		004360
	NN=(NY+9)/10		004370
	IF (NY .NE. 0) GOTO 545		004380
	NY=7		004390
	YTITLE(I)=7HZ-VALUE		004400
95	GOTO 540		004410
545	IT=INDEX(1,1)		004420
	DO 410 I=1, NN		004430
	YTITLE(I)=DATAIN(IT,1)		004440
	IT=I+1		004450
100	410 CONTINUE		004460
540	NR=INDEX(2,2)		004470
	IF (NR .NE. 0) GOTO 555		004480
	NN=(NR+9)/10		004490
	NR=10		004500
105	PTITLE(I)=10HPARAPETER=		004510
	GOTO 550		004520
555	IT=INDEX(2,1)		004530
	DO 420 I=1, NN		004540
	PTITLE(I)=DATAIN(IT,1)		004550
	IT=I+1		004560
110	420 CONTINUE		004570
550	ISY=0		004580
	MCODE(5) .OP. 0		004590
	ISWCH=3		004600
115	IF (CODE(6) .EQ. PHON) GOTO 430		004610
	ISWCH=2		004620
	SCALEX=DELY		004630
	XMIN=XMIN		004640
	SCALEY=DELY		004650

120		VMT=VMTN1	0.4660
		C START OF MAIN PLOTTING LOOP	0.4670
	470	IF (M.GT. NLM) GOTO 440	0.4680
		IF (CODE(3).EQ. 1HV) GOTO 450	0.4690
		DO 460 I=1,NPTS	0.4700
125		VARDAY(I)=7(I,M)	0.4710
	460	CONTINUE	0.4720
		GOTO 470	0.4730
	450	DO 480 I=1,NPTS	0.4740
		VARDAY(I)=7(M,I)	0.4750
130		CONTINUE	0.4760
	470	CHPM=PMIN*(M-1)*NEID	0.4770
		IF (CODE(7).NE. 2HSD) GOTO 425	0.4780
		TIMT=TIM	0.4790
		TIM=CURVE	0.4800
135		CURVE=TIMT	0.4810
		DO 215 I=1,5	0.4820
		TITM=PTITLE(I)	0.4830
		PTITLE(I)=TITLE(I)	0.4840
		TITLE(I)=TIMT	0.4850
140	215	CONTINUE	0.4860
		TIMT=NB	0.4870
		NHENT	0.4880
		NT=TIMT	0.4890
		IF (XSS.NE. 0.) GOTO 200	0.4900
145	425	GOTO (200,220,210,200) ISWCH	0.4910
	210	CALL PLOT(XS,YS,3)	0.4920
		ISWCH=4	0.4930
		XSVS=0.	0.4940
		SCAV=TICU/SCALXX	0.4950
150		SCAV=TICU/SCALYY	0.4960
		ENCODE(10,1,1SYMR) YMINYY	0.4970
		CALL SYMBOL(-.1,0E0,.,1E0,1SYMB,90E0,10)	0.4980
		CALL SYMBOL(XS-.2E0,YS+1.2E0,.,1E0,YTITLE,90E0,NY)	0.4990
		CALL SYMBOL(999E0,999E0,.,1E0,10H SCALE IS,90E0,10)	0.5000
155		ENCODE(10,1,1SYMR) SCALYY	0.5010
		CALL SYMBOL(999E0,999E0,.,1E0,1SYMB,90E0,10)	0.5020
		CALL SYMBOL(999E0,999E0,.,1E0,10H UNITS/TIC,90E0,11)	0.5030
		ENCODE(10,1,1SYMR) YMINXX	0.5040
		CALL SYMBOL(0E0,.,2E0,.,1E0,1SYMB,0E0,10)	0.5050
160		CALL SYMBOL(1.2E0,.,3E0,.,1E0,XTITLE,0E0,NX)	0.5060
		CALL SYMBOL(999E0,999E0,.,1E0,10H SCALE IS,0E0,10)	0.5070
		ENCODE(10,1,1SYMR) SCALXX	0.5080
		CALL SYMBOL(999E0,999E0,.,1E0,1SYMB,0E0,10)	0.5090
		CALL SYMBOL(999E0,999E0,.,1E0,10H UNITS/TIC,0E0,11)	0.5100
165		CALL PLOT(0E0,0E0,3)	0.5110
		YPT=0.	0.5120
		DO 100 I=1,10000	0.5130
		N=I	0.5140
		XPT=I*TICU	0.5150
170		IF (XPT.GT. XLEN) GOTO 1000	0.5160
		CALL PLOT(XPT,YPT,2)	0.5170
		CALL PLOT(XPT,YPT,.,1,2)	0.5180
		CALL PLOT(XPT,YPT,2)	0.5190
	100	CONTINUE	0.5200
175	1000	XPT=(N-1)*TICU	0.5210
		DO 110 I=1,10000	0.5220
		N=I	0.5230
		YPT=I*TICU	0.5240
		IF (YPT.GT. YLEN) GOTO 1010	0.5250
180		CALL PLOT(XPT,YPT,2)	0.5260
		CALL PLOT(XPT,.,1,YPT,2)	0.5270
		CALL PLOT(XPT,YPT,2)	0.5280
	110	CONTINUE	0.5290
185	1010	YPT=(N-1)*TICU	0.5300
		XPT=XPT	0.5310
		DO 120 I=1,10000	0.5320
		N=I	0.5330
		XPT=XPT-I*TICU	0.5340
		IF (XPT.LT. XS) GOTO 1020	0.5350
190		CALL PLOT(XPT,YPT,2)	0.5360
		CALL PLOT(XPT,YPT,.,1,2)	0.5370
		CALL PLOT(XPT,YPT,2)	0.5380
	120	CONTINUE	0.5390
195	1020	YPT=YPT	0.5400
		XPT=XS	0.5410
		CALL PLOT(XS,YPT,2)	0.5420
		CALL PLOT(XS,YPT,3)	0.5430
		DO 130 I=1,10000	0.5440
		YPT=YPT-I*TICU	0.5450

200	IF (YPT,LT,YS) GOTO 1030	005470
	CALL PLOT(XPT,YPT,2)	005480
	CALL PLOT(XPT,1,YPT,2)	005490
	CALL PLOT(XPT,YPT,2)	005500
170	CONTINUE	005510
205	1730 CALL PLOT(XS,YS,2)	005520
	GOTO 230	005530
	220 CALL PLOT(XS,YS,3)	005540
	ISWYCH=1	005550
	XSS=YSS=0F0	005560
210	CALL AXTC(XS,YS,XTITLE,NX,XLEN,0E0,XMIN,SCALEX,20.)	005570
	CALL AXTC(XS,YS,YTITLE,NY,YLEN,0E0,YMIN,SCALEY,20.)	005580
	C NEXT PLOT PARAMETER AND CURVE TITLES	005590
	270 CALL SYMROL(XS,1F0,YS,YLEN,2,1E0,PTITLE,0E0,NB)	005600
	SYM=SYMRL(TIM)	005610
215	CALL SYMROL(999F0,999F0,1E0,SYM,0E0,10)	005620
	XSS=XLEN-1E0	005630
	YSS=YLEN-1E0	005640
	CALL SYMROL(XSS,YSS,1E0,TITLE,0E0,NT)	005650
	C PLOT CURVE	005660
220	200 CALL PLOT(0E0,0F0,3)	005670
	GOTO (240,240,250,250) ISWYCH	005680
	240 CALL LINE(XARRAY,YARRAY,NPTS,1,5,ISYM,XMIN,SCALEX,YMIN,	005690
	*SCALEY,07)	005700
	GOTO 1050	005710
225	250 X0=XQ=-.1	005720
	XLEM=XLEN+.1	005730
	YLEM=YLEN+.1	005740
	IP=0	005750
	DO 140 J=1,NPTS	005760
230	V=1	005770
	XPT=(XARRAY(J)-XMINXX)*SCAX	005780
	YPT=(YARRAY(J)-YMINYY)*SCAY	005790
	IF (XPT,GE,XQ,AND,YPT,GF,Y0,AND,YPT,LE,YLEM) GOTO 1040	005800
	140 CONTINUE	005810
235	WRITE(17,2)	005820
	GOTO 1050	005830
	2 FORMAT(1X,' NO POINTS PLOTTED')	005840
	1040 IF (ISYM,1070,1070,1080	005850
	1070 CALL PLOT(XPT,YPT,10)	005860
240	IP=0	005870
	GOTO 1060	005880
	1080 CALL SYMROL(XPT,YPT,1,ISYM,0,.-1)	005890
	1060 N=N+1	005900
	IF (N,GT,NPTS) GOTO 1050	005910
245	YPT=(YARRAY(N)-YMINYY)*SCAY	005920
	IF (YPT,GT,YLEM,OR,YPT,LI,Y0) GOTO 1065	005930
	XPT=(XARRAY(N)-XMINXX)*SCAX	005940
	IF (XPT,GT,XLEM,OR,XPT,LI,X0) GOTO 1065	005950
	GOTO 1040	005960
250	1065 IP=3	005970
	GOTO 1060	005980
	1050 IF (ISYM,LT,0) ISYM=15	005990
	YSS=YSS-.15	006000
	IF (YSS,GT,0.) GOTO 260	006010
255	YSS=YLEN-1.15	006020
	XSS=XSS+.2	006030
	260 CALL SYMROL(XSS,YSS,1F0,ISYM,0E0,-1)	006040
	CALL SYMROL(999F0,999F0,1E0,2H,0E0,2)	006050
	ENCODE(10,1,ISYM), CURVE	006060
260	CALL SYMROL(999F0,999F0,1E0,ISYM,0E0,10)	006070
	ISYM=MOD(ISYM+1,17)	006080
	IF (CODE(17),EQ,2HSD) GOTO 560	006090
	M=M+1	006100
	GOTO 430	006110
265	440 XPT=XLEN+6E0	006120
	CALL PLOT(XPT,0F0,-3)	006130
	560 RETURN	006140
	1 FORMAT(10,3)	006150
	END	

E.3 Subroutine PARMPLT

1	SUBROUTINE PARMPLT(XS,YS,HT,PARM,NS,N)	006160
	C THIS SUBROUTINE PLOTS N PARAMETERS IN 'PARM' STARTING AT LOCATION	006170
	C XS,YS. HT IS THE HEIGHT OF THE LETTERS (INCHES),NS IS THE 'STARTING	006180
	C LOCATION ' ' IN PARM AT WHICH TO LOOK FOR DATA FOR PLOTTING.	006190
5	DIMENSION PARM(1)	006200
	IF (N .LT. 0) GOTO 2000	006210
	XPT=XS	006220
	YPT=YS	006230
	NSI=NS-1	006240
10	DO 100 I=1,N+2	006250
	II=NSI+I	006260
	CALL SYMBOL(XPT,YPT,HT,PARM(II),0E0,20)	006270
	YPT=YPT-2.*HT	006280
15	100 CONTINUE	006290
	2000 RETURN	006300
	END	006310

E.4 Subroutine FILL

1	SUBROUTINE FILL(DATAIN,PARM,INDEX,ISIZE,NS,N)	006320
	C THIS SUBROUTINE SELECTS DATA FROM DATAIN(ISIZE,3) AND PLACES IT IN	006330
	C 2-D ARRAY PARM STARTING AT NS ACCORDING TO NUMBERS IN INDEX. THE	006340
	C PARM VALUES ARE CHARACTER-STRINGS SUITABLE FOR PLOTTING.	006350
5	DIMENSION DATAIN(1),PARM(1),INDEX(1)	006360
	EQUIVALENCE (IF,F1)	006370
	II=2*NS-1	006380
	DO 100 I=1,40	006390
	K=INDEX(I)	006400
10	IF (K .EQ. 0) GOTO 100	006410
	II=II+2	006420
	K1=K+1517E	006430
	K2=K1+1517E	006440
	F1=DATAIN(K2)	006450
15	PARM(II)=DATAIN(K1)	006460
	IF (IF) 1000,1010,1020	006470
	1000 ENCODE (10.1,PARM(II+1)) DATAIN(K)	006480
	GOTO 100	006490
	1010 ENCODE (10.2,PARM(II+1)) DATAIN(K)	006500
20	GOTO 100	006510
	1020 ENCODE (10.3,PARM(II+1)) DATAIN(K)	006520
	100 CONTINUE	006530
	N=II	006540
	RETURN	006550
25	1 FORMAT(A10)	006560
	2 FORMAT(I10)	006570
	3 FORMAT(G10.3)	006580
	END	006590

E.5 Subroutine CFRAME

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1      SUBROUTINE CFRAME(INDEX,ZMIN,ZMAX,COORD,NP,MP,TIM,PPI,C,XS,YS,      006600
      *XMIN,XMAX,YMIN,YMAX,DATAIN,XLEN,YLEN,CCODE)      006610
C INDEX IS A 2-D ARRAY OF INTEGERS (IN SEQUENCE) DENOTING THE      006620
C STARTING LOCATION AND NUMBER OF WORDS IN DATAIN CONTAINING THE      006630
C FOLLOWING INFORMATION-      006640
C 1.1 FUNCTION TITLE      006650
C 1.2 F-TITLE LENGTH (WORDS)      006660
C 2.1 PARAMETER LABEL      006670
C 2.2 P-LABEL LENGTH      006680
10  C 3.1 X-LABEL      006690
C 3.2 X-LABEL LENGTH      006700
C 4.1 Y-LABEL      006710
C 4.2 Y-LABEL LENGTH      006720
C C IS THE FUNCTION NORMALIZATION CONSTANT      006730
C XS,YS IS THE STARTING POINT OF THE FRAME      006740
15  C T IS SUBROUTINE ASSUMES THAT THE PRECEDING PLOT WAS TERMINATED AT THE      006750
C LOWER RIGHT CORNER OF ITS ALLOTTED SPACE (AND THIS IS THE NEW ORIGIN)      006760
C      006770
      DIMENSION DATAIN(100,3),INDEX(4,2)      006780
      INTEGER CCODE,COORD      006790
      TICH=5/ODI      006800
C FIRST DRAW TITLE,SCALING INFO,PARAMETER      006810
      NX=INDEX(1,2)      006820
      IF (NX.EQ.0) GOTO 170      006830
25  CALL SYMBOL(1E0,8,5F0,1E0,DATAIN(INDEX(1,1),1),OE0,NX)      006840
      IF (CCODE.EQ.1) GOTO 215      006850
170  SYM=SYMBOL(TIM)      006860
      NX=INDEX(2,2)      006870
      IF (NX.EQ.0) GOTO 200      006880
30  CALL SYMBOL(1E0,8,8,2F0,1E0,DATAIN(INDEX(2,1),1),OE0,NX)      006890
      GOTO 210      006900
210  CALL SYMBOL(1E0,8,8,2F0,1E0,PARAMETER,OE0,9)      006910
215  CALL SYMBOL(999F0,999E0,1E0,SYM,OE0,10)      006920
      IF (CODE.EQ.2HNN) GOTO 220      006930
35  CALL SYMBOL(1E0,8,8,1F0,1E0,24HALL FUNCTION VALUES HAVE,OE0,24)      006940
      CALL SYMBOL(1E0,7,8F0,1E0,25HHEFN SCALED ACCORDING TO-,OE0,25)      006950
      CALL SYMBOL(1E0,7,45E0,1E0,1H2,OE0,1)      006960
      CALL ARPDW(1E0,7,5,7,1E0,1H,0)      006970
      ENCODE(1,1,SYM) C      006980
40  CALL SYMBOL(1E0,7,7,6F0,1E0,SYM,OE0,10)      006990
      CALL SYMBOL(999F0,999E0,1E0,9H*(Z-ZMIN),OE0,9)      007000
      CALL PLOT(1E0,7,5F0,3)      007010
      CALL PLOT(3,1E0,7,5F0,2)      007020
      CALL SYMBOL(2E0,7,3F0,1E0,11H(ZMAX-ZMIN),OE0,11)      007030
      ENCODE(1,1,SYM) ZMAX      007040
45  CALL SYMBOL(1E0,7,1F0,1E0,11HWHERE ZMAX=,OE0,13)      007050
      CALL SYMBOL(999F0,999E0,1E0,SYM,OE0,10)      007060
      ENCODE(1,1,SYM) ZMIN      007070
      FORMAT(G10,3)      007080
50  CALL SYMBOL(1E0,6,9F0,1E0,11H ZMIN=,OE0,11)      007090
      CALL SYMBOL(999F0,999E0,1E0,SYM,OE0,10)      007100
      CALL SYMBOL(1E0,6,7F0,1E0,2HARE THE MAX. AND MIN.,OE0,20)      007110
      IF (CODE.EQ.2HNN) 110,120      007120
110  CALL SYMBOL(1E0,6,5F0,1E0,2HVALUES OVER ALL SURFACES,OE0,24)      007130
55  GOTO 100      007140
120  CALL SYMBOL(1E0,6,5F0,1E0,2HVALUES OF THE SURFACE,OE0,21)      007150
      CONTINUE      007160
C NEXT SET THE PLOT ORIGIN AT THE ORIGIN OF THE SURFACE COORDINATE      007170
C FRAME, DRAW THE FRAME AND LABEL IT.      007180
60  CALL PLOT(XS,YS,-3)      007190
C THE COORDINATE FRAME IS DRAWN WITH THE TIC-MARKS EVERY TICH (INCHES).      007200
      ENCODE(1,1,SYM) XMIN      007210
      CALL SYMBOL(OE0,-2F0,1E0,SYM,OE0,10)      007220
      NX=INDEX(3,2)      007230
65  IF (NX.EQ.0) GOTO 180      007240
      CALL SYMBOL(OE0,-5F0,1E0,DATAIN(INDEX(3,1),1),OE0,NX)      007250
      ENCODE(1,1,SYM) XMAX      007260
180  XPT=OE0      007270
      YPT=OE0      007280
      CALL PLOT(XPT,YPT,3)      007290
70  DO I=30 I=1,100000      007300
      N=I      007310
      XPT=I*TICH      007320
      IF (XPT.GT. XLEN) GOTO 1000      007330

```


E.6 Subroutine INTERP

223

15	READ(I,CARD,1) (LETTER(I),I=1,80)	007990
	IF (EOF(I,CARD)) 115,100	008000
115	FLAG=F.	008010
	GOTO 110	008020
160	CONTINUE	008030
20	1	008040
	FORMAT(RAR1)	008050
	DO 120 I=1,80	008060
	N=1	008070
	IF (LETTER(I) .NE. BLANK) GOTO 130	008080
120	CONTINUE	008090
25	130	008100
	IF (I .EQ. 81) GOTO 110	008110
	IF (LETTER(N) .EQ. C) CCODE=1	008120
	IF (LETTER(N+1) .EQ. L) CCODE=3	008130
	GOTO (131,134,133) CCODE	008140
	C SET DEFAULT VALUES OF CODE	008150
30	131	008160
	CODE(1)=1 .OR. 0	008170
	CODE(3)=10 .OR. 0	008180
	CODE(4)=2HNA	008190
	CODE(5)=10H	008200
	GOTO 132	008210
35	134	008220
	CODE(1)=1 .OR. 0	008230
	CODE(3)=45	008240
	CODE(4)=2HNA	008250
	GOTO 132	008260
40	133	008270
	CODE(1)=1 .OR. 0	008280
	CODE(3)=1HX	008290
	CODE(4)=1 .OR. 0	008300
	CODE(5)=1 .OR. 0	008310
	CODE(6)=2HNA	008320
	CODE(7)=10H	008330
45	132	008340
	DO 140 I=N,80	008350
	M=I	008360
	IF (LETTER(I) .EQ. LPAREN) GOTO 150	008370
	CONTINUE	008380
50	150	008390
	IF (I .EQ. 81) GOTO 110	008400
	CALL NUMB(CODE(1),M,1)	008410
	C IF M=0 THEN A RIGHT PAREN HAS BEEN FOUND, OTHERWISE IT RETURNS	008420
	C THE POSITION OF THE COMMA.	008430
	IF (M .EQ. 0) GOTO 110	008440
	CALL NUMB(CODE(2),M,1)	008450
55		008460
	IF (M .EQ. 0) GOTO 110	008470
	GOTO (160,170,140) CCODE	008480
	160	008490
	CALL NUMB(CODE(3),M,1)	008500
	IF (M .EQ. 0) GOTO 110	008510
	CODE(4)=2HNA	008520
60		008530
	IF (LETTER(M+1) .EQ. D) CODE(4)=2HDN	008540
	IF (LETTER(M+2) .EQ. E) CODE(4)=2HNE	008550
	IF (LETTER(M+3) .EQ. 23H) CODE(5)=2HSD	008560
	GOTO 110	008570
65	170	008580
	CALL NUMB(CODE(3),M,2)	008590
	IF (M .EQ. 0) GOTO 110	008600
	IF (LETTER(M+2) .EQ. E) CODE(4)=2HNE	008610
	GOTO 110	008620
70	140	008630
	IF (LETTER(M+1) .EQ. Y) CODE(3)=1HY	008640
	IF (LETTER(M+2) .EQ. PPAREN) GOTO 110	008650
	IF (LETTER(M+1) .EQ. 56R) M=M-1	
	M=M+2	
	CALL NUMB(CODE(4),M,1)	
	IF (M .EQ. 0) GOTO 110	
	CALL NUMB(CODE(5),M,1)	
75		
	IF (M .EQ. 0) GOTO 110	
	CODE(6)=2HNA	
	IF (LETTER(M+1) .EQ. D) CODE(6)=2HDN	
	IF (LETTER(M+2) .EQ. E) CODE(6)=2HNE	
	IF (LETTER(M+3) .EQ. 23H) CODE(7)=2HSD	
80	110	
	RETURN	
	END	

E.7 Subroutine NUMB

[illegible]

E.8 Subroutine ARROW

```

1      SUBROUTINE APPRO(XP,YP,L,THETA0,LABEL,NC)
      C      THETA= IS THE ARROW ANGLE WRT X-AXIS IN DEGREES
      C      L IS THE LENGTH OF THE ARROW IN INCHES
      C      THE LOCATION OF THE ARROW TIP (XP,YP) IS RETURNED
5      C NC IS THE NUMBER OF CHARACTERS IN THE ARROW LABEL
      REAL L
      DIMENSION LABEL(11)
      THETA=THETA0*3.1415927/180.
      XYP=L*COS(THETA)+YP
      YYP=L*SIN(THETA)+YP
10      XI=.2*L*COS(THETA+.1745)+XP
      YL=.2*L*SIN(THETA+.1745)+YP
      XII=.2*L*COS(THETA+.1745)+XP
      YII=.2*L*SIN(THETA+.1745)+YP
15      CALL PLOT(XP,YP,3)
      CALL PLOT(XYP,YYP,2)
      CALL PLOT(XI,YL,2)
      CALL PLOT(XL,YL,2)
      CALL PLOT(XP,YP,3)
      CALL PLOT(XU,YU,2)
20      YII=.25*L*COS(THETA+.6877)+XP
      YII=.25*L*SIN(THETA+.6877)+YP
      IF (NC.EQ. 0) GO TO 1000
      CALL SYMBOI(XII,YII,1,LABEL+THETA0*NC)
25      RETURN
      END)

```


E.9 Subroutine APLACE

1	SUBROUTINE APLACE(XP,YP,XLEN1,YLEN1,THETA2)	009230
	C THIS SUBROUTINE FINDS THE X,Y COORDINATES (XP,YP) FOR THE TIP	009240
	C OF THE ARROW WHICH INDICATES THE VIEW ANGLE (THETA2-DEGREES)	009250
	C FOR PERSPECTIVE PLOTS	009260
5	X2=.5*XLEN1	009270
	Y2=.5*YLEN1	009280
	PI180=3.1415927/180.	009290
	TH=PI180*THETA2	009300
	R=SQRT((X2+.5)**2+(Y2+.5)**2)	009310
10	XP=Y2+R*COS(TH)	009320
	YP=Y2+R*SIN(TH)	009330
	RETURN	009340
	END	009350

E.10 Subroutine RD1

1	SUBROUTINE RD1(IT3,MP,MP,ZMAX,ZMIN,ISW,FLAG,TIM,XMIN,XMAX,YMIN,	009360
	YMAX)	009370
	COMMON Z(103,103)	009380
	DIMENSION BUF(101)	009390
5	LOGICAL FLAG	009400
	C THIS SUBROUTINE FILLS UP THE 'SURFACE ARRAY' Z(...) AND/OR FINDS THE	009410
	C SURFACE MAX. AND MIN. (ZMAX,ZMIN). IT ALSO RETURNS THE SIZE OF THE	009420
	C SURFACE (MP X NP) AND THE SURFACE PARAMETER VALUE, TIM. THE LOGICAL	009430
	C VARIABLE, FLAG, IS .TRUE. UNTIL AN END-OF-FILE IS REACHED AT WHICH	009440
10	C POINT IT BECOMES FALSE. EACH UNFORMATTED RECORD OF THE INPUT FILE, IT3,	009450
	C IS ASSUMED TO BE OF THE FORM-	009460
	C I ROW NUMBER	009470
	C NP TOTAL NO. OF ROWS	009480
	C Y Y-VALUE CORRESPONDING TO THIS ROW	009490
15	C TIM SURFACE PARAMETER VALUE (E.G. TIME)	009500
	C MP TOTAL NO. OF COLUMNS	009510
	C XMIN VALUE ASSOCIATED WITH THE FIRST COLUMN	009520
	C XMAX VALUE ASSOCIATED WITH THE LAST COLUMN	009530
	C BUF(J) MP SURFACE ELEMENTS OF THE I-TH ROW	009540
20	C ISW ACTS AS A SWITCH TO CONTROL THE ACTION OF RD1 AS FOLLOWS-	009550
	C ISW=1 => RETURN ZMAX,ZMIN ONLY	009560
	C ISW=2 => RETURN SURFACE Z AND ZMAX,ZMIN	009570
	C ISW=3 => RETURN SURFACE Z BORDERED BY ZEROS AND ZMAX,ZMIN	009580
	C ISW=4 => SKIP A SURFACE	009590
25	C NOTE THAT THE FIRST RECORD READ IS ASSUMED TO INCLUDE THE FIRST	009600
	C ROW OF THE SURFACE	009610
	100 READ(IT3) I,NP,Y,TIM,MP,XMIN,XMAX,(BUF(J),J=1,MP)	009620
	IF (EOF(IT3)) 110,120	009630
	110 FLAG=.F.	009640
30	GOTO 1000	009650
	120 IF (ISW .EQ. 4) GOTO 230	009660
	I=I+1	009670
	Z(I,1)=Z(I,MP+2)=0.	009680
	IF (I .EQ. 1) 210,220	009690
35	210 ZMIN=ZMAX=BUF(1)	009700
	YMIN=Y	009710
	MP2=MP+2	009720
	DO 160 J=1,MP2	009730
40	90 Z(I,J)=0.	009740
	220 IF (I .EQ. NP) YMAX=Y	009750
	DO 160 J=1,MP	009760
	ZT=BUF(J)	009770
	IF (ZT .LT. ZMIN) ZMIN=ZT	009780
	IF (ZT .GT. ZMAX) ZMAX=ZT	009790
45	GOTO (160,170,180) ISW	009800
	170 Z(I,J)=ZT	009810
	GOTO 160	009820
	180 Z(I,J+1)=ZT	
	GOTO 160	

50	140	CONTINUE	009830
	230	IF (I.LT. NP) GOTO 100	009840
		GOTO (1000,1000,100,1000) IS	009850
	100	MP2=NP+2	009860
		NP2=NP+2	009870
55		DO 200 I=1,MP2	009880
	200	Z(VD2,J)=0.	009890
	1000	RETURN	009900
		END	009910

E.11 Subroutine CLEV

1		SUBROUTINE CLEV(NLEV,ZMAX,ZMIN,ZLEVS)	009920
		DIMENSION ZLEVS(1)	009930
		C THIS SUBROUTINE RETURNS NLEV EQUI-SPACED CONTOUR LEVELS BETWEEN ZMIN	009940
		C AND ZMAX (BUT NOT INCLUDING ZMIN)	009950
5		DEL=(ZMAX-ZMIN)/NLEV	009960
		DO 100 I=1,NLEV	009970
		ZLEVS(I)=ZMIN+I*DEL	009980
	100	CONTINUE	009990
		RETURN	010000
10		END	010010

E.12 Subroutine SKIP

1		SUBROUTINE SKIP(ITAPE,NSK(IP,FLAG,N)	010020
		LOGICAL FLAG	010030
		IF (NSK(IP.EQ. 0) GOTO 120	010040
		NREC=NSK(IP	010050
5		DO 100 I=1,NREC	010060
		READ(ITAPE)	010070
		IF (EOF(ITAPE)) 110,100	010080
	100	CONTINUE	010090
		GOTO 120	010100
10	110	FLAG=.F.	010110
	120	RETURN	010120
		END	010130

E.13 Subroutine FACE

1		SUBROUTINE FACE(XD1,YD1,ZPP,THETA1,THETA2,NREFIN)	010140
		DIMENSION R(3,3)	010150
		COMMON/BLOCK3/INUM, JNUM, XMIN, YMIN, DX, DY, SW1, IT6	010160
		COMMON DATA(103,103,2)	010170
5		WRITE(IT6,101)XD1,YD1,ZPP,THETA1,THETA2,INUM,JNUM,NREFIN	010180
	101	FORMAT(3(F6.2,1X),2(F7.4,1X),J(13,1X))	010190
		YES=3HYES	010200
		YNO=2HNO	010210
		INUM=INUM	010220
10		JNUM=JNUM	010230
		YD=YD1	010240
		XD=XD1	010250
		XB = ZPP*COS(THETA2)/TAN(THETA1)	010260
		YB = ZPP*SIN(THETA2)/TAN(THETA1)	010270

15		XHAR = XDP-XH	010280
		YHAR = YDP-YH	010290
		XDP = XDP-XBAR	010300
		YDP = YDP-YBAR	010310
		DTS = SQRT(XPP*XDP+YPP*YDP+ZPP*ZDP)	010320
20		R(1,1) = -SIN(THETA2)	010330
		R(1,2) = COS(THETA2)	010340
		R(1,3) = 0.0	010350
		R(2,1) = -SIN(THETA1)*COS(THETA2)	010360
		R(2,2) = -SIN(THETA1)*SIN(THETA2)	010370
25		R(2,3) = COS(THETA1)	010380
		R(3,1) = COS(THETA1)*COS(THETA2)	010390
		R(3,2) = COS(THETA1)*SIN(THETA2)	010400
		R(3,3) = SIN(THETA1)	010410
		DO 20 I=1,INUM	010420
30		A = FLOAT(I)	010430
		Y = A-YHAR	010440
		DO 20 J=1,JNUM	010450
		B = FLOAT(J)	010460
		X = B-XBAR	010470
35		Z = DATA(I,J,1)	010480
		DATA(I,1,1) = R(1,1)*X + R(1,2)*Y + R(1,3)*Z	010490
		DATA(I,1,2) = R(2,1)*X + R(2,2)*Y + R(2,3)*Z	010500
		Z = DTS-(R(3,1)*X + R(3,2)*Y + R(3,3)*Z)	010510
		DATA(I,J,1) = DATA(I,J,1)/Z	010520
40	20	DATA(I,J,2) = DATA(I,J,2)/Z	010530
		INUM1 = INUM/2	010540
		JNUM1 = JNUM/2	010550
		IF (YP .EQ. 1.0) GO TO 45	010560
		IF (YP .GE. FLOAT(INUM1)) GO TO 30	010570
45		IF (XP .EQ. 1.0) GO TO 40	010580
		IF (XP .GE. FLOAT(JNUM1)) GO TO 30	010590
	30	DO 25 J=1,JNUM	010600
		DO 25 I=1,INUM1	010610
		T1 = DATA(I,J,1)	010620
		T2 = DATA(I,J,2)	010630
50		DATA(I,J,1) = DATA(INUM+1-I,J,1)	010640
		DATA(I,J,2) = DATA(INUM+1-I,J,2)	010650
		DATA(INUM+1-I,J,1) = T1	010660
	35	DATA(INUM+1-I,J,2) = T2	010670
		GO TO 45	010680
55		XP = YES	010690
	40	ITEMP = INUM	010700
		JNUM = JNUM	010710
		JNUM = ITEMP	010720
60		ITEMP = MAX0(INUM,JNUM)	010730
		DO 42 I=1,ITEMP	010740
		DO 41 J=1,I	010750
		T1 = DATA(I,J,1)	010760
		T2 = DATA(I,J,2)	010770
65		DATA(I,J,1) = DATA(I,1,1)	010780
		DATA(I,1,1) = T1	010790
		DATA(I,J,2) = DATA(I,1,2)	010800
	41	DATA(I,1,2) = T2	010810
	42	CONTINUE	010820
70		IF (XP .EQ. YES) GO TO 30	010830
	45	IF (DATA(I,1,1) .LT. DATA(I,JNUM,1)) GO TO 46	010840
		IF (DATA(INUM,JNUM,1) .LT. DATA(I,JNUM,1)) GO TO 50	010850
		GO TO 90	010860
	46	IF (DATA(I,JNUM,1) .LT. DATA(INUM,JNUM,1)) GO TO 50	010870
		GO TO 90	010880
75		DO 45 I=1,INUM	010890
		DO 45 J=1,JNUM	010900
		T1 = DATA(I,J,1)	010910
		T2 = DATA(I,J,2)	010920
80		DATA(I,J,1) = DATA(I,JNUM+1-I,1)	010930
		DATA(I,J,2) = DATA(I,JNUM+1-I,2)	010940
		DATA(I,JNUM+1-I,1) = T1	010950
	55	DATA(I,JNUM+1-I,2) = T2	010960
	90	CALL HIDE	010970
85	1000	CONTINUE	010980
		RETURN	010990
		END	011000

E.14 Subroutine HIDE

1	SHROUTINE HIDE	011010
	COMMON DATA(103,103,2)/BLOCK1/TEST(500,2),TEST1(500,2),NUM/BLOCK2/	011020
	IP(2),Q(2),JCUT	011030
	COMMON/BLOCK3/INUM, NUM,XMIN,YMIN,DX,DY,SWI,IT6	011040
5	LOGICAL SWI	011050
	SI7=8.	011060
	KFLAG = 0	011070
	JFLAG = 0	011080
	IF (SWI) GOTO 2000	011090
10	SMALL = DATA(1,1,1)	011100
	RIG = SMALL	011110
	DO K = 1,INUM	011120
	DO J = 1,NUM	011130
	IF (DATA(I,J,1) .LT. SMALL) SMALL = DATA(I,J,1)	011140
15	IF (DATA(I,J,1) .GT. RIG) BIG = DATA(I,J,1)	011150
	XMIN = SMALL	011160
	DY = (BIG-SMALL)/SI7	011170
	SMALL = DATA(1,1,2)	011180
	RIG = SMALL	011190
20	DO K = 1,INUM	011200
	DO J = 1,NUM	011210
	IF (DATA(I,J,2) .LT. SMALL) SMALL = DATA(I,J,2)	011220
	IF (DATA(I,J,2) .GT. RIG) BIG = DATA(I,J,2)	011230
	YMIN = SMALL	011240
25	DY = (BIG-SMALL)/SI7	011250
	D = DY	011260
	IF (DX .GE. DY) D=DY	011270
	DY = D	011280
	DX = D	011290
30	GOTO 2010	011300
	2000 DO I = 1,INUM	011310
	TEST(I,1) = DATA(I,1,1)	011320
	TEST(I,2) = DATA(I,1,2)	011330
	TEST1(I,1) = TEST(I,1)	011340
35	CALL LINE(TEST,TEST1,INUM,1,0,0,XMIN,DX,YMIN,DY,0.)	011350
	I = 1	011360
	NUM = INUM	011370
	JCUT = 0	011380
	JCUT = 2	011390
40	JCUT = JCUT + 1	011400
	KFLAG = 0	011410
	JFLAG = 0	011420
	IF (JCUT .EQ. INUM+1) GO TO 100	011430
	I = 0	011440
45	DO J = 1,NUM	011450
	IF ((DATA(JCUT,J,1) .LE. TEST(I,1)) .AND. (DATA(JCUT,J,1)	011460
	1,GE. TEST(I-1,1))) GO TO 31	011470
	IF ((DATA(JCUT,J,1) .LT. TEST(I,1)) .OR. (DATA(JCUT,J,1)	011480
	1,GT. TEST(I-1,1))) GO TO 35	011490
50	31 R = (TEST(I,2)-TEST(I-1,2))/(TEST(I,1)-TEST(I-1,1))	011500
	C = TEST(I,2) - R*TEST(I,1)	011510
	Y = R*DATA(JCUT,J,1) + C	011520
	IF (Y .LE. DATA(JCUT,J,2)) GO TO 35	011530
	I = J + 1	011540
55	35 CONTINUE	011550
	IF (2*(J/2) .EQ. 1) GO TO 120	011560
	GO TO 400	011570
	100 JCUT = 1	011580
	JCUT = JCUT + 1	011590
60	IF (JCUT .NE. INUM+1) GO TO 30	011600
	RETURN	011610
	120 IF (JCUT .EQ. 1) GO TO 200	011620
	P(1) = DATA(JCUT,J,1)	011630
	P(2) = DATA(JCUT,J,2)	011640
65	Q(1) = DATA(JCUT,J,1)	011650
	Q(2) = DATA(JCUT,J,2)	011660
	IF (P(2) .GE. 6.0) GO TO 130	011670
	X = P(2)	011680
	Y = Q(2)	011690
70	GO TO 200	011700
	130 CALL DRAW(X,Y,K,KFLAG)	011710
	IF (K .GT. NUM) GO TO 365	011720
	200 P(1) = DATA(JCUT,J,1)	011730
	P(2) = DATA(JCUT,J,2)	011740

75	Q(1) = DATA(ICUT,JCUT,2)	011750
	Q(2) = DATA(ICUT-1,JCUT,2)	011760
	IF (P(2) .GE. 6.0) GO TO 210	011770
	X1 = P(2)	011780
	Y1 = Q(2)	011790
80	GO TO 305	011800
	210 CALL DRAW(X1,Y1,J,JFLAG)	011810
	IF (J .GT. NUM) GO TO 365	011820
	300 IF (JCUT .NE. 1) GO TO 305	011830
	K = 1	011840
85	GO TO 314	011850
	305 CONTINUE	011860
	600 FORMAT (5H HERE)	011870
	IF (KFLAG .EQ. 1) GO TO 314	011880
	DO 310 I=1,NUM	011890
90	IF ((X .EQ. TEST(I,1)) .AND. (Y .EQ. TEST(I,2))) GO TO 313	011900
	310 CONTINUE	011910
	311 FORMAT (10H 310 ERROR)	011920
	GO TO 365	011930
	313 K = I	011940
95	314 IF (JFLAG .EQ. 1) GO TO 320	011950
	DO 315 I=1,NUM	011960
	IF ((X1 .EQ. TEST(I,1)) .AND. (Y1 .EQ. TEST(I,2))) GO TO 318	011970
	315 CONTINUE	011980
	316 FORMAT (10H 316 ERROR)	011990
100	GO TO 365	012000
	318 J = I	012010
	C IF IFLAG IS SET, WE ARE LOOKING AT THE BACK OF THE SQUARE PIECE	012020
	C WHOSE CORNER IS DATA(ICUT,JCUT). IN THIS CASE WE DO NOT DRAW THE	012030
	C LINE TO DATA(ICUT,JCUT-1). AND WE DO NOT INCLUDE IT IN THE SKYLINE.	012040
105	C T.E. TEST.	012050
	320 IFLAG = 0	012060
	IF (JFLAG .EQ. 0) J = J + 1	012070
	IF (J .LT. K) IFLAG = 1	012080
	IF ((J .EQ. 0) .AND. (ABS(X1-TEST(J,1)) .GT. ABS(X-TEST(J,1))))	012090
110	IFLAG = 1	012100
	JFLAG = 0	012110
	KFLAG = 0	012120
	II = 0	012130
	DO 330 I=J,NUM	012140
	II = II + 1	012150
	TEST1(II,1) = TEST(I,1)	012160
	330 TEST1(II,2) = TEST(I,2)	012170
	IF (IFLAG .EQ. 0) GO TO 341	012180
	K = J	012190
5	X = X1	012200
	Y = Y1	012210
	GO TO 335	012220
	331 IF (JCUT .NE. 1) GO TO 335	012230
10	K = K - 1	012240
	GO TO 341	012250
	335 TEST(K,1) = X	012260
	TEST(K,2) = Y	012270
15	340 TEST(K+1,1) = DATA(ICUT,JCUT,1)	012280
	TEST(K+1,2) = DATA(ICUT,JCUT,2)	012290
	TEST(K+2,1) = X1	012300
	TEST(K+2,2) = Y1	012310
	K = K + 2	012320
	IF (J .EQ. (NUM + 1)) GO TO 350	012330
20	DO 345 I=1,II	012340
	K = K + 1	012350
	TEST(K,1) = TEST1(I,1)	012360
	345 TEST(K,2) = TEST1(I,2)	012370
	601 FORMAT (1H ,3110)	012380
25	350 NUM = K	012390
	IF (JCUT .EQ. 1) GO TO 355	012400
	IF (IFLAG .EQ. 1) GO TO 355	012410
	P(2) = X	012420
	Q(2) = Y	012430
30	CALL LINE(P,0,2,1,0,0,XMIN,DX,YMIN,DY,0,0)	012440
	355 P(2) = X1	012450
	Q(2) = Y1	012460
	CALL LINE(P,0,2,1,0,0,XMIN,DX,YMIN,DY,0,0)	012470
	365 GO TO 20	012480
35	400 CONTINUE	012490
	401 FORMAT (4H 400,2X,110)	012500
	IF (JCUT .EQ. 1) GO TO 500	012510
	P(1) = DATA(ICUT,JCUT-1,1)	012520
	P(2) = DATA(ICUT,JCUT,1)	012530

4	Q(1) = DATA(ICUT, ICUT-1, 2)	012540
	Q(2) = DATA(ICUT, ICUT, 2)	012550
	IF (P(1) .GE. 6.0) GO TO 500	012560
	CALL DRAW(X, Y, K, KFLAG)	012570
	IF (K .GT. NUM) GO TO 545	012580
45	P(2) = X	012590
	Q(2) = Y	012600
	CALL LINE(P, Q, 2, 1, 0.0, XMIN, DX, YMIN, DY, 0.0)	012610
400	IC = ICUT	012620
	JC = ICUT - 1	012630
5	CALL SORT(IC, JC, K, X, Y)	012640
500	P(1) = DATA(ICUT-1, ICUT, 1)	012650
	P(2) = DATA(ICUT, ICUT, 1)	012660
	Q(1) = DATA(ICUT-1, ICUT, 2)	012670
	Q(2) = DATA(ICUT, ICUT, 2)	012680
55	IF (P(1) .GE. 6.0) GO TO 545	012690
	CALL DRAW(X, Y, J, JFLAG)	012700
	IF (J .GT. NUM) GO TO 545	012710
	P(2) = X	012720
	Q(2) = Y	012730
	CALL LINE(P, Q, 2, 1, 0.0, XMIN, DX, YMIN, DY, 0.0)	012740
175	IC = ICUT - 1	012750
	JC = ICUT	012760
	CALL SORT(IC, JC, J, X, Y)	012770
	545 DATA(ICUT, JCUT, 1) = DATA(ICUT, JCUT, 1) + SIZE	012780
	GO TO 365	012790
180	200 RETURN	012800
	END	012810

E.15 Subroutine DRAW

1	SHRUBOUTINE DRAW(X, Y, K, KFLAG)	012820
	COMMON /BLOCK1/TEST(500, 2), TEST1(500, 2), NUM/BLOCK2/P(2), Q(2), JCUT	012830
	SIZE = 0.	012840
	Q(2) = 0.	012850
5	IF (P(2) .GE. 6.0) GO TO 10	012860
	GO TO 15	012870
10	P(2) = P(2) - SIZE	012880
15	Y = 15.0	012890
	S = .00001	012900
	R1 = (Q(2) - Q(1)) / (P(1) - P(2))	012910
	IP = LEQVAR(R1)	012920
	IF (IP .NE. 0) GO TO 20	012930
	C1 = Q(1) + R1 * P(1)	012940
	DO 10 I = 1, NUM	012950
15	QY = TEST(I, 1) - TEST(I-1, 1)	012960
	QY = TEST(I, 2) - TEST(I-1, 2)	012970
	QY = 5 * SORT(DX * DX, DY * DY)	012980
	Q2 = (TEST(I-1, 2) - TEST(I, 2)) / (TEST(I, 1) - TEST(I-1, 1))	012990
	IT = LEQVAR(Q2)	013000
20	IF (IT .NE. 0) GO TO 35	013010
	C2 = TEST(I, 2) + Q2 * TEST(I, 1)	013020
	IF (IP .NE. 0) GO TO 40	013030
	XX = (C2 - C1) / (R2 - R1)	013040
	IF (LEQVAR(XX) .NE. 0) GO TO 40	013050
25	YY = C1 - R1 * XX	013060
	IF ((TEST(I-1, 1) - QY .LE. XX) .AND. (XX .LE. TEST(I, 1) + QY)) GO TO 30	013070
	IF ((TEST(I, 1) - QY .LE. XX) .AND. (XX .LE. TEST(I-1, 1) + QY)) GO TO 30	013080
	GO TO 40	013090
30	IF (P(1) - QY .LE. YY) .AND. (YY .LE. P(2) + QY) GO TO 45	013100
	IF (P(2) - QY .LE. YY) .AND. (YY .LE. P(1) + QY) GO TO 45	013110
	GO TO 40	013120
35	IF (IP .NE. 0) GO TO 40	013130
	XX = TEST(I, 1)	013140
	YY = C1 - R1 * XX	013150
35	IF ((TEST(I-1, 2) - QY .LE. YY) .AND. (YY .LE. TEST(I, 2) + QY)) GO TO 30	013160
	IF ((TEST(I, 2) - QY .LE. YY) .AND. (YY .LE. TEST(I-1, 2) + QY)) GO TO 30	013170
	GO TO 40	013180
40	XX = P(1)	013190
	YY = C2 - Q2 * XX	013200

40	IF (I(1)-DS .LE. YY) .AND. (YY.LE. 0(1)+DS)) GO TO 25	013220
	IF (I(2)-DS .LE. YY) .AND. (YY.LE. 0(1)+DS)) GO TO 25	013230
	GO TO 90	013240
45	DX = P(1)-XX	013250
	DY = Q(1)-YY	013260
45	D = SQRT(DX*DX+DY*DY)	013270
	IF (D .LT. DIS) GO TO 90	013280
	DIS = D	013290
153	FORMAT (1H ,F10.3)	013300
	X=XY	013310
50	Y=YY	013320
	K = I	013330
90	CONTINUE	013340
	IF (Y .EQ. 15.0) GO TO 110	013350
152	FORMAT (1H ,110.1X,2F10.3)	013360
55	KFLAG = 1	013370
151	FORMAT (4H 150.2X,110)	013380
	RETURN	013390
110	K = NUM + 1	013400
171	FORMAT (15H ERROR AT ICUT=.12)	013410
60	RETURN	013420
	END	

E.16 Subroutine SORT

1	SUBROUTINE SORT(IC, IC,K,X,Y)	013430
	COMMON DATA(103,103,2)/BLOCK1/TEST(500,2),TEST1(500,2),NUM	013440
	COMMON/BLOCK3/INUM, NUM,XMIN,YMIN,DX,DY,SWI,IT6	013450
	DO 10 I=1,NUM	013460
5	IF (TEST(I,1) .NE. DATA(IC,JC,1)) GO TO 10	013470
	IF (TEST(I,2) .NE. DATA(IC,JC,2)) GO TO 10	013480
	J = I	013490
	GO TO 20	013500
10	CONTINUE	013510
431	FORMAT (4H 430.2X,4H = .13,110)	013520
	GO TO 90	013530
20	IF (J .LT. K) GO TO 30	013540
	IF (J .EQ. K) GO TO 90	013550
	KK = J	013560
15	JJ = K	013570
	GO TO 40	013580
30	KK = K	013590
	JJ = J + 1	013600
40	II = 0	013610
20	DO 60 I=KK,NUM	013620
	II = II + 1	013630
	TEST1(II,1) = TEST(I,1)	013640
50	TEST1(II,2) = TEST(I,2)	013650
	TEST(IJ,1) = X	013660
25	TEST(IJ,2) = Y	013670
	DO 60 I=1,II	013680
	JJ = JJ + 1	013690
	TEST(IJ,1) = TEST1(I,1)	013700
60	TEST(IJ,2) = TEST1(I,2)	013710
30	NUM = JJ	013720
90	RETURN	013730
	END	013740

E.17 Subroutine PARFIT

1	SUBROUTINE PARFIT(Y1,Y2,Y3,YF1,YF2)	013750
	C THIS SUBROUTINE FITS A PARABOLA TO THREE DATA POINTS Y1,Y2,Y3, TAKEN	013760
	C AT EQUAL INTERVALS AND COMPUTES POINTS YF1,YF2, ON THE FITTED PARABOL	013770
	C • AT THE MIDDLE OF THE INTERVALS	013780
5	C	013790
	A=(Y1+Y3-2.*Y2)/8.	013800
	B=(Y3-Y1)/4.	013810
	C=Y2	013820
	YF1=A-B+C	013830
10	YF2=A+B+C	013840
	RETURN	013850
	END	013860

E.18 Subroutine CONTOR

1	SUBROUTINE CONTOR(M,N,NLEVS,HLEVS,BLANK,XLEN,YLEN,XP,YP)	013870
	C	013880
	C DRAW PENPLOT CONTOURS FROM RECTANGULAR GRID INPUT	013890
	C	013900
5	C PARAMETERS	013910
	C	013920
	C Z THE GIVEN FUNCTION	013930
	C M NUMBER OF ROWS IN Z ARRAY	013940
	C N NUMBER OF COLS IN Z ARRAY	013950
10	C XT TEMPORARY ARRAY SIZE=(M*N)	013960
	C YT TEMPORARY ARRAY SIZE=(M*N)	013970
	C NLEVS NUMBER OF CONTOURS	013980
	C HLEVS CONTOUR VALUES	013990
	C BLANK MSG DATA CODE	014000
15	C XLEN LENGTH OF X-AXIS IN INCHES	014010
	C YLEN LENGTH OF Y-AXIS IN INCHES	014020
	C	014030
	C Z(I,J) ASSUMED TO BE IN ASCENDING ORDER BY X AND Y	014040
	C IF Z(1,1) = Z(XMIN,YMIN)	014050
20	C Z(M,N) = Z(XMAX,YMAX)	014060
	C	014070
	C	014080
	C PROGRAM WILL PLOT ANY NUMBER OF CONTOURS	014090
	C LINES ARE LABELED BY CHARACTERS 0 - 12	014100
25	C CHARACTERS ARE REPEATED AS NECESSARY	014110
	C	014120
	C USES SUBROUTINES NETROR AND FOUR	014130
	C	014140
	C DIMENSION HLEVS(1)	014150
30	C COMMON 7(103,103),XT(103,103),YT(103,103)	014160
	C DIMENSION T(150)	014170
	C DIMENSION SX(3),SY(3),IC(4)	014180
	C DIMENSION IO(16),IP(16)	014190
35	C DATA (IO(I),I=1,16,1)/-1,-1,-2,-1,-1,-2,-1,-1,-1,0,0,0,0,0,0,-1/	014200
	C DATA (IP(I),I=1,16,1)/-1,-1,-1,0,0,0,1,0,0,1,0,0,0,-1,-1,-1/	014210
	C	014220
	C K=75	014230
	C XMIN=YM1N=0E0	014240
	C IFLAG=1	014250
40	C VSYMB=YP-.2	014260
	C XPLT=XLEN*XP	014270
	C JLINE=8	014280
	C	014290
	C CALL PLOT (0,0,0,0,3)	014300
45	C XSIZE=FLOAT(N-1)/XLEN	014310
	C YSIZE=FLOAT(M-1)/YLEN	014320
	C UD=M*N	014330
	C	014340
	C FIND ZMAX, ZMIN	014350

50	C	IMAX=0	014360
		DO 13 I=1,M	014370
		DO 12 J=1,N	014380
		IF (Z(I,J).EQ.BLANK) GO TO 12	014390
55		IMAX=IMAX+1	014400
		IF (IMAX.GT.1) GO TO 11	014410
		ZMAX=Z(I,J)	014420
		ZMIN=Z(I,J)	014430
		GO TO 12	014440
60	11	IF (Z(I,J).GT.ZMAX) ZMAX=Z(I,J)	014450
		IF (Z(I,J).LT.ZMIN) ZMIN=Z(I,J)	014460
	12	CONTINUE	014470
	13	CONTINUE	014480
		PRINT 100, ZMIN,ZMAX,NLEVS,(HLEVS(I),I=1,NLEVS)	014490
65	C		014500
	C	GET H.	014510
	C		014520
		ILEVS=0	014530
	99	ILEVS=ILEVS+1	014540
70		LLINE=ILEVS-1	014550
		IF (ILEVS.GT.NLEVS) GO TO 999	014560
		H=HLEVS(ILEVS)	014570
		PRINT 200, H	014580
		INDHE=0	014590
75		IF ((H.GE.ZMIN).AND.(H.LE.ZMAX)) GO TO 101	014600
		PRINT 300	014610
		GO TO 99	014620
	C		014630
	C	PREPARE THE XT-TABLE	014640
80	C		014650
	101	DO 102 I=1,M	014660
		DO 102 J=1,N	014670
		XT(I,J)=0	014680
		IF (I.EQ.M) GO TO 102	014690
85		IF (Z(I,J).EQ.BLANK) GO TO 102	014700
		IF (Z(I+1,J).EQ.BLANK) GO TO 102	014710
		IF ((Z(I,J)-H)*(Z(I+1,J)-H)).GE.0.0) GO TO 102	014720
		XT(I,J)=ABS(FLOAT(I-1)*((H-Z(I,J))/(Z(I+1,J)-Z(I,J))))	014730
	102	CONTINUE	014740
90	C		014750
	C	PREPARE THE YT-TABLE	014760
	C		014770
		DO 103 I=1,M	014780
		DO 103 J=1,N	014790
		YT(I,J)=0	014800
95		IF (J.EQ.N) GO TO 103	014810
		IF (Z(I,J).EQ.BLANK) GO TO 103	014820
		IF (Z(I,J+1).EQ.BLANK) GO TO 103	014830
		IF ((Z(I,J)-H)*(Z(I,J+1)-H)).GE.0.0) GO TO 103	014840
100		YT(I,J)=ABS(FLOAT(J-1)*((H-Z(I,J))/(Z(I,J+1)-Z(I,J))))	014850
	103	CONTINUE	014860
	C		014870
		DO 201 I=1,4	014880
	201	IC(I)=0	014890
105		DO 207 I=1,M	014900
		DO 207 J=1,N	014910
		IF (Z(I,J).NE.H) GO TO 207	014920
	C		014930
	C	COUNT ENTRANCES AND EXITS IN SURROUNDING BLOCKS	014940
110	C		014950
		DO 202 I=1,16	014960
		I1=I0(I2)+1	014970
		IF (I1.LT.1.OR.I1.GT.M) GO TO 202	014980
		J1=I1(I2)+J	014990
115		IF (J1.LT.1.OR.J1.GT.N) GO TO 202	015000
		I1=(I2-1)/4+1	015010
		IF ((XT(I1,J1).NE.0).OR.(YT(I1,J1).NE.0)) IC(I1)=IC(I1)+1	015020
	202	CONTINUE	015030
		IHOLD=0	015040
120		DO 206 I=1,4	015050
		IC(I2)=MOD(IC(I2),2)	015060
		IF (IC(I2).EQ.0) GO TO 206	015070
		IF (IHOLD.NE.0) GO TO 203	015080
		IHOLD=I2	015090
125		GO TO 206	015100
	203	IF (I2-IHOLD.EQ.1) GO TO 204	015110
		IF (IHOLD.EQ.1.AND.I2.EQ.4) GO TO 205	015120
		GO TO 301	015130
	204	IF (I2-IHOLD.EQ.5) GO TO 205	015140
			015150

130		I3=I+I2-1	015160
		XT(I3,J)=-ABS(FLOAT(I3-1)+.001)	015170
		GO TO 207	015180
205		I3=I-1	015190
		J4=J+4-I2	015200
135		YT(I3,J4)=-ABS(FLOAT(J4)+.001)	015210
		GO TO 207	015220
206		CONTINUE	015230
207		CONTINUE	015240
		C	015250
140	301	IL=-30	015260
		JL=-30	015270
		KL=-30	015280
		XF=HD	015290
		YF=HD	015300
145	C		015310
	C	COMPILE A LIST	015320
	C		015330
302		CONTINUE	015340
		DO 203 I=1,M	015350
150		DO 203 J=1,N	015360
		KEY=1	015370
		IF (XT(I,J).NE.HD) GO TO 304	015380
		KEY=2	015390
		IF (YT(I,J).NE.HD) GO TO 304	015400
155	303	CONTINUE	015410
	C		015420
		IF (IDONE.EQ.0) PRINT 400	015430
		GO TO 49	015440
	C		015450
160	304	IX=	015460
		IF (NEIROR(KEY,I,J,KL,IL,JL).LE.0) GO TO 305	015470
		IX=2	015480
		T(1)=XF	015490
		T(2)=YF	015500
165	305	IL=I	015510
		JL=J	015520
		KL=KEY	015530
		LR=1	015540
		GO TO (306,307), KEY	015550
170	306	XF=XT(I,J)	015560
		YF=I-1	015570
		GO TO 401	015580
	307	YF=I-1	015590
		YF=YT(I,J)	015600
175	C		015610
	C	ADD A POINT TO THE LIST	015620
	C		015630
	401	XS=YF	015640
		YS=YF	015650
180		ISAVE=I	015660
		JSAVE=J	015670
		KSAVE=KEY	015680
	402	IF (IX-K+2).LT.0) GO TO 404	015690
		I47=1	015700
185		GO TO 801	015710
	403	CONTINUE	015720
		T(1)=T(IY-1)	015730
		T(2)=T(IX)	015740
		IX=2	015750
190	404	IX=IX+2	015760
		T(IY-1)=ARS(XS)	015770
		T(IX)=ARS(YS)	015780
		IF (I47.EQ.1) GO TO 405	015790
		IF (IX.LT.6) GO TO 406	015800
195	405	IF (KSAVE.EQ.1) XT(ISAVE,JSAVE)=HD	015810
		IF (KSAVE.EQ.2) YT(ISAVE,JSAVE)=HD	015820
	406	IF (IX.EQ.2) GO TO 501	015830
		GO TO (407,409), KEY	015840
	C		015850
200	C	THE POINT IS ON AN HORIZONTAL LINK	015860
	C		015870
	407	IF (XT(I,J).GE.0.0) GO TO 408	015880
		XT(I,J)=ARS(XT(I,J))	015890
		GO TO 501	015900
205	409	XT(I,J)=HD	015910
		GO TO 501	015920
	C		015930
	C	THE POINT IS ON A VERTICAL LINK	015940
	C		015950

210	400	IF (YT(I,J).GE.0.0) GO TO *10	015960
		YT(I,J)=ABS(YT(I,J))	015970
		GO TO 501	015980
	410	YT(I,J)=UD	015990
	C		016000
215	C	INTO BOX - IS THERE A WAY OUT	016010
	C		016020
	501	KH=	016030
		ISAVE=I	016040
		JSAVE=J	016050
220		KSAVE=KEY	016060
		GO TO (502,601), KEY	016070
	502	CONTINUE	016080
		IF (LR.F0.2) GO TO 505	016090
		IF (J.E0.0) GO TO 701	016100
225		IF (XT(I,J+1).E0.UD) GO TO 503	016110
		KH=KH+1	016120
		KS=1	016130
		SX(I)=XT(I,J+1)	016140
		SY(I)=J	016150
230	503	CONTINUE	016160
		IF (YT(I,J).E0.UD) GO TO 504	016170
		KH=KH+1	016180
		KS=2	016190
		SX(2)=I-1	016200
235		SY(2)=YT(I,J)	016210
	504	CONTINUE	016220
		IF (I.E0.0) GO TO 508	016230
		IF (YT(I+1,J).E0.UD) GO TO 508	016240
		KH=KH+1	016250
240		KS=3	016260
		SX(3)=I	016270
		SY(3)=YT(I+1,J)	016280
		GO TO 508	016290
	505	CONTINUE	016300
245		IF (J.E0.1) GO TO 701	016310
		IF (XT(I,J-1).E0.UD) GO TO 500	016320
		KH=KH+1	016330
		KS=4	016340
		SX(4)=XT(I,J-1)	016350
250		SY(4)=J-2	016360
	506	CONTINUE	016370
		IF (YT(I,J-1).E0.UD) GO TO 507	016380
		KH=KH+1	016390
		KS=5	016400
255		SX(5)=I-1	016410
		SY(5)=YT(I,J-1)	016420
	507	CONTINUE	016430
		IF (I.E0.0) GO TO 508	016440
		IF (YT(I+1,J-1).E0.UD) GO TO 508	016450
260		KH=KH+1	016460
		KS=6	016470
		SX(6)=I	016480
		SY(6)=YT(I+1,J-1)	016490
265	508	IF (KH.F0.0.0R.KH.E0.2) GO TO 701	016500
		IF (KH.F0.1) CALL FOUR (T,IX,SX,SY,KS,KEY)	016510
		GO TO (509,510,511,512,513,514), KS	016520
	509	KEY=1	016530
		LR=1	016540
270		J=J+1	016550
		GO TO 514	016560
	510	KEY=2	016570
		LR=2	016580
		GO TO 514	016590
275	511	KEY=2	016600
		I=I+1	016610
		LR=1	016620
		GO TO 514	016630
	512	KEY=1	016640
		LR=2	016650
280		GO TO 515	016660
	513	KEY=2	016670
		LR=2	016680
		GO TO 515	016690
285	514	KEY=2	016700
		I=I+1	016710
		LR=1	016720
	515	KS=KS-3	016730
		J=J-1	016740
	516	XK=SK(KS)	016750

294		YS=XT(IAS)	016760
		IFLAG=2	016770
		GO TO 402	016780
	C		016790
	C		016800
295	601	CONTINUE	016810
		IF (LR.EQ.2) GO TO 604	016820
		IF (I.EQ.M) GO TO 701	016830
		IF (XT(I,J).EQ.UD) GO TO 602	016840
		KH=KH+1	016850
300		KS=1	016860
		SY(I)=XT(I,J)	016870
		SY(I)=J-1	016880
	602	CONTINUE	016890
		IF (J.EQ.N) GO TO 603	016900
305		IF (XT(I,J+1).EQ.UD) GO TO 603	016910
		KH=KH+1	016920
		KS=2	016930
		SY(I)=XT(I,J+1)	016940
		SY(I)=J	016950
310	603	CONTINUE	016960
		IF (I.EQ.M) GO TO 607	016970
		IF (YT(I+1,J).EQ.UD) GO TO 601	016980
		KH=KH+1	016990
		KS=3	017000
315		SY(I)=I	017010
		SY(I)=YT(I+1,J)	017020
		GO TO 607	017030
	604	CONTINUE	017040
		IF (I.EQ.1) GO TO 701	017050
320		IF (XT(I-1,J).EQ.UD) GO TO 605	017060
		KH=KH+1	017070
		KS=4	017080
		SY(I)=XT(I-1,J)	017090
		SY(I)=J-1	017100
325	605	CONTINUE	017110
		IF (J.EQ.N) GO TO 606	017120
		IF (XT(I-1,J+1).EQ.UD) GO TO 606	017130
		KH=KH+1	017140
		KS=5	017150
330		SY(I)=XT(I-1,J+1)	017160
		SY(I)=J	017170
	606	CONTINUE	017180
		IF (YT(I-1,J).EQ.UD) GO TO 601	017190
		KH=KH+1	017200
335		KS=6	017210
		SY(I)=I-2	017220
		SY(I)=YT(I-1,J)	017230
	607	CONTINUE	017240
		IF (KH.EQ.0.OR.KH.EQ.2) GO TO 701	017250
340		IF (KH.NE.1) CALL FOUR (I,X,SY,KS,KEY)	017260
		GO TO (608,609,610,611,612,613), KS	017270
	608	KEY=1	017280
		LR=2	017290
		GO TO 615	017300
345	609	KEY=1	017310
		LR=1	017320
		I=J+1	017330
		GO TO 615	017340
	610	KEY=2	017350
350		I=I+1	017360
		LR=1	017370
		GO TO 615	017380
	611	KEY=1	017390
		LR=2	017400
355		GO TO 614	017410
	612	KEY=1	017420
		LR=1	017430
		I=J+1	017440
		GO TO 614	017450
360	613	KEY=2	017460
		LR=2	017470
	614	I=I-1	017480
		KS=KS-3	017490
365	615	XS=XS(KS)	017500
		YS=YS(KS)	017510
		IFLAG=2	017520
		GO TO 402	017530
	C		017540
	C	NO MORE POINTS	017550

370	C		017560
701		IF (NEIROR(KEY,T,I,KL,IL,JL),LE.0) GO TO 704	017570
		IF (IX,LT.6) GO TO 704	017580
		IF (T(1),EQ,T(IX-1),AND,T(2),EQ,T(IX)) GO TO 704	017590
		IX=IX+2	017600
375		T(IX-1)=ABS(XF)	017610
		T(IX)=ABS(YF)	017620
	C		017630
		GO TO (702,703), KEY	017640
702		XT(T,J)=ID	017650
380		GO TO 704	017660
703		YT(T,J)=ID	017670
		GO TO (702,704), IFLAG	017680
704		I47=2	017690
	C		017700
385	801	LLINE=MOD(LLINE,11)	017710
		IF (IX,NE.2) GO TO 901	017720
		IF (LR,EQ.2) GO TO 802	017730
		LR=2	017740
		GO TO 501	017750
390	802	IF (KEY,EQ. 1) XT(I,J)=ID	017760
		IF (KEY,EQ. 2) YT(I,J)=ID	017770
		GO TO 902	017780
	C		017790
	C		017800
395	901	IDONE=IDONE+1	017810
		CALL LINE (T(2),T(1),IX/2+2,ILINE,LLINE,XMIN,XSIZE,YMIN,YSIZE,.06)	017820
		IF (IDONE,GT.1) GO TO 902	017830
		YSYMB=YSYMB+.2	017840
		IF (YSYMB,LT. 0.) 110,120	017850
400	110	YSYMB=YP-.2	017860
		XPLT=XPLT+.2	017870
	120	CALL SYMROL (XPLT,YSYMB,0.09,LLINE,0.0,-1)	017880
		CALL SYMROL (3HOLD,3HOLD,.09,1H=.0,.1)	017890
		ENCODE(1H,1,ISYM) H	017900
405		CALL SYMROL (3HOLD,3HOLD,.09,TSYM,0.0,10)	017910
		PRINT 500, LLINE	017920
	902	IF (I47,EQ. 1) GO TO 403	017930
		IFLAG=1	017940
		I=I	017950
410		J=J	017960
		KEY=KL	017970
		GO TO 301	017980
	C		017990
	1	FORMAT(G10.3)	018000
415	100	FORMAT (*1REGIN CONTOUR PLOT*,2G13.5,15/(5X,10G13.5))	018010
	200	FORMAT (* CONTOUR*,G13.5)	018020
	300	FORMAT (10X,*OUTSIDE GRID*)	018030
	400	FORMAT (10X,*NO DATA*)	018040
	500	FORMAT (10X,*PLOTED CHARACTER*,13)	018050
420	C		018060
	990	RETURN	018070
		END	018080

E.19 Subroutine NEIBOR

1	FUNCTION NEIBOR (KA,TA,JA,KB,IB,JB)	018090
	C	018100
	C	018110
	C	018120
5	NEIBOR=-1 IF NOT NEIGHBORS	018130
	C	018140
	C	018150
	C	018160
10	DIMENSION K1(14),K2(14),IT(14),JT(14)	018170
	DATA K1/1,1,1,1,1,1,2,2,2,2,2,2,1,2/	018180
	DATA K2/1,1,1,2,2,2,2,1,1,1,1,2,2,1,2/	018190
	DATA IT/1,0,0,0,0,1,1,0,0,-1,-1,1,-1,0,0/	018200
	DATA JT/-1,1,0,-1,-1,0,1,0,1,0,1,0,0,0,0/	018210
	ID = IB-IA	018220
15	JD = JB-JA	018230
	DO 90 I=1,14	018240
	IF (KA-K1(I)) 80,50,90	018250
	50 IF (KB-K2(I)) 80,60,90	018260
	60 IF (ID-IT(I)) 80,70,90	018270
	70 IF (JD-JT(I)) 80,90,90	018280
20	90 CONTINUE	018290
	NEIBOR = -1	018300
	GO TO 100	018310
	90 NEIBOR = 1	018320
	RETURN	018330
25	100 CONTINUE	018340
	RETURN	018350
	END	

E.20 Subroutine FOUR

1	SUBROUTINE FOUR(T,IX,SY,KS,KEY)	018360
	DIMENSION T(150),SX(3),SY(3)	018370
	IF (IX.GE.4) GO TO 499	018380
	KS=0	018390
5	RETURN	018400
	499 SLOPT=(T(IX)-T(IX-2))/(T(IX-1)-T(IX-3))	018410
	DO 515 I=1,3	018420
	SX=ABS(SX(I))	018430
	YS=ABS(SY(I))	018440
10	SLOPE=(T(IX)-YS)/(T(IX-1)-XS)	018450
	IF (SLOPT*SLOPE .LT. 0.0) GO TO 515	018460
	IF (KEY.EQ.1 .AND. I1.EQ.1) GO TO 515	018470
	IF (KEY.EQ.2 .AND. I1.EQ.3) GO TO 515	018480
	IF (KS.LE.3) GO TO 1	018490
15	KS=I+3	018500
	RETURN	018510
	1 KS=1	018520
	RETURN	018530
	515 CONTINUE	018540
20	RETURN	018550
	END	018560

E.21 Function SYMBL

```

1      FUNCTION SYMBL(TTM)
      IF (MVGFTX(TTM,1,1) .EQ. 55H) GOTO 100
      ENCODE(100,1,SYMBL) TTM
      RETURN
5      100 SYMBL=TTM
      RETURN
      1    FORMAT(610,3)
      END

```

```

018750
018760
018770
018780
018790
018800
018810
018820

```


Appendix F

Fortran Listing for Program T3D

1	PROGRAM T30(TAPE3,OUTPUT)
	C REVISION---SEPT 18,1975
	C PURPOSE---DISPLAY VALUES OF F1 AND F2 FROM TAPE3 (TEMP5 OUTPUT)
	C USING LINEAR INTERPOLATION BETWEEN TIMES.
5	C SUBROUTINE---
	C RTAPE3
	INTEGER DATAIN(100,3)
	EQUIVALENCE(I1,DATAIN)
	DATA IT3/3/
10	REWIND IT3
	READ(IT3) DATAIN
	TLAST=TNEXT=0.
	IP=1
	DELT=.1*TAUMX
15	WRITE 1,N0,NMX,DTAUD,TAUMX
	DO 100 I=1,10
	T=DELT*I
	CALL RTAPE3(T)
	WRITE 2,T
20	WRITE 3,(F1(J),J=1,81,10)
	WRITE 3,(F2(J),J=1,81,10)
	100 CONTINUE
	1 FORMAT(1H1,* N0=*I3*, NMX=*I3*, DTAUD=*E13.6* TAUMX=*E13.6/
	* VALUES OF F1 AND F2 AT 1,11,...,81*)
25	2 FORMAT(/* TAU=*E13.6)
	3 FORMAT(/(4E13.6))
	END

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